

ANEXA A1

PROGRAM DE REGLARE NUMERICA A FRECVENTEI
UNUI MOTOR DE CURENT CONTINUU

-VARIANTA CHOPPERULUI CU TIRISTORDE-

BIBLIOTECA CENTRALĂ
UNIVERSITATEA "POLITEHNICA"
TIMIȘOARA

anexa

NR. SERIE	5	BIȘOARA	A
VOL.	56833		
DATA	191		

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;
; PROGRAM DE REGLARE NUMERICA A TURATIEI UNUI MCC
;
; VARIANTA TIRISTORIZATA
;
; INITIALIZARI VARIABLE SI COEFICIENTI
2023 BYTE EQU 2023H ;OCTET DE CONTROL PENTRU
;RST 7.5
2022 WK EQU 2022H ;MARIME PRESCRISA wk
200B W1 EQU 200BH ;MARIME PRESCRISA wk-1
2026 RK EQU 2026H ;REACTIE rk
2027 RK1 EQU 2027H ;REACTIE rk-1
2028 YK EQU 2028H ;MARIME DE COMANDA yk
2024 YK1 EQU 2024H ;MARIME DE COMANDA yk-1
2021 SIGN EQU 2021H ;SEMN ABATERE
2001 ADCOD EQU 2001H ;ADRESA PRESCRIERE DE LA DAF
202B TEST EQU 202BH ;VARIABLEA FANION
4441 CRLF EQU 4441H ;SUBROUTINA PENTRU CR, LF
2012 ADAD EQU 2012H ;ADRESA CURENTA PENTRU
;RECEPTIE DAF
2000 FAN EQU 2000H ;FANION RECEPTIE COMPLETA DAF
PAGE
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;
20CE'   C3 8300          ;
                                ORG    20CEH ;AICI SE AJUNGE PRIN RST 7.5
                                JMP    8300H ;SALT IN INTERRUPT TIMER
;
                                ORG    8300H
;SUBROUTINA INTERRUPT TIMER
8300'   F5              PUSH   PSW
8301'   FB              FI
8302'   3A 2023        LDA    BYTE
8305'   B7              ORA    A
8306'   CA 8321'       JZ     I1 ;SALT DACA BYTE = ALFA
8309'   3C              INR    A
830A'   C2 8312'       JNZ   I2 ;SALT DACA BYTE = GAMMA
830D'   32 2023        STA   BYTE ;BYTE A POST BETA, VA FI ALFA
8310'   F1              POP    PSW
8311'   C9              RET
8312'   21 2026        LXI   I2: H,RK ;TRATAREA PENTRU BYTE = GAMMA
8315'   56              MOV   D,M ;D=RK
8316'   71              MOV   M,C ;RK=REZULTAT MASURA
8317'   23              INX   H
8318'   72              MOV   M,D ;RK1=D
8319'   E1              POP    H ;IGNORARE PSW SALVAT INITIAL
831A'   E1              POP    H ;IGNORARE ADEKSA DE INTOARCERE
;IN PROGRAMUL APELANT
831R'   FA 8548'       JM     R2C ;BYTE=GAMMA2
831E'   C3 84A8'       JMP   T ;BYTE=GAMMA1
8321'   3E 08          MVI   I1: A,S ;TRATARE PENTRU BYTE=ALFA
8323'   D3 29          OUT  29H ;COMANDA Th2
8325'   3E 07          MVI   A,7
8327'   3D          DCR   A
8328'   C2 8327'       JNZ   I1A: ;INTIRZIERE PENTRU FORMAREA
;IMPULSULUI
832B'   D3 29          OUT  29H
832D'   3E FF          MVI   A,255
832F'   32 2023        STA   BYTE ;BYTE=BETA
8332'   E5              PUSH  H
8333'   2A 2024        LHLD  YK1
8336'   7C              MOV   A,H
8337'   D6 3C          SUI   3CH
8339'   2F              CMA
833A'   67              MOV   H,A
833B'   7D              MOV   A,L
833C'   2F              CMA
833D'   6F              MOV   L,A
833E'   23              INX   H ;HL=T/2-HL
833F'   7C              MOV   A,H
8340'   B6 3F          ANI   3FH ;MASCARE PE 14 BITI
8342'   C6 80          ADI   80H ;MOD DE LUCRU 2
8344'   D3 2D          OUT  2DH ;TIMER HIGH
8346'   7D              MOV   A,I
8347'   D3 2C          OUT  2CH ;TIMER LOW
8349'   E1              POP    H
834A'   3E C1          MVI   A,0C1H
834C'   D3 28          OUT  28H ;START TIMER

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834F' F1 POP PSW
834F' C9 RET
PAGE

```

;
;
;
SUBROUTINA MASURA
;IN STATIC RAM
2030' 3E BC      MAS:  ORG 2030H
2032' D3 2D      MVI A,0E0H
2034' 3E 00      OUT 2DH
2036' D3 2C      MVI A,0
2038' 3E C1      OUT 2CH ;TIMER=5msec
203A' 0E 00      MVI A,0C1H
203C' D3 28      MVI C,0 ;CONTOR=0
203E' DB 2A      OUT 28H ;START TIMER
2040' E6 08      EF1: IN 2AH
2042' 47        ANI 8
2043' DB 2A      EF2: MOV B,A
2045' E6 08      IN 2AH
2047' B8        ANI 8
2048' CA 2043'  CMP B
204B' 0C        JZ EF2
204C' C3 203E'  INR C ;NUMARARE TRANZITII
                JMP EF1
                PAGE

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;
;
;
      ORG      8380H
8380' 2A 2024      ARN:  LHLJ)  YK1
8383' AF          ARN1: XRA    A
8384' 32 2021      STA    SIGN ;SIGN=0
8387' 3A 2026      LDA    BK
838A' 47          MOV    B,A
838B' 3A 2022      LDA    WK
838E' 90          SUB    B ;A=W-R
838F' D2 839B'    JNC    C3 ;SALT DACA W>=R
8392' 2F          CMA
8393' 3C          INR    A ;W<R
8394' 47          MOV    B,A ;R=-A
8395' 3E 01      MVI    A,1
8397' 32 2021      STA    SIGN ;SIGN=1
839A' 78          MOV    A,B ;A=B
;
;
;
      C3:  MOV    D,A
839B' 57          MOV    B,A
839C' 47          ORA    A
839D' B7          RAR
839E' 1F          MOV    B,A
839F' 5F          MVI    A,0
83A0' 3E 00      RAR
83A2' 1F          MOV    C,A
83A3' 4F          MOV    A,B
83A4' 78          ADD    E
83A5' 83          MOV    B,A
83A6' 47          MOV    A,D
83A7' 7A          ORA    A
83A8' B7          RAL
83A9' 17          MOV    B,A
83AA' 5F          MVI    A,C
83AB' 3E 00      RAR
83AD' 17          MOV    D,A
83AE' 57          MOV    A,C
83AF' 79          SUP    E
83B0' 93          MOV    C,A
83B1' 4F          MOV    A,B
83B2' 78          SPB    D
83B3' 9A          MOV    B,A
83B4' 47          MOV    A,E
83B5' 7B          ORA    A
83B6' B7          RAL
83B7' 17          MOV    B,A
83B8' 5F          MOV    A,D
83B9' 7A          RAL
83BA' 17          MOV    D,A
83BB' 57          MOV    A,C
83BC' 79          SUB    E
83BD' 93          MOV    C,A
83BE' 4F          MOV    A,B
83BF' 78

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83C0' 9A          - A1.6FB D
83C1' 47          MOV  E,A
;
83C2' 3A 2021    LDA  SIGN
83C5' B7          ORA  A
83C6' CA 83D0'   JZ   C5          ;SALT DACA SIGN=0
83C9' 79          MOV  A,C
83CA' 2F          CMA
83CB' 4F          MOV  C,A
83CC' 78          MOV  A,B
83CD' 2F          CMA
83CE' 47          MOV  B,A

83CF' 03          INX  B          ;SIGN=1; BC=-BC
83D0' 09          C5:  DAD  B          ;HL=HL+PC
83D1' 3E 01      MVI  A,1
83D3' 32 2021    STA  SIGN          ;SIGN=1
83D6' 3A 2027    LDA  RK1
83D9' 47          MOV  B,A
83DA' 3A 200B    LDA  W1
83DD' 90          SUB  B          ;A=W-R
83DE' D2 83E9'   JNC  C8          ;SALT DACA W>=R
83E1' 2F          CMA
83E2' 3C          INR  A
83E3' 47          MOV  B,A          ;E=-A
83E4' AF          XRA  A
83E5' 32 2021    STA  STGN          ;SIGN=C
83E8' 78          MOV  A,B          ;A=-B
;
83E9' 47          C8:  MOV  B,A
83EA' 4F          MOV  C,A
83EB' B7          ORA  A
83EC' 1F          RAR
83ED' 5F          MOV  E,A
83EE' 3E 00      MVI  A,0
83F0' 1F          RAR
83F1' 57          MOV  D,A
83F2' 7B          MOV  A,E
83F3' 1F          RAR
83F4' 5F          MOV  E,A
83F5' 7A          MOV  A,D
83F6' 1F          RAR
83F7' 57          MOV  D,A
83F8' 81          ADD  C
83F9' 4F          MOV  C,A
83FA' 78          MOV  A,B
83FB' 8B          ADC  E
83FC' 47          MOV  B,A
83FD' B7          ORA  A
83FE' 7B          MOV  A,E
83FF' 1F          RAR
8400' 5F          MOV  E,A
8401' 7A          MOV  A,D
8402' 1F          RAR
8403' 81          ADD  C
8404' 4F          MOV  C,A
8405' 78          MOV  A,B

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8406' 8B          ADC      E
8407' 47          MOV      B,A
;
8408' 3A 2021     LDA      SIGN
840B' B7          ORA      A
840C' CA 8416'   JZ       C10      ;SALT DACA SIGN=0
840F' 79          MOV      A,C
8410' 2F          CMA
8411' 4F          MOV      C,A
8412' 78          MOV      A,B
8413' 2F          CMA
8414' 47          MOV      B,A
8415' 03          INX      B      ;SIGN=1 ; BC=-BC
8416' 09          C10:    DAD      B      ;HL=HL+BC
8417' 3A 202B     LDA      TEST
841A' B7          ORA      A
841B' CA 842A'   JZ       C14      ;SALT DACA TEST=0
841E' 3E 71      MVI      A,71H    ;TEST=1
8420' EC          CMP      H      ;TEST DEPASIRE SUPERIOARA
8421' D2 8432'   JNC      C15
8424' 21 7200    LXI      H,7200H  ;CORECTIE DEPASIRE
8427' C3 8432'   JMP      C15
842A' 7C          C14:    MOV      A,H
842B' B7          ORA      A      ;TEST DEPASIRE INFERIOARA
842C' F2 8432'   JP       C15
842F' 21 0000    LXI      H,0      ;CORECTIE DEPASIRE
8432' 22 2028    C15:    SHLD   YK
8435' C9          RET
PAGE
    
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;
;
;
PROGRAMUL PRINCIPAL
ORG 8480H
8480' 31 BFFE LXI SP,OBFFEH ;INITIALIZARE STIVA
8483' AF XRA A
8484' 32 2022 STA WK ;INITIALIZARI VARIABLE
8487' 32 2026 STA RK
848A' 32 20C9 STA 20C9H ;ADRESA LOW PENTRU RST 6.5
;ESTE 00

848D' 32 2027 STA RK1
8490' 32 2000 STA FAN
8493' 32 2028 STA YK
8496' 32 2029 STA YK+1
8499' 3E 01 MVI A,1
849B' D3 28 OUT 28H ;PROGRAMARE PORTURI 29H, 2AH
849D' 3E 09 MVI A,9
849F' 30 DB 30H ;ACEASTA ESTE INSTRUCIUNEA SI
84A0' 3E 87 MVI A,87H
84A2' 32 20CA STA 20CAH ;ADRESA HIGH PENTRU RST 6.5
;ESTE 87H

84A5' C3 84A8' JMP T
;
T: ORG 8500H

8500' 3A 2028 LDA YK
8503' 32 2024 STA YK1 ;YK1=YK (LOW)
8506' 3A 2029 LDA YK+1
8509' 32 2025 STA YK1+1 ;YK1=YK (HIGH)
850C' AF XRA A
850D' 32 202B STA TEST
8510' 3A 2022 LDA WK
8513' 32 200B STA W1 ;WK1=WK
8516' 3A 2000 LDA FAN
8519' FE 02 CPI 2
851B' C2 8528' JNZ PP1
851E' 3A 2001 LDA ADCOD
8521' 32 2022 STA WK
8524' AF XRA A
8525' 32 2000 STA FAN

;
PP1: LDA YK1+1
852B' FE 3C CPI 3CH
852D' FA 8570' JM PP2 ;SALT IN REGIMUL 1 SAU 3

;
R2: MVI A,ODDH ;REGIMUL 2
8532' 32 2023 STA BYTE ;BYTE=GAMMA2
8535' 3E 04 MVI A,4
8537' D3 29 OUT 29H ;COMANDA Th1
8539' 3E 07 MVI A,7
853B' 3D R2T: DCR A
853C' C2 853B' JNZ R2T ;INTIRZIERE PENTRU FORMAREA
;IMPULSULUI

853F' D3 29 OUT 29H

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8541' 3C          INR    A
8542' 32 202B    STA    TEST    ;TEST=1
8545' C3 2030'   JMP    MAS
8548' AF          R2C:  XRA    A
8549' 32 2023    STA    BYTE    ;BYTE=ALFA
854C' 2A 2024    LHLD   YK1
854F' 7C          MOV    A,H
8550' D6 3C      SUI    3CH
8552' 32 2025    STA    YK1+1   ;YK1=YK1-T/2
8555' E6 3F      ANI    3FH
8557' C6 80      ADI    80H
8559' D3 2D      OUT    2DH
855B' 7D          MOV    A,L
855C' D3 2C      OUT    2CH    ;TIMER=YK1
855E' 3E C1      MVI    A,CC1H
8560' D3 28      OUT    28H    ;START TIMER
8562' CD 8383'   CALL   ARN1
8565' 76          HLT
8566' 3A 2023    R2A:  LDA    BYTE
8569' B7          ORA    A
856A' C2 8566'   JNZ    R2A    ;SALT DACA BYTE <> ALFA
856D' C3 84A8'   JMP    T      ;SALT DACA BYTE = ALFA

;
8570' FE 01      PP2:  CPI    1
8572' D2 8591'   JNC    R1    ;SALT IN REGIMUL 1
;
;
;
8575' 3E 19      R3:  MVI    A,25
8577' 32 2023    STA    BYTE    ;BYTE=BETA
857A' 3C          INR    A
857B' D3 2C      OUT    2CH
857D' 3E BC      MVI    A,ORCH
857F' D3 2D      OUT    2DH    ;TIMER=T/2
8581' 3E C1      MVI    A,CC1H
8583' D3 28      OUT    28H    ;START TIMER

;
8585' CD 8380'   CALL   ARN
8588' 76          HLT
8589' 3E 23      MVI    A,23H
858B' 32 2023    STA    BYTE    ;BYTE=GAMMA1
858E' C3 2030'   JMP    MAS
;
;
;
8591' 3E 04      R1:  MVI    A,4
8593' D3 29      OUT    29H    ;AMORSARE Th1
8595' 3E 07      MVI    A,7
8597' 3D          R1T:  DCR    A
8598' C2 8597'   JNZ    R1T    ;FORMARE IMPULS
859B' D3 29      OUT    29H
859D' AF          XRA    A
859E' 32 2023    STA    BYTE    ;BYTE=ALFA
85A1' 3A 2024    LDA    YK1
85A4' D3 2C      OUT    2CH
85A6' 3A 2025    LDA    YK1+1
85A9' E6 3F      ANI    3FH
85AB' C6 80      ADI    80H
85AD' D3 2D      OUT    2DH    ;TIMER=YK1
85AF' 3E C1      MVI    A,CC1H
85B1' D3 28      OUT    28H

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85B3'	CD 8380'		CALL	ARN	
85B6'	76		HIT		
85B7'	3A 2023	R1A:	LDA	BYTE	
85BA'	B7		ORA	A	
85BB'	02 85B7'		JNZ	R1A	;SALT DACA BYTE <> ALFA
85BE'	3E 23		MVI	A,23H	;BYTE = ALFA
85C0'	32 2023		STA	BYTE	;BYTE = GAMMA1
85C3'	03 2030'		JMP	MAS	
			PAGE		

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;
;
;
      ORG      8700H
      PUSH    PSW
      PUSH    B
      LDA     7000H
      CALL   4336H      ;TRANSFORMA A(DAF) IN B(ASCII)
      XTHL   XTHL
      XTHL   XTHL
      XTHL   XTHL
      XTHL   XTHL
      XTHL   XTHL
      XTHL   XTHL
      XTHL   XTHL
      XTHL   XTHL
      XTHL   XTHL
      XTHL   XTHL
      ;INTIRZIERE CERUTA DE
      ;INTERFATA CU DAF-UL
      ;TRIMITE B(ASCII) CATRE DAF
      CALL   4436H
      LDA     FAN
      ORA     A
      EDI     ;SAIT DACA FAN >= 1
      MOV     A,B      ;FAN=0; A=CARACTER ASCII
      CALL   4565H     ;CONVERSIE A(ASCII) IN A(HEXA)
      STA     ADCOD    ;DEPOZITARE PROVIZOPIE
      MVI     A,1
      STA     FAN      ;FAN=1
      POP     B
      POP     PSW
      EI
      RET
      EDI:   MOV     A,B      ;FAN=1; A=CARACTER ASCII
      CALL   4565H     ;CONVERSIE A(ASCII) IN A(HEXA)
      MOV     B,A      ;B=ULTIMUL CARACTER
      ;RECEPTIONAT (HEXA)
      PUSH    H
      LXI    H,ADCOD
      MOV     A,M      ;A=PRIMUL CARACTER
      ;RECEPTIONAT (HEXA)
      RLC
      RLC
      RLC
      RLC
      ORA     A      ;FORMARE OCTET DIN CULE 2
      ;CARACTERE
      ;ADCOD = VALOARE RECEPTIONATA
      MOV     M,A
      POP     H
      MVI     A,2
      STA     FAN      ;FAN=2 (RECEPTIE COMPLETA)
      CALL   CRLF     ;CAR RETURN, LINE FRED
      POP     B
      POP     PSW
      EI
      RET
8700'  F5
8701'  C5
8702'  3A 7000
8705'  CD 4336
8708'  E3
8709'  E3
870A'  E3
870B'  E3
870C'  E3
870D'  E3
870E'  E3
870F'  E3
8710'  CD 4436
8713'  3A 2000
8716'  B7
8717'  C2 872A'
871A'  78
871B'  CD 4565
871E'  32 2001
8721'  3E 01
8723'  32 2000
8726'  C1
8727'  F1
8728'  FB
8729'  C9
872A'  78
872B'  CD 4565
872E'  47
872F'  E5
8730'  21 2001
8733'  7E
8734'  07
8735'  07
8736'  07
8737'  07
8738'  B7
8739'  77
873A'  E1
873B'  3E 02
873D'  32 2000
8740'  CD 4441
8743'  C1
8744'  F1
8745'  FB
8746'  C9

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END

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Macros:

Symbols:

2012	ADAD	2001	ADCOD	8380'	ARN
8383'	ARN1	2023	BYTE	8416'	C10
842A'	C14	8432'	C15	839B'	C3
83D0'	C5	83E9'	C8	4441	ORLF
872A'	ED1	203E'	EF1	2043'	EP2
2000	FAN	8321'	I1	8327'	I1A
8312'	I2	2030'	MAS	8528'	PP1
8570'	PP2	8591'	R1	85B7'	R1A
8597'	R1T	8530'	R2	8566'	R2A
8548'	R2C	853B'	R2T	8575'	R3
2026	RK	2027	RK1	2021	SIGN
84A3'	T	202B	TEST	200F	W1
202?	W1	2028	YK	2024	YK1

No Fatal error(s)

ANEXA A2

PROGRAM DE REGLARE NUMERICA A TITLĂȚIEI
ȘI MOTOR DE CURENT CONTINUU

-VARIANTA CHOPPERULUI CU TRANȘĂȚARE-

568.331 |
191 H

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;
; PROGRAM DE REGLARE NUMERICA A TURATIEI UNUI MCC
;
;
; VARIANTA TRANZISTORIZATA
;
; INITIALIZARI VARIABLE SI COEFICIENTI
202C SRK EQU 202CH ;SEMN RK
202D SRK1 EQU SRK+1 ;SEMN RK1
202E SW EQU SRK+2 ;SEMN WK
200B SW1 EQU 200BH ;SEMN W1
201E YT EQU 201EH ;MARIME DE COMANDA PENTRU
;TIMER
2015 DO EQU 2015H ;COEFICIENT d0
2017 D1 EQU 2017H ;COEFICIENT d1
2023 RYTE EQU 2023H ;OCTET DE CONTROL PENTRU
;RST 7.5
2022 WK EQU 2022H ;MARIME PRESCRISA wk
200B W1 EQU 200BH ;MARIME PRESCRISA wk-1
2026 RK EQU 2026H ;REACTIE rk
2027 RK1 EQU 2027H ;REACTIE rk-1
2028 YK EQU 2028H ;MARIME DE COMANDA yk
2024 YK1 EQU 2024H ;MARIME DE COMANDA yk-1
2021 STGN EQU 2021H ;SEMN ABATERE
200C KP EQU 200CH ;COEFICIENT kr
200E TI EQU 200EH ;COEFICIENT Ti
2001 ADCOD EQU 2001H ;ADRESA PRESCRIERE DE LA DAF
202B TEST EQU 202BH ;VARIABILA FANION
4441 CRLF EQU 4441H ;SUBRUTINA PENTRU CR, LF
2012 ADAD EQU 2012H ;ADRESA CURENTA PENTRU
;RECEPTIE DAF
2019 ADIN EQU 2019H ;ADRESA INITIALA PENTRU
;RECEPTIE DAF
2014 ADSI EQU 2014H ;SEMN ADCOD
4437 OU EQU 4437H ;SUBRUTINA PENTRU CR, LF
D000 MES1 EQU 0D000H ;ADRESA MESAJ 1
D1A0 MES2 EQU 0D1A0H ;ADRESA MESAJ 2
D1B0 MES3 EQU 0D1B0H ;ADRESA MESAJ 3
D200 MES4 EQU 0D200H ;ADRESA MESAJ 4
456D HOUT EQU 456DH ;SUBRUTINA OUT DAF (HEXA)
45AD SCRIN EQU 45ADH ;SUBRUTINA EDITARE TEXTE PE DAF
2000 FAN EQU 2000H ;FANION RECEPTIE COMPLETA DAF
PAGE

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;
20CE' C3 8800          ; ORG 20CEH ;AICI SE AJUNGE PRIN RST 7.5
                      ; JMP 8800H ;SALT IN INTERRUPT TIMER
;
                      ; ORG 8800H
                      ;SUBRUTINA INTERRUPT TIMER
8800' F5              PUSH PSW
8801' FB              EI
8802' 3A 2023         LDA BYTE
8805' B7              ORA A
8806' CA 882D'        JZ I1 ;SALT DACA BYTE = ALFA
8809' 3C              INR A
880A' C2 8812'        JNZ I2 ;SALT DACA BYTE = GAMMA
880D' 32 2023         STA BYTE ;BYTE A POST BETA, VA FI ALFA
8810' F1              POP PSW
8811' C9              RET
8812' F5              I2: PUSH PSW ;TRATAREA PENTRU BYTE = GAMMA
8813' 21 2026         LXI H,RK
8816' 56              MOV D,M ;D=RK
8817' 71              MOV M,C ;RK=REZULTAT MASURA
8818' 23              INX H
8819' 72              MOV M,D ;RK1=D
881A' 2E 2C           MVI L,2CH ;HL=ADRESA SRK
881C' 56              MOV D,M ;D=SRK
881D' DB 08           IN 8 ;PRELUARE SEMN REACTIE
881F' E6 01           ANI 1 ;MASCARE
8821' 77              MOV M,A ;SRK=A
8822' F1              POP PSW ;RESTAURARE FLAGURI (I2)
8823' 23              INX H ;HL=ADRESA SRK1
8824' 72              MOV M,D ;SRK1=D
8825' E1              POP H ;IGNORARE PSW SALVAT INITIAL
8826' E1              POP H ;IGNORARE ADRESA DE INTOARCERE
                      ;IN PROGRAMUL APLANT
8827' FA 8592'        JM R2C ;BYTE=GAMMA2
882A' C3 84E5'        JMP T ;BYTE=GAMMA1
882D' D3 29           I1: OUT 29H
882F' 3E FF           MVI A,255
8831' 32 2023         STA BYTE ;BYTE=BETA
8834' E5              PUSH H
8835' 2A 201E         LHLD YT
8838' 7C              MOV A,H
8839' D6 3C           SUI 3CH
883B' 2F              CMA
883C' 67              MOV H,A
883D' 7D              MOV A,L
883E' 2F              CMA
883F' 6F              MOV L,A
8840' 23              INX H ;HL=T/2-HL
8841' 7C              MOV A,H
8842' E6 3F           ANI 3FH ;MASCARE PE 14 BITI
8844' C6 80           ADI 80H ;MOD DE LUCRU 2
8846' D3 2D           OUT 2DH ;TIMER HIGH
8848' 7D              MOV A,L
8849' D3 2C           OUT 2CH ;TIMER LOW

```

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884B'	F1	POP	H	
884C'	3E C1	MVI	A,0C1H	
884E'	D3 28	OUT	28H	;START TIMER
8850'	F1	POP	PSW	
8851'	C9	RET		
		PAGE		

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```

;
;
;
          SUBROUTINA MASURA
          ;IN STATIC RAM
          ORG 2030H
MAS:      MVI A,00CH
          OUT 2BH
          MVI A,0
          OUT 2CH ;TIMER=5msec
          MVI A,0011H
          MVI C,0 ;CONTOR=0
          OUT 2BH ;START TIMER
EF1:     IN 2AH
          ANI 8
          MOV B,A
EF2:     IN 2AH
          ANI 8
          CMP B
          JZ EF2
          INR C ;NUMARARE TRANZITII
          JMP EF2-1
          PAGE
    
```

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```

;
;
;
;
      SUBROUTINA CALCUL ARN
      ORG      8880H
      ARN:    LHL.D  YK1
      ARN1:   XRA    A
              STA   SIGN  ;SIGN=0
              LDA   SRK
              MOV   B,A
              LDA   SW
              XRA   B
              JNZ  A2      ;SALT PENTRU SEMNE DIFERITE
              ORA   B      ;SEMNE IDENTICE
              LDA   RK
              MOV   B,A
              LDA   WK
              JNZ  A3      ;SALT DACA W<0 SI R<0
              SUB  B      ;W>=0 SI R>=0 ; A=W-R
              JNC  C3      ;SALT DACA W>=R
      A4:    CMA
              INR   A
              MOV   B,A
              MVI   A,1
              STA   SIGN  ;SIGN=1
              MOV   A,B
              JMP   C3
      A3:    MOV   C,A
              MOV   A,B
              SUB  C      ;A=W-R
              JMP   A4
      A2:    XRA   B
              LDA   RK
              MOV   B,A
              LDA   WK
              JNZ  A5      ;SALT DACA W<0 SI R>=0
              ADD  B      ;W>=0 SI R<0 ; A=W+R
              JNC  C3
              MVI   A,255 ;CORECTIE DEPASIRE
              JMP   C3
      A5:    ADD   B      ;A=W+R
              MOV   B,A
              MVI   A,1
              STA   SIGN  ;SIGN=1
              MOV   A,B
              JNC  C3
              MVI   A,255 ;CORECTIE DEPASIRE
      C3:    XCHG
              LHL.D  DO
              CALL  INO   ;INMULTIRE CU do
              XRA   A
              STA   SIGN  ;SIGN=0
              LDA   SRK1
              MOV   B,A
              LDA   SW1

```

```

88F6'  A8                XRA      B
88F7'  C2 890B'        JNZ      A6      ;SALT PENTRU SEMNE DIFERITE
88EA'  B0              ORA      B      ;SEMNE IDENTICE
88EB'  3A 2027        LDA      RK1
88F3'  47              MOV      B,A
88EF'  3A 200B        LDA      W1
88F2'  CA 8905'        JZ       A7      ;SALT DACA W>=0 SI R>=0
88F5'  90              SUB      B      ;W<0 SI R<0 ; A=W-R
88F6'  D2 892C'        A8:     JNC      C8      ;SALT DACA W>=R
88F9'  2F              CMA
88FA'  3C              INR      A
88FB'  47              MOV      B,A
88FC'  3E 01          MVI      A,1
88FE'  32 2021        STA      SIGN    ;SIGN=1
8901'  78              MOV      A,B
8902'  C3 892C'        JMP      C8
8905'  4F              A7:     MOV      C,A
8906'  78              MOV      A,B
8907'  91              SUB      C      ;A=R-W
8908'  C3 88F5'        JMP      A8
890B'  A8              A5:     XRA      B
890C'  3A 2027        LDA      RK1
890F'  47              MOV      B,A
8910'  3A 200B        LDA      W1
8913'  CA 891F'        JZ       A9      ;SALT DACA W>=0 SI R<0
8916'  80              ADD      B      ;A=W+R
8917'  D2 892C'        JNC      C8
891A'  3E FF          MVI      A,255   ;CORECTIE DEPASIRE
891C'  C3 892C'        JMP      C8
891F'  80              A9:     ADD      B      ;A=W+R
8920'  47              MOV      B,A
8921'  3E 01          MVI      A,1
8923'  32 2021        STA      SIGN    ;SIGN=1
8926'  78              MOV      A,B
8927'  D2 892C'        JNC      C8
892A'  3E FF          MVI      A,255   ;CORECTIE DEPASIRE
892C'  EF              C8:     XCHG
892D'  2A 2017        LHLD    D1
8930'  CD 8770'        CALL   INO      ;INMULTIRE CU d1
8933'  C9              RET           ;REZULTATUL NECORECTAT IN H
;
;
;
ORG      84A0H
84A0'  31 BFFE        LXI      SP,0BFFE ;INITIALIZARE STIVA
84A3'  AF            XRA      A
84A4'  D3 0A          OUT     10      ;PROGRAMARE PORT B
84A6'  32 2022        STA     WK      ;INITIALIZARI VARIABLE
84A9'  32 201E        STA     YT
84AC'  32 201F        STA     YT+1
84AF'  32 202E        STA     SW
84B2'  32 202B        STA     TEST
84B5'  32 202C        STA     SRK
84B8'  32 202D        STA     SRK1
84BB'  32 2026        STA     RK
84BE'  32 2014        STA     ADSI

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84C1'  32 20C9          STA    20C9H    ;ADRESA LOW PENTRU RST 6.5
                        ;ESTE 00
84C4'  32 2027          STA    RK1
84C7'  32 2000          STA    FAN
84CA'  32 2028          STA    YK
84CD'  32 2029          STA    YK+1
84D0'  3E 01           MVI    A,1
84D2'  D3 28           OUT    28H    ;PROGRAMARE PORTURI 29H SI 2AH
84D4'  3E 09           MVI    A,9
84D6'  30              DB     30H    ;ACEASTA ESTE INSTRUCIUNEA SI
84D7'  3E 87           MVI    A,87H
84D9'  32 20CA          STA    20CAH  ;ADRESA HIGH PENTRU RST 6.5
                        ;ESTE 87H

84DC'  21 2019          LXI    H,ADIN
84DF'  22 2012          SHLD  ADAD
84E2'  C3 84E5'        JMP    T

                        ;
                        T:
84E5'          ORG    8500H

8500'  3A 2028          LDA    YK
8503'  32 2024          STA    YK1    ;YK1=YK (LOW)
8506'  3A 2029          LDA    YK+1
8509'  32 2025          STA    YK1+1  ;YK1=YK (HIGH)
850C'  3A 2022          LDA    WK
850F'  4F              MOV    C,A    ;C=WK
8510'  32 200B          STA    W1     ;W1=WK
8513'  3A 202E          LDA    SW
8516'  32 200B          STA    SW1   ;SW1=SW
8519'  3A 2000          LDA    FAN
851C'  B7              ORA    A
851D'  CA 8570'        JZ     PP1    ;SALT PENTRU FAN=0
8520'  3A 2001          LDA    ADCOD
8523'  57              MOV    D,A    ;D=WDAF
8524'  3A 2014          LDA    ADSI
8527'  47              MOV    B,A    ;B=SDAF
8528'  3A 202E          LDA    SW    ;A=SW
852B'  A8              XRA    B
852C'  79              MOV    A,C    ;A=WK
852D'  C2 855D'        JNZ   T1     ;SALT PENTRU SEMNE DIFERITE
8530'  BA              CMP    D     ;SEME IDENTICE
8531'  DA 8543'        JC     T2    ;SALT PENTRU WDAF>WK
8534'  D6 14           SUI   20    ;WDAF<=WK ; A=WK+20
8536'  DA 854F'        JC     T3    ;SALT PENTRU A<0
                        ;(DEPASIRE INFERIOARA)
8539'  32 2022          STA    WK    ;WK=A
853C'  BA              CMP    D
853D'  D2 8570'        JNC   PP1   ;SALT DACA WDAF<=A
                        ;(PRELUAREA NU S-A TERMINAT)
8540'  C3 854F'        JMP    T3    ;SALT DACA WDAF>A
8543'  C6 14           ADI   20    ;WDAF>WK ; A=WK+20
8545'  DA 854F'        JC     T3    ;SALT IN CAZ DE DEPASIRE
8548'  32 2022          STA    WK    ;WK=A
854B'  BA              CMP    D
854C'  DA 8570'        JC     PP1   ;SALT DACA WDAF>A
                        ;(PRELUAREA NU S-A TERMINAT)
854F'  7A              MOV    A,D   ;FINAL PRELUARE
                        T3:

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```

8550' 32 2022          STA   WK      ;WK=WDAF
8553' AF              XRA   A
8554' 32 2000          STA   FAN     ;FAN=0 (RECEPTIE COMPLETA)
8557' 32 2014          STA   ADSI    ;ADSI=0
855A' C3 8570'        JMP   PP1
855D' D6 14           T1:   SUI   20   ;SEMNE DIFERITE ; A=WK-20
855F' 32 2022          STA   WK      ;WK=A
8562' D2 8570'        JNC   PP1    ;SALT DACA A>0
                                   ;(PRELUAREA NU S-A TERMINAT)

8565' 2F              CMA
8566' 3C              INR   A
8567' 4F              MOV   C,A
8568' 78              MOV   A,B
8569' 32 202E        STA   SW      ;SW=SDAF
856C' 79              MOV   A,C
856D' C3 854B'        JMP   T3-4   ;SALT IN RAMURA CU SEMNE
                                   ;IDENTICE

8570' 3A 2025        PP1:   LDA   YK1+1
8573' B7              ORA   A
8574' F2 8575'        JP    J+1
8577' 2F              CMA
8578' FE 3C          CPI   3CH
857A' FA 85EB'        JM    PP2    ;SALT IN REGIMUL 1 SAU 3

;
R2:   MVI   A,ODDH  ;REGIMUL 2
      STA   BYTE   ;BYTE=GAMMA2
      LDA   TEST
      ORA   A
      MVI   A,4
      JZ    R2T    ;SALT DACA TEST=0 ; A=4
      ADI   4      ;TEST=1 ; A=8
R2T:  OUT   29H    ;COMANDA TRANZISTOARE
      JMP   MAS
R2C:  XRA   A
      STA   BYTE   ;BYTE=ALFA
      LHLD YK1
      ADD   H      ;A=YK1 (HIGH)
      PUSH H
      JP    R2B    ;SALT DACA YK1>=0
      ADI   3CH    ;YK1<0
      CMA
      MOV   H,A
      MOV   A,L
      CMA
      MOV   L,A
      INX   H      ;HL=!YK1!-T/2
      MOV   A,H
      JMP   R2E
R2B:  SUI   3CH
      MOV   H,A   ;HL=YK1-T/2
R2E:  SHLD YT     ;YT=HL
      ANI   3FH
      ADI   80H
      OUT   2DH
      MOV   A,L
      OUT   2CH   ;TIMER=HL

```

```

85B9' 3E C1          MVI    A,CC1H
85BB' D3 28          OUT    23H      ;START TIMER
85BD' E1            POP    H
85BE' CD 8883'      CALL   ARN1
85C1' 3A 202B      LDA    TEST
85C4' B7           ORA    A
85C5' C2 85D4'      JNZ    R2P      ;SALT DACA YK1<0
85C8' 3E 77        MVI    A,77H    ;YK1>0
85CA' EC          CMP    H      ;TEST DEPASIRE SUPERIOARA
85CB' D2 85DD'      JNC    R2D
85CE' 21 77F0      LXI    H,77F0H  ;CORECTIE DEPASIRE
85D1' C3 85DD'      JMP    R2D
85D4' 3E 87        R2P:   MVI    A,87H
85D6' EC          CMP    H      ;TEST DEPASIRE INFERIOARA
85D7' DA 85DD'      JC     R2D
85DA' 21 8810      LXI    H,8810H ;CORECTIE DEPASIRE
85DD' 22 2028      R2D:   SHLD   YK      ;YK=REZULTAT CALCUL ARN,
                        ;CORECTAT

85E0' 76          HLT
85E1' 3A 2023      R2A:   LDA    BYTE
85E4' B7           ORA    A
85E5' C2 85E1'      JNZ    R2A      ;SALT DACA BYTE <> ALFA
85E8' C3 84E5'      JMP    T        ;SALT DACA BYTE = ALFA

;
85EB' B7          PP2:  ORA    A
85EC' C2 861C'      JNZ    R1
85EF' 3A 2024      LDA    YK1
85F2' B7           ORA    A
85F3' C2 861C'      JNZ    R1

;
85F6' 3E FF        R3:   MVI    A,255
85F8' 32 2023      STA    BYTE     ;BYTE=BETA
85FB' 3C          INR    A
85FC' D3 2C        OUT    2CH
85FE' 3E EC        MVI    A,0ECH
8600' D3 2D        OUT    2DH      ;TIMER=T/2
8602' 3E C1        MVI    A,CC1H
8604' D3 28        OUT    23H      ;START TIMER
8606' CD 8880'      CALL   ARN
8609' 7C          MOV    A,H
860A' 07          RLC
860B' E6 01        ANI    1
860D' 32 202B      STA    TEST     ;ACTUALIZARE VARIABILA "TEST"
8610' 22 2028      SHLD   YK      ;YK=REZULTAT CALCUL ARN,
                        ;CORECTAT

8613' 76          HLT
8614' 3E 23        MVI    A,23H
8616' 32 2023      STA    BYTE     ;BYTE=GAMMA1
8619' C3 2030'      JMP    MAS

;
861C' 3A 202B      R1:   LDA    TEST
861F' B7           ORA    A
8620' 3E 04        MVI    A,4
8622' CA 8627'      JZ     R1T      ;SALT DACA TEST=0 ; A=4
8625' C6 04        ADI    4         ;TEST=1 ; A=8
8627' D3 29        R1T:  OUT    29H    ;COMANDA TRANZISTOARE

```



```
8629' 2A 2024          LHLD   YK1
862C' AF              XRA    A
! 862D' 32 2023       STA    BYTE ;BYTE=ALFA
8630' 84              ADD    H
8631' E5              PUSH   H
8632' F2 863B'        JP     R1B ;SALT DACA YK1>=0
8635' 2F              CMA
8636' 67              MOV    H,A
8637' 7D              MOV    A,L
8638' 2F              CMA
8639' 6F              MOV    L,A
863A' 23              INX    H ;HL=!YK1!
863B' 22 201E        R1B:   SHLD  YT
863E' 7D              MOV    A,L
863F' D3 2C          OUT    2CH
8641' 7C              MOV    A,H
8642' E6 3F          ANI    3FH
8644' C6 80          ADI    80H
8646' D3 2D          OUT    2DH ;TIMER=HL
8648' 3E C1          MVI    A,0C1H
864A' D3 28          OUT    28H ;START TIMER
864C' E1              POP    H
864D' CD 88E3'        CALL  ARN1
8650' 7C              MOV    A,H
8651' 07              RLC
8652' E6 01          ANI    1
8654' 32 202B        STA    TEST ;ACTUALIZARE VARIABILA TEST
8657' 22 2028        SHLD  YK ;YK=REZULTAT CALCUL ARN,
;CORECTAT

865A' 76              HLT
865B' 3A 2023        R1A:   LDA    BYTE
865E' B7              ORA    A
865F' C2 865B'        JNZ   R1A ;SALT DACA BYTE <> ALFA
8662' 3E 23          MVI    A,23H ;BYTE=ALFA
8664' 32 2023        STA    BYTE ;BYTE=GAMMA1
8667' C3 2030'        JMP    MAS
PAGE
```

```

;
;
;
      ORG      8700H
8700'  F5      PUSH   PSW
8701'  C5      PUSH   B
8702'  E5      PUSH   H
8703'  2A 2012 LHLD   ADAD      ;HL=ADRESA ADRESEI CURENTE
8706'  3A 7000 LDA    7000H
8709'  CD 4336 CALL   4336H      ;TRANSFORMA A(DAF) IN B(ASCII)
870C'  0E 19   MVI   C,25
870E'  0D      DCR    C
870F'  C2 870B JNZ   J-4      ;INTIRZIERE CERUTA DE
;INTERFATA CU DAF-UL
;A=CARACTER ASCII RECEPTIONAT
8712'  78      MOV   A,B
8713'  FE 2D   CPI   '-'
8715'  C2 8723 JNZ   ED2      ;SALT DACA NU E 'MINUS'
8718'  CD 4437 CALL   OU        ;TRIMITE ECOU CATRE DAF
871B'  3E 01   MVI   A,1
871D'  32 2014 STA   ADSI      ;ADSI=1
8720'  C3 8730 JMP   ED3
8723'  FE 0D   ED2:  CPI   13
8725'  CA 8735 JZ    ED1      ;SALT DACA E "RETURN"
8728'  CD 4437 CALL   OU        ;ECOU CATRE DAF
872B'  70      MOV   M,B      ;INSCRIERE IN SIRUL DE
;CARACTERE
872C'  23      INX   H
872D'  22 2012 SHLD  ADAD      ;ADAD=ADAD+1
8730'  E1      ED3:  POP   H      ;RESTAURARE REGISTRE -
;FINAL SUBRUTINA
8731'  C1      POP   B
8732'  F1      POP   PSW
8733'  FB      EI
8734'  C9      RET
;
8735'  3E 3D   ED1:  MVI   A,'='
8737'  CD 4437 CALL   OU        ;TRIMITE LA DAF '='
873A'  36 00   MVI   M,0      ;SFIRSIT SIR CARACTERE
;RECEPTIONATE
873C'  3A 2014 LDA   ADSI
873F'  B7      ORA   A
8740'  CA 8748 JZ    ED4      ;SALT DACA ADSI=0
8743'  3E 2D   MVI   A,'-'
8745'  CD 4437 CALL   OU        ;DACA NU,
;TRIMITE LA DAF '-'
8748'  01 2019 ED4:  LXI   B,ADIN
874B'  21 2019 LXI   H,ADIN
874E'  22 2012 SHLD  ADAD      ;ADAD=ADRESA INITIALA
8751'  D5      PUSH  D
8752'  CD 4534 CALL   4534H      ;TRANSFORMA CIFRELE ZECIMALE
; (ASCII) INCEPIND DE LA ADRESA
; BC IN HEXA (HL). REVENIREA
; DIN SUBRUTINA SE FACE LA
; PRIMUL ZERO (OO) INTILMIT.
; SUBRUTINA AFECTEAZA TOATE
;
```

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```

;
8755' E5          PUSH   H
8756' 7D          MOV    A,L
8757' CD 456D     CALL   HOUT ;TRIMITE A LA DAF
;              ;(FORMAT HEXA)

875A' E1          POP    H
875B' D1          POP    D
875C' 3E 48       MVI   A,'H'
875E' CD 4437     CALL   OU   ;TRIMITE LA DAF 'H'
8761' CD 4441     CALL   CRLF ;CAR RETURN, LINE FEED
8764' 7D          MOV    A,L
8765' 32 2001     STA   ADCOD ;ADCOD=VALOAREA RECEPTIONATA
8768' 3E 01       MVI   A,1
876A' 32 2000     STA   FAN  ;FAN=1
876D' C3 8730'   JMP   ED3
PAGE
```

```

;
8770' 47          INO:  MOV    E,A
8771' EB          XCHG
8772' 3A 2021     LDA    SIGN
8775' B7          ORA    A
8776' CA 8780'   JZ     INM    ;SALT DACA SIGN=0
8779' 7A          MOV    A,D    ;SIGN=1
877A' 2F          CMA
877B' 57          MOV    D,A
877C' 7B          MOV    A,E
877D' 2F          CMA
877E' 5F          MOV    E,A
877F' 13          INX    D      ;DE=-DE
;                                     SUBROUTINA INM EXECUTA
;                                     OPERATIA HL=HL+B*DE
8780' 0E 08     INM:  MVI    C,8
8782' 78          IN2:  MOV    A,B
8783' 1F          RAR
8784' 47          MOV    B,A
8785' D2 8789'   JNC    IN3
8788' 19          DAD    D
8789' EB          IN3:  XCHG
878A' 29          DAD    H
878B' EB          XCHG
878C' 0D          DCR    C
878D' C2 8782'   JNZ    IN2
8790' C9          RET
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C163'	03		INX	B
C164'	09		DAD	B
C165'	09		DAD	B
C166'	22 2017		SHLD	D1 ;d1=(b)-(d)
				;
C169'	0E 04		MVI	C,4
C16B'	21 D200		LXI	H,MES4
C16E'	CD 45AD	SJ:	CALL	SCRN
C171'	CD 4441		CALL	CRLF
C174'	23		INX	H
C175'	0D		DCR	C
C176'	C2 C16E'		JNZ	SJ
C179'	CD 45AD		CALL	SCRN
C17C'	EB		XCHG	
C17D'	2A 2015		LHLD	D0 ;HL=d0
C180'	CD C1B9'		CALL	S3
C183'	23		INX	H
C184'	CD 45AD		CALL	SCRN
C187'	EB		XCHG	
C188'	2A 2017		LHLD	D1
C18B'	CD C1B9'		CALL	S3
C18E'	23		INX	H
C18F'	CD 45AD		CALL	SCRN
C192'	09		RET	;REVENIRE IN SISTEMUL ;DE OPERARE
				;
C193'	01 0000	IMP:	LXI	B,0 ;SUBRUTINA EXECUTA ;IMPARTIREA BC=HL/DE
C196'	7B		MOV	A,E
C197'	2F		CMA	
C198'	5F		MOV	E,A
C199'	7A		MOV	A,D
C19A'	2F		CMA	
C19B'	57		MOV	D,A
C19C'	13		INX	D
C19D'	19	IM1:	DAD	D
C19E'	D0		RNC	
C19F'	03		INX	B
C1A0'	03 C19D'		JMP	IM1
				;
C1A3'	CD 4429	SO:	CALL	4429H ;ASTEAPTA SOSIREA UNUI ;CARACTER DE LA DAF, ;IL TRANSFORMA IN B (ASCI)
C1A6'	70		MOV	M,B
C1A7'	78		MOV	A,B
C1A8'	CD 4437		CALL	OU ;ECOUL CATRE DAF
C1AB'	78		MOV	A,B
C1AC'	FE 0D		CPI	13
C1AE'	23		INX	H
C1AF'	C2 C1A3'		JNZ	SO ;SALT DACA NU E "RETURN"
C1B2'	2B		DCX	H
C1B3'	36 00		MVI	M,0 ;SFIIRSIT STR DE CARACTERE ;RECEPTIONATE
C1B5'	CD 4441		CALL	CRLF
C1B8'	09		RET	

```

C1B9'  EB          S3:  XCHG          ;SUBROUTINA TRIMITE LA DAF HL,
C1BA'  E5          PUSH          H      ;IN FORMAT HEXA SI ZECIMAL
C1BB'  7A          MOV           A,D
C1BC'  CD 456D     CALL          HOUT
C1BF'  7B          MOV           A,E
C1C0'  CD 456D     CALL          HOUT
C1C3'  E1          POP           H
C1C4'  23          INX           H
C1C5'  CD 45AD     CALL          SCRNR
C1C8'  23          INX           H
C1C9'  E5          PUSH          H
C1CA'  21 0000     LXI           H,0
C1CD'  7A          S4:  MOV           A,D
C1CE'  B3          ORA           E
C1CF'  CA C1DF'   JZ            S2
C1D2'  1B          DCX           D
C1D3'  7D          MOV           A,L
C1D4'  3C          INR           A
C1D5'  27          DAA
C1D6'  6F          MOV           L,A
C1D7'  7C          MOV           A,H
C1D8'  CE 00      ACI           0
C1DA'  27          DAA
C1DB'  67          MOV           H,A
C1DC'  C3 C1CD'   JMP            S4
C1DF'  7C          S2:  MOV           A,H
C1E0'  5D          MOV           E,L
C1E1'  CD 456D     CALL          HOUT
C1E4'  7B          MOV           A,E
C1E5'  CD 456D     CALL          HOUT
C1E8'  E1          POP           H
C1E9'  CD 45AD     CALL          SCRNR
C1EC'  CD 4441     CALL          CRLF
C1EF'  C9          RET
                                BND

```

Macros:

Symbols:

88B3'	A2	88AD'	A3	889E'	A4
88C7'	A5	890E'	A6	8905'	A7
88F6'	A8	891F'	A9	2012	ADAD
2001	ADCOD	2019	ADIN	2014	ADSI
8880'	ARN	8883'	ARN1	2023	BYTE
88D4'	C3	892C'	C8	4441	CRLF
2015	D0	2017	D1	8735'	ED1
8723'	ED2	8730'	ED3	8748'	ED4
203E'	EF1	2043'	EF2	2000	FAN
456D	HOUT	882D'	I1	8812'	I2
C19D'	IM1	C193'	IMP	8770'	INO
8782'	IN2	8789'	IN3	8780'	INM
200C	KR	2030'	MAS	D000	MES1
D1A0	MES2	D1B0	MES3	D200	MES4
4437	OU	8570'	PP1	85EB'	PP2
861C'	R1	865B'	R1A	863B'	R1B
8627'	R1T	857D'	R2	85E1'	R2A
85AA'	R2B	8592'	R2C	85DD'	R2D
85AD'	R2E	85D4'	R2P	858D'	R2T
85F6'	R3	2026	RK	2027	RK1
C1DF'	S2	C1B9'	S3	C1CD'	S4
45AD	SCRN	C105'	SI	2021	SIGN
C16E'	SJ	C1A3'	S0	202C	SRK
202D	SRK1	202E	SW	200B	SW1
84E5'	T	855D'	T1	8543'	T2
854F'	T3	202B	TEST	200E	TI
200E	W1	2022	WK	2028	YK
2024	YK1	201E	YT		

No Fatal error(s)

- 13.0 -

ANEXA A3

PROGRAM DE REGLARE NUMERICA A VITEI SI
POZITII PENTRU UN SISTEM DE ACTIUNARE CU
MOTOR DE CURENT CONTINUU

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```
0000' 09          R  
                ;  
                ;                               Program de reglare numerica  
                ;                               a vitezei si pozitiei unui MCC  
                ;  
                ;                               Definire coeficienti  
                ;                               si variabile  
2016          ADAD  EQU      2016H  ;adresa curenta pentru  
                ;receptie DAF  
2018          D0    EQU      2018H  ;coeficient D0  
2019          D1    EQU      D0+1   ;coeficient D1  
201A          D2    EQU      D0+2   ;coeficient D2  
201C          D3    EQU      D0+4   ;coeficient D3  
201E          D4    EQU      D0+6   ;coeficient D4  
2020          YK    EQU      D0+8   ;marime de comanda y(k)  
2022          YK1   EQU      D0+10  ;marime de comanda y(k-1)  
2024          YS    EQU      D0+12  ;semn YK  
2025          YS1   EQU      D0+13  ;semn YK1  
2026          YT    EQU      D0+14  ;marime de comanda TIMER  
2028          WK    EQU      D0+16  ;marime prescrisa w(k)  
202A          W1    EQU      D0+18  ;marime prescrisa w(k-1)  
202C          RK    EQU      D0+20  ;reactie r(k)  
202E          RK1   EQU      D0+22  ;reactie r(k-1)  
2030          RK2   EQU      D0+24  ;reactie r(k-2)  
2034          BYTE  EQU      D0+28  ;octet control pentru RST 7.5  
2035          FAN   EQU      D0+29  ;fanion receptie completa DAF  
2036          ADIN  EQU      D0+30  ;adresa initiala pentru  
                ;receptie DAF  
456D          HOUT  EQU      456DH  ;subrutina OUT DAF (HEXA)  
4437          OU    EQU      4437H  ;subrutina OUT DAF (ASCII)  
                PAGE
```



```

;
;
;
                                Programul principal
ORG      8600H
LXI      SP,0      ;initializare stiva
8603'    AF        XRA      A
8604'    32 20C9   STA      20C9H  ;adresa low pentru RST 6.5
                                ;este 00
8607'    21 2020   LXI      H,2020H
860A'    06 20     MVI      B,32
860C'    77        MOV      M,A
860D'    05        DCR      B
860E'    23        INX      H
860F'    C2 8609' JNZ      8-6      ;initializari variabile
9612'    D3 02     OUT      2      ;programare port 0
8614'    D3 03     OUT      3      ;programare port 11.
8616'    3E 02     MVI      A,2
8618'    D3 0A     OUT      10     ;programare port 8
861A'    D3 08     OUT      8      ;CLEAR numarator
861C'    AF        XRA      A
861D'    D3 08     OUT      8
861F'    3E 87     MVI      A,87H
8621'    32 20CA   STA      20CAH  ;adresa high pentru RST 6.5
                                ;este 87H
8624'    21 2036   LXI      H,ADIN
8627'    22 2016   SHLD   ADAD
862A'    3E 09     MVI      A,9
862C'    30        DB      30H    ;aceasta este instructiunea SIM
862D'    C3 20B8' JMP      T

;
TT:      ORG      2050H  ;in RAM-ul static
2050'    3E 09     MVI      A,9      ;sint validate RST 6.5, RST 7.5
2052'    30        DB      30H    ;aceasta este instructiunea SI
2053'    2A 2020   LHL   YK
2056'    22 2022   SHLD   YK1    ;yk1=yk
2059'    3A 2024   LDA      YS
205C'    32 2025   STA      YS1    ;ys1=ys

;
                                preluare pozitie curenta de la numarator
205F'    DB 00     CP1:   IN      0
2061'    6F        MOV      L,A
2062'    DB 01     CP2:   IN      1
2064'    67        MOV      H,A
2065'    DB 01     IN      1
2067'    EC        CMP      H
2068'    CA 206F'  JZ      CP3
206B'    DB 01     IN      1
206D'    67        MOV      H,A
206E'    DB 00     CP3:   IN      0
2070'    BD        CMP      L
2071'    C2 205F'  JNZ      CP1
2074'    22 202C   SHLD   YK
2077'    C3 207A' JMP      PP1

;
PP1:    ORG      8900H
207A'

```

```

8900' 3A 2025          LDA    YS1
8903' B7              ORA    A
8904' 2A 2022          LHL.D YK1
8907' EB              XCHG          ;DE=yk1
8908' 06 04           MVI    B,4
890A' CA 8912'        JZ     PP2      ;salt daca ys1=0; B=4
890D' 06 08           MVI    B,8      ;ys=255; B=8
890F' CD 20AB'        CALL   ATN
8912' 7A              PP2:  MOV   A,D
8913' FE 3C           CPI    3CH
8915' FA 892F'        JM     PP3      ;salt in regimul 1
;                               Regimul 2
8918' D6 3C           SUI    3CH
891A' 67              MOV   H,A
891B' 6B              MOV   L,E
891C' 22 2026         SHLD  YT      ;yt=!yk1!-T/2
891F' 78              MOV   A,B
8920' D3 29           OUT   29H     ;comanda tranzistoare
8922' CD 8743'        CALL  SPR1     ;etapa de calcul
8925' 2A 2026         LHL.D YT
8928' 76              HLT
8929' CD 8808'        CALL  SBR2     ;etapa de comanda
892C' C3 20B8'        JMP   T
;                               Regimul 1
892F' FE 00           PP3:  CPI    0
8931' C2 893A'        JNZ   PP4
8934' 7B              MOV   A,E
8935' B7              ORA   A
8936' C2 893A'        JNZ   PP4
8939' 1C              INR   E      ;daca yk1=0, atunci DE=1
893A' EB              PP4:  XCHG
893B' 78              MOV   A,B
893C' D3 29           OUT   29H     ;comanda tranzistoare
893E' CD 8808'        CALL  SBR2     ;etapa de comanda
8941' 3E 09           MVI   A,9     ;sint validate RST 6.5,RST 7.5
8943' 30              DB    30H     ;aceasta este instructiunea SII
8944' CD 8743'        CALL  SBR1     ;etapa de calcul
8947' 76              HLT
8948' C3 20B8'        JMP   T
PAGE

```

```

;
;
;
                                Subrutina INTERRUPT DAF
                                ORG    8700H
8700'    F5                    PUSH    PSW
8701'    C5                    PUSH    B
8702'    E5                    PUSH    H
8703'    2A 2016                LHL    ADAD    ;HL=adresa curenta
8706'    3A 7000                LDA    7000H    ;A=caracter emis de DAF
8709'    CD 4336                CALL    4336H    ;conversie A(DAF) - B(ASCII)
870C'    78                    MOV    A,R
870D'    FE OD                 CPI    13
870F'    CA 8734'                JZ    ED1        ;salt daca e "RETURN"
8712'    FE 18                 CPI    24
8714'    C2 871D'                JNZ    ED2        ;salt daca nu e "CLEAR"
8717'    CD 4437                CALL    OU        ;ecou "CLEAR"
871A'    C3 872F'                JMP    ED3
871D'    FE 30                 ED2:    CPI    30H
871F'    DA 872F'                JC    ED3        ;salt daca e < '0'
8722'    FE 40                 CPI    40H
8724'    D2 872F'                JNC    ED3        ;salt daca e > '9'
8727'    CD 4437                CALL    OU        ;ecou cifra zecimala
872A'    70                    MOV    M,B        ;inscriere in sir
872B'    23                    INX    H
872C'    22 2016                SHLD    ADAD     ;ADAD = ADAD+1
872F'    E1                    ED3:    POP    H        ;final subrutina
8730'    C1                    POP    B
8731'    F1                    POP    PSW
8732'    FB                    EI
8733'    C9                    RET
8734'    3E 3D                 ED1:    MVI    A,'='
8736'    CD 4437                CALL    OU        ;ecou '='
8739'    36 00                 MVI    H,0
873B'    3E 01                 MVI    A,1
873D'    32 2035                STA    FAN        ;FAN=1
8740'    C3 872F'                JMP    ED3
                                PAGE

```

```

;
;
; Subrutina SER1 ( etapa de calcul )
;
8743' 3E BC      SER1: MVI   A,OBCH
8745' D3 2D      OUT   2DH
8747' AF         XRA   A
8748' D3 2C      OUT   2CH      ;TIMER=5msec
874A' 3E C1      MVI   A,OC1H
874C' D3 28      OUT   28H      ;start TIMER
874E' 3E 01      MVI   A,1
8750' 32 2034    STA   BYTE      ;BYTE=1

;
; ARN:
8753' 2A 2028    LHLD  WK
8756' EB         XCHG          ;DE=wk
8757' 2A 2022    LHLD  YK1      ;HL=yk1
875A' 3A 2025    LDA   YS1
875D' 4F         MOV   C,A      ;C=ys1
875E' 3A 2018    LDA   D0
8761' 47         MOV   B,A      ;B=D0
8762' AF         XRA   A        ;A=0
8763' CD 2081'   CALL  I24      ;CHL=CHL+B*ADE
8766' EB         XCHG
8767' 2A 202A    LHLD  W1
876A' EB         XCHG          ;DE=w1
876B' 3A 2019    LDA   D1
876E' 47         MOV   B,A      ;B=D1
876F' CD 207A'   CALL  I2M      ;CHL=CHL-B*ADE
8772' EB         XCHG
8773' 2A 202C    LHLD  RK
8776' EB         XCHG          ;DE=rk
8777' 3A 201B    LDA   D2+1     ;A=D2(high)
877A' B7         ORA   A
877B' CA 8782'   JZ    AR2      ;salt daca A=0
877E' 47         MOV   B,A
877F' CD 209D'   CALL  A2M      ;CHL=CHL-256*B*DE
8782' 3A 201A    AR2: LDA   D2
8785' 47         MOV   B,A      ;B=D2(low)
8786' EB         XCHG
8787' 2A 202C    LHLD  RK
878A' EB         XCHG          ;DE=rk
878B' CD 207A'   CALL  I2M      ;CHL=CHL-B*ADE
878E' EB         XCHG
878F' 2A 202E    LHLD  RK1
8792' EB         XCHG          ;DE=rk1
8793' 3A 201D    LDA   D3+1     ;A=D3(high)
8796' B7         ORA   A
8797' CA 879E'   JZ    AR3      ;salt daca A=0
879A' 47         MOV   B,A
879B' CD 20A0'   CALL  A24      ;CHL=CHL+256*B*DE
879E' 3A 201C    AR3: LDA   D3
87A1' 47         MOV   B,A      ;B=D3(low)
87A2' AF         XRA   A        ;A=0
87A3' CD 2061'   CALL  I24      ;CHL=CHL+B*ADE
87A6' EB         XCHG

```

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87A7' 2A 2030 LHL D RK2
87AA' E5 XCHG ;DE=rk2
87AB' 3A 201F LDA D4+1 ;A=D4(high)
87AE' E7 OR A
87AF' CA 87B6' JZ AR5 ;salt daca A=0
87B2' 47 AR4: MOV B,A
87B3' CD 209D' CALL A2M ;CHL=CHL-256*B*DE
87B6' 3A 201F AR5: LDA D4
87B9' 47 MOV B,A ;B=D4(low)
87BA' EB XCHG
87BB' 2A 2030 LHL D RK2
87BE' EB XCHG ;DE=rk2
87BF' CD 207A' CALL I2M ;CHL=CHL-B*ADE
; in CHL se afla rezultatul
87C2' E5 PUSH H
87C3' 2A 2028 LHL D WK
87C6' 22 202A SHLD W1 ;w1=wk
87C9' 2A 202E LHL D RK1
87CC' 22 2030 SHLD RK2 ;rk2=rk1
87CF' 2A 202C LHL D RK
87D2' 22 202E SHLD RK1 ;rk1=rk
87D5' E1 POP H
87D6' 79 MOV A,C
87D7' E7 OR A
87DS' FA 87EF' JM AR6 ;salt daca C<0
87DB' C2 87E4' JNZ AR7-3 ;salt daca C>0
87DE' 3E 77 MVI A,77H ;C=0
87E0' BC CMP H
87E1' D2 87E7' JNC AR7 ;salt daca H<=77H
87E4' 21 77F0 LXI H,77F0H ;corectie depasire superioara
87E7' 22 2020 AR7: SHLD YK ;yk=HL
87EA' AF XRA A
87EB' 32 2024 STA YS ;ys=0
87EE' C9 RET
87EF' 3C AR6: INR A
87F0' C2 87F9' JNZ AR8-3 ;salt daca C<255
87F3' 3E 87 MVI A,87H
87F5' EC CMP H
87F6' DA 87FC' JC AR8 ;salt daca H>87H
87F9' 21 8810 LXI H,8810H ;corectie depasire inferioara
87FC' 22 2020 AR8: SHLD YK ;yk=HL
87FF' 3E FF MVI A,255
8801' 32 2024 STA YS ;ys=255
8804' 3E 0B MVI A,11 ;este validata RST 7.5
8806' 30 DP 30H ;aceasta este instructiunea S
8807' C9 RET
;
;
; Subrutina SBR2 (etapa de comanda)
8808' 7C SBR2: MOV A,H
8809' E5 3F ANI 3FH ;mascare pe 14 biti
880B' C6 80 ADI 80H ;mod de lucru 2
880D' D3 2D OUT 2DH ;TIMER high
880F' 7D MOV A,L
8810' D3 2C OUT 2CH ;TIMER low
8812' AF XRA A

```


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8813'	32 2034	STA	BYTE	;BYTE=0
8816'	3E 0E	MVI	A,11	;validare RST7.5
8818'	30	DB	30H	;aceasta este instructiunea SIM
8819'	3E C1	MVI	A,0C1H	
881E'	D3 2S	OUT	2EH	;start TIMER
881D'	76	HLT		
881E'	09	RET		
		PAGE		

```

;
;                               Subrutina de inmultire pe 24 biti
;
;                               ORG   K+3   ;in RAM-ul static
207A'  CD 20AB'  I2M:  CALL   AIN     ;DE=-DE
207D'  3E 00      MVI   A,0
207F'  CE FF      ACI   255
;
;                               I24:  PUSH  H
208'   E5        MVI   L,8
2082'  2E 08      I22:  XTHL
2084'  E3        PUSH  PSW
2085'  F5        MOV   A,B
2086'  78        RAR
2087'  1F        MOV   B,A
2088'  47        JNC   I23
2089'  D2 2091'  POP   PSW
208C'  F1        DAD   D
208D'  19        PUSH  PSW
208E'  F5        ADC   C
208F'  89        MOV   C,A
2090'  4F        I23:  POP   PSW
2091'  F1        XCHG
2092'  EB        DAD   H
2093'  29        ADC   A
2094'  8F        XCHG
2095'  EB        XTHL
2096'  E3        DCR   L
2097'  2D        JNZ   I22
2098'  C2 2084'  POP   H
209B'  E1        RET
209C'  C9        ;CHL=CHL+B*ADE
;
;                               Subrutina de inmultire, prin
;                               adunari repetate, pe 24 biti
;
;                               A2M:  CALL   AIN     ;DE=-DE
;
;                               A24:  MOV   A,H
20A0'  7C        ADD   B
20A1'  83        MOV   H,A     ;H=H+B
20A2'  67        MOV   A,C
20A3'  79        ADC   D
20A4'  8A        MOV   C,A     ;C=C+D+CY
20A5'  4F
;
;                               DCR   B     ;repetata de B ori
20A6'  05        JNZ   A24     ;CHL=CHL+256*B*DDE
20A7'  C2 20A0'  RET
20AA'  C9
;
;                               Subrutina pentru complementarea DE,
;                               cu posibilitatea de complementare pe
;                               24 biti
;
;                               AIN:  MOV   A,D
20AB'  7A        CMA
20AC'  2F

```

20AD'	57	MOV	D,A	
20AE'	7B	MOV	A,E	
20AF'	2F	CMA		
20E0'	5F	MOV	E,A	
20B1'	B7	ORA	A	
20B2'	1C	INR	E	
20B3'	00	RNZ		;CY=0
20B4'	14	INR	D	
20B5'	00	RNZ		;CY=0
20B6'	37	STC		;CY=1
20B7'	09	RET		
		PAGE		

```

;
;
;
T:      ORG      SBR2+30
        LDA      FAN
        ORA      A
        JZ       TT      ;salt daca FAN=0
        XRA      A
        STA      FAN     ;FAN=0
        LXI      B,ADIN
        LXI      H,ADIN
        SHLD     ADAD
        CALL     4534H   ;conversie
                          ;(zecimal ASCII) - (hexa)

        PUSH     H
        SHLD     WK     ;wk=w(DAF)
        MOV      A,H
        CALL     HOUT   ;ecou wk (high)
        POP      H
        MOV      A,L
        CALL     HOUT   ;ecou wk (low)
        MVI      A,'H'
        CALL     OU     ;ecou caracter 'H'
        CALL     4441H  ;CR,LF
        JMP      TT

;
        END
```

Macros:

Symbols:

20A0'	A24	209D'	A2I	2016	ADAD
2036	ADIN	20AB'	AIN	877E'	AR1
8782'	AR2	879E'	AR3	87B2'	AR4
87B6'	AR5	87EF'	AR6	87E7'	AR7
87FC'	AR8	8753'	ARN	2034	BYTE
205F'	CP1	2062'	CP2	206E'	CP3
2018	DO	2019	D1	201A	D2
201C	D3	201E	D4	8734'	ED1
871D'	ED2	872F'	ED3	2035	FAN
456D	HOUT	2084'	I22	2091'	I23
2081'	I24	207A'	I2M	20D1'	IT
2077'	K	4437	OU	207A'	PP1
8912'	PP2	892F'	PP3	893A'	PP4
202C	RK	202E	RK1	2030	RK2
8743'	SBR1	8808'	SBR2	20E8'	T
8630'	TT	202A	W1	2028	WK
2020	YK	2022	YK1	2024	YS
2025	YS1	2026	YT		

No Fatal error(s)

ANEXA A4

PROGRAM DE REGLARE NUMERICA A VITEZEI PENTRU TREI
SISTEME DE ACTIONARE CU MOTOR DE CURENT CONTINUU
INDEPENDENTE COMANDATE DE UN SINGUR MICROPROCESOR
UZUAL

```
0000' 09 R;
; I PROGRAM PENTRU REGLAREA VITEZEI I
; I A 3 MOTOARE DE C.C.CU UN I
; I SINGUR MICROPROCESOR DE COMANDA I
;
;-----
;zona de date
;
000' ' DSEG
283E TABI EQU 283EH ;inceput tabel intreruperi
2852 TABC EQU 2852H ;inceput tabel calcul
2876 CCR EQU 2876H ;contor caractere receptionate
2877 NRMOT EQU 2877H ;nr.motor
2878 VITPR EQU 2878H ;viteza prescrisa
287A SVIT EQU 287AH ;sensul vitezei
287B VPRN EQU 287BH ;vector pornire
287C SEMN EQU 287CH ;variabila de legatura subr.
;in progr.de calcul
287D ADRTAB EQU 287DH ;contor adresa tabel
;intreruperi
00F6 MSKA EQU 0F6H ;masca pentru motor 1
00ED MSKE EQU 0EDH ;masca pentru motor 2
00FB MSKC EQU 0FBH ;masca pentru motor 3
287E COCC EQU 287EH ;contor intr.oprire chopper
PAGE
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```
0000" ; DSEG
;
;salt subr.intr.RST 7.5
ORG 20CEH
20CE" C3 288A" JMP ITIM
;tabel subr.numarare
ORG 2800H
2800" C3 2883" JMP NUM
ORG 2809H
2808" 04 INR B
2809" C3 2883" JMP NUM
ORG 2810H
2810" 0C INR C
2811" C3 2883" JMP NUM
ORG 2819H
2818" 04 INR B
2819" 0C INR C
281A" C3 2883" JMP NUM
ORG 2820H
2820" 14 INR D
2821" C3 2883" JMP NUM
ORG 2828H
2828" 04 INR B
2829" 14 INR D
282A" C3 2883" JMP NUM
ORG 2830H
2830" 0C INR C
2831" 14 INR D
2832" C3 2883" JMP NUM
ORG 2838H
2838" 04 INR B
2839" 0C INR C
283A" 14 INR D
283B" C3 2883" JMP NUM
;subprogram pornire
START: ORG 9000H
9000" 3E 00 MVI A,00H ;adr.subr.intr.RST 6.5
9002" 32 20C9 STA 20C9H ; low
9005" 3E 88 MVI A,88H
9007" 32 20CA STA 20CAH ; high
900A" 31 0000 LXI SP,0 ;initializare stiva
900D" 3E 0C MVI A,0CH ;programare porturi 8155
900F" D3 20 OUT 20H
9011" 21 283E LXI H,TABI;initializare tabele &
;variabile
9014" 0E 38 MVI C,56
9016" AF XRA A
9017" 77 ST1: MOV M,A
9018" 2C INR L
9019" 0D DCR C
901A" C2 9017" JNZ ST1
901D" 3E 3C MVI A,3CH
901F" 32 284F STA TABI+17
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9022" 3E 01          MVI  A,1
9024" 32 284C       STA  TABI+14
9027" 3E 03          MVI  A,3
9029" 32 2850       STA  TABI+18
902C" AF           XRA  A
902D" 32 287B       STA  VPRN
9030" 3E 4A          MVI  A,4AH
9032" 32 287D       STA  ADRTAB
9035" 3E 3C          MVI  A,3CH ;programare timer 5 ms
9037" D3 2D         OUT  2DH
9039" AF           XRA  A
903A" D3 2C         OUT  2CH
903C" 32 2876       STA  CCR
903F" C3 9047"     JMP  INI1

;program principal
9042" 3E 3E          INIT: MVI  A,3EH ;initializare ADRTAB
9044" 32 287D       STA  ADRTAB
9047" 01 0000       INI1: LXI  B,0 ;initializare contoare
904A" 11 0000       LXI  D,0
904D" 3E 0B          MVI  A,0BH ;validare intr.RST 7.5
904F" 30           DB   30H ;codul instr.SIM pentru 8085
9050" 3A 287B       LDA  VPRN
9053" D3 23         OUT  23H ;start chopper
9055" 3E C0          MVI  A,0C0H
9057" D3 28         OUT  28H ;start timer
9059" FB           EINIT: EI
905A" C3 905D"     JMP  NUMR

;subrutina numarare
905D"              NUMR: ORG  287FH
287F" 26 28         MVI  H,28H
2881" 1E 00         MVI  E,0
2883" D3 21         NUM:  IN  21H
2885" 6F           MOV  L,A
2886" AB           XRA  E
2887" 5D           MOV  E,L
2888" 6F           MOV  L,A
2889" E9           ENUMR: PCHL
PAGE

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;subr.trataare intr.RST 7.5 (timer)
288A" F5          ITIM: PUSH   PSW
288B" E5          PUSH   H
288C" 3A 287D    LDA    ADRTAB
288F" 06 04      ADI    4
2891" 6F         MOV    L,A
2892" 32 287D    STA    ADRTAB
2895" 26 28      MVI    H,28H ;(HL)=adr.(const.timer low)
                    ;ot.cuanta urmatoare

2897" 7E         MOV    A,M
2898" D3 2C      OUT    2CH ;incarcare timer
289A" 2C         INR    L
289B" 7E         MOV    A,M
289C" D3 2D      OUT    2DH
289E" 2D         DCR    L
289F" 2D         DCR    L
28A0" 2D         DCR    L ;(HL)=adr.(cod intr.)
                    ;pt.cuanta curenta

28A1" 7E         MOV    A,M
28A2" 2C         INR    L
28A3" 1F         RAR                    ;testare IOC sau ITNC
28A4" DA 28D0"   JC     ITNC
28A7" F5          IOC:  PUSH   PSW
28A8" 66         MOV    H,M ;stop chopper
28A9" DB 23      IN     23H
28AB" A4         ANA    H
28AC" D3 23      OUT    23H
28AE" F1         POP    PSW
28AF" 1F         RAR                    ;testare IOCN sau IOCC
28B0" DA 28C5"   JC     RCALC
28B3" 26 06      RNUM: MVI    H,6 ;intr.IOCN
28B5" 33         RN1:  INX    SP
28B6" 25         DCR    H
28B7" C2 28B5"  JNZ   RN1 ;6xINX SP
28BA" 3E 0B      MVI    A,0BH ;validare intr RST 7.5
28BC" 30         DB     30H ;codul instr. SIM pentru 8085
28BD" FB         EI
28BE" 3E C0      MVI    A,0C0H ;start timer
28C0" D3 28      OUT    28H
28C2" C3 905D"   JMP    NUMR
28C5" E1         RCALC: POP    H ;intr.IOCC
28C6" 3E 09      MVI    A,9 ;valid.intr.RST 6.5,RST 7.5
28C8" 30         DB     30H ;codul instr.SIM pentru 8085
28C9" 3E C0      MVI    A,0C0H ;start timer
28CB" D3 28      OUT    28H
28CD" F1         POP    PSW
28CE" FB         EI
28CF" C9         RET
28D0" 26 06      ITNC: MVI    H,6 ;intr.ITN sau ITC
28D2" 33         IT1:  INX    SP
28D3" 25         DCR    H
28D4" C2 28D2"  JNZ   IT1
28D7" 1F         RAR                    ;testare ITN sau ITC
28D8" DA 28E2"   JC     ITC

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```
28DB" 3E C0          ITN:  MVI  A,0COH ;intr.ITN
28DD"  D3 28          OUT  28H  ;start timer
28DF"  C3 88F0"      JMP  CALC
28E2"  2A 283E      ITC:  LHL  TABI  ;intr.ITC
28E5"  7D           MOV  A,L    ;incarcare timer cu const.
                ;pt.primul interval
28E6"  D3 2C           OUT  2CH  ;de temporizare din cuanta
                ;urmatoare
28E8"  7C           MOV  A,H
28E9"  D3 2D           OUT  2DH
28EB"  C3 9042"      EITIM: JMP  INIT
                PAGE
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;subr.tratare intr.RST 6.5 (DAF)
1 28EE"
8800" F5          DIAL:  ORG   8800H
8801" C5          PUSH  PSW
8802" D5          PUSH  B
8803" E5          PUSH  D
8804" 3A 7000     LDA   7000H
8807" CD 4336     CALL  4336H ;preluare caracter de la DAF
                        ;in reg.B
880A" OE 19      MVI   C,25 ;intirziere pentru dialogul
                        ;cu DAF-ul
880C" OD          DIO:  DCR   C
                        ;testare CCR
880D" C2 880C"   JNZ   DIO
8810" 3A 2876     LDA   CCR
8813" B7          ORA   A
8814" CA 882A"   JZ    DIA0
8817" 3D          DCR   A
8818" CA 8854"   JZ    DIA1
881B" 3D          DCR   A
881C" CA 8866"   JZ    DIA2
881F" 3D          DCR   A
8820" CA 8882"   JZ    DIA3
8823" 3D          DCR   A
8824" CA 8893"   JZ    DIA4
8827" C3 88DB"   JMP   DHLT
882A" 78          DIA0: MOV  A,B ;CCR=0
882B" FE 2B      CPI  '+'
882D" CA 883D"   JZ    DIO1
8830" FE 2D      CPI  '-'
8832" CA 884C"   JZ    DIO2
8835" FE 18      CPI  24 ;ecou <CLEAR>
8837" CC 88E4"   CZ   DAF
883A" C3 88DB"   JMP   DHLT
883D" CD 88E4"   DIO1: CALL DAF
8840" AF          XRA  A ;SVIT=0 pt. '+'
8841" 32 287A   DIO3: STA  SVIT
8844" 3E 01     MVI  A,1
8846" 32 2876   STA  CCR ;pune CCR=1
8849" C3 88DB"   JMP   DHLT
884C" CD 88E4"   DIO2: CALL DAF
884F" 3E 01     MVI  A,1 ;SVIT=1 pt. '-'
8851" C3 8841"   JMP   DIO3
8854" 78          DIA1: MOV  A,B ;CCR=1
8855" CD 88E4"   CALL DAF ;afisare reg.A(ASCII)
8858" CD 4565   CALL  4565H ;conversie A(ASCII) ->
                        ;A(HEXA)
885B" 32 2878   STA  VITPR ;stocare temporara cifra I
885E" 3E 02     MVI  A,2
8860" 32 2876   STA  CCR ;pune CCR=2
8863" C3 88DB"   JMP   DHLT
8866" 78          DIA2: MOV  A,B ;CCR=2
8867" CD 88E4"   CALL DAF
886A" CD 4565   CALL  4565H
886D" 47          MOV  B,A ;(B)=cifra a II-a

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886E"	3A 2878	LDA	VITPR	; (A)=cifra I
8871"	B7	ORA	A	
8872"	17	RAL		
8873"	17	RAL		
8874"	17	RAL		
8875"	17	RAL		
8876"	B0	ORA	B	; concatenare cifre
8877"	32 2878	STA	VITPR	
887A"	3E 03	MVI	A,3	
887C"	32 2876	STA	CCR	; pune CCR=3
887F"	C3 88DE"	JMP	DHLT	
8882"	78	DIA3: MOV	A,B	; CCR=3
8883"	FE 2F	CPI	'/'	; accepta numai '/'
8885"	C2 88DR"	JNZ	DHLT	
8888"	CD 88E4"	CALL	DAF	
888B"	3E 04	MVI	A,4	
888D"	32 2876	STA	CCR	; pune CCR=4
8890"	C3 88DB"	JMP	DHLT	
8893"	78	DIA4: MOV	A,B	; CCR=4
8894"	CD 4565	CALL	4565H	; conversie A(ASCII) -> ; A(HEXA)
8897"	3D	DCR	A	; verificare nr.motor = 1,2,3
8898"	FA 88DD"	JM	DHLT	
889B"	FE 03	CPI	3	
889D"	D2 88DB"	JNC	DHLT	
88A0"	3C	INR	A	; (A)=nr.motor
88A1"	F5	PUSH	PSW	
88A2"	78	MOV	A,E	
88A3"	CD 88E4"	CALL	DAF	; ecou
88A6"	CD 4441	CALL	4441H	; transmite la DAF <CR>, <LF>
88A9"	F1	POP	PSW	
88AA"	32 2877	STA	NR:MOT	
88AD"	47	MOV	B,A	
88AE"	3E 80	MVI	A,80H	; constructie masti
88B0"	07	DIA4: RLC		
88B1"	05	DCR	B	
88B2"	C2 88B0"	JNZ	DI40	
88B5"	47	MOV	B,A	; masca pornire inainte ; (de baza)
88B6"	3A 287A	LDA	SVIT	
88B9"	B7	ORA	A	; testare sens rotatie
88BA"	C2 88C6"	JNZ	DI41	
88BD"	78	MOV	A,B	; masca pornire inainte
88BE"	07	RLC		
88BF"	07	RLC		
88C0"	07	RLC		
88C1"	2F	CMA		
88C2"	4F	MOV	C,A	; masca oprire inainte
88C3"	C3 88CE"	JMP	DI42	
88C6"	78	DIA41: MOV	A,B	; masca pornire inainte
88C7"	2F	CMA		
88C8"	4F	MOV	C,A	; masca oprire inapoi
88C9"	2F	CMA		
88CA"	17	RAL		
88CB"	17	RAL		
88CC"	17	RAL		

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```

88CD"  47
88CE"  3A 287B
88D1"  A1
88D2"  B0
88D3"  32 287B
88D6"  3E 05
88D8"  32 2876
88DB"  3E 09

88DD"  30
88DE"  F1
88DF"  D1
88E0"  C1
88E1"  F1
88E2"  FB
88E3"  C9
88E4"  F5
88E5"  0E 19
88E7"  0D
88E8"  C2 88E7"
88EE"  CD 4437
88EF"  F1
88EF"  C9

DI42:  MOV      B,A      ;masca pornire inapoi
        LDA      VPRN    ;mascare vector pornire
        ANA      C
        CRA      B
        STA      VPRN
        MVI      A,5
        STA      CCR     ;pune CCR=5
DHLT:  MVI      A,9     ;validare intr. RST 6.5,
                        ;RST 7.5
                        ;codul instr.SIM pentru 8085

        DB      30H
        POP     H
        POP     D
        POP     B
        POP     PSW
        EI
        RET
DAF:   PUSH    PSW      ;subr.ecou
        MVI    C,25    ;temporizare
DAF1:  DCR     C
        JNZ   DAF1
        CALL  4437H    ;transmite la DAF A(ASCII)
        POP   PSW
        RET
PAGE

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;subrutina calcule
;**** completare tabel calcule
88F0"
905A" 3E 09
905C" 30
905D" FE
905E" C5
905F" D5
9060" 21 2852
9063" 11 2858
9066" 06 03
9068" 0E 06
906A" 7E
906B" 12
906C" 2C
906D" 1C
906E" 0D
906F" C2 906A"
9072" 7D
9073" C6 06
9075" 6F
9076" 7B
9077" C6 05
9079" 5F
907A" 05
907B" C2 9068"
907E" D1
907F" C1
9080" 78
9081" 32 2856

9084" 79
9085" 32 2862
9088" 7A
9089" 32 2864
908C" DB 22

908E" 47
908F" E6 01
9091" 32 2854
9094" 78
9095" 1F
9096" 47
9097" E6 01
9099" 32 2860
909C" 78
909D" 1F
909E" E6 01
90A0" 32 286C
90A3" 3A 2876
90A6" FE 05

90A8" C2 90C7"
90AB" AF

CALC:  ORG      EINIT+1
        MVI     A,9      ;validare intr.RST 6.5,RST 7.5
        DB      30H     ;codul instr.SIM pentru 8085
        EI
CLC1:  PUSH    B        ;actualizare variabile:y(k-1),
        PUSH    D        ; sr(k-1),sw(k-1),r(k-1),w(k-1)
        LXI     H,TABC
        LXI     D,TABC+6
        MVI     B,3      ;repetare 3x
CL11:  MVI     C,6      ;repetare 6x
CL12:  MOV     A,M
        STAX   D
        INR   L
        INR   E
        DCR   C
        JNZ   CL12
        MOV   A,L
        ADI   6
        MOV   L,A
        MOV   A,E
        ADI   6
        MOV   E,A
        DCR   B
        JNZ   CL11
        POP   D
        POP   B
        MOV   A,B
        STA   TABC+4 ;pune in tabel r(k) de la
                    ;subr. de numarare
        MOV   A,C
        STA   TABC+15
        MOV   A,D
        STA   TABC+13
        IN    22H    ;citire sensuri de rotatie
                    ;de la TIRO
        MOV   B,A
        ANI   1
        STA   TABC+2 ;pune in tabel sr(k)
        MOV   A,B
        RAR
        MOV   B,A
        ANI   1
        STA   TABC+14
        MOV   A,B
        RAR
        ANI   1
        STA   TABC+26
        LDA   CCR
        CPI   5      ;testare receptie completa
                    ;(CCR=5)
        JNZ   CLC2
        XRA   A      ;CY=0

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90AC" 3A 2877          LDA      NRMOT   ;calcul adr[sw(k)]
90AF" 17              RAL
90B0" 17              RAL
90B1" 47              MOV      B,A
90B2" 17              RAL
90B3" 80              ADD      B
90B4" 21 2849         LXI      H,TABC-9
90B7" 85              ADD      L
90B8" 6F              MOV      L,A     ;(HL)=TABC-9+12*NRMOT=
                      ;adr[sw(k)]
90B9" 3A 287A         LDA      SVIT
90BC" 77              MOV      M,A     ;pune in tabel sw(k)
90BD" 2C              INR      L
90BE" 2C              INR      L     ;(HL)=adr[w(k)]
90BF" 3A 2878         LDA      VITPR
90C2" 77              MOV      M,A     ;pune in tabel w(k)
90C3" AF              XRA      A
90C4" 32 2876         STA      CCR     ;pune CCR=0
                      ;****calcul y(k)
90C7" 21 2852         CLC2:  LXI      H,TABC
90CA" 3E 03           MVI      A,3     ;repetare de 3x calcul
90CC" F5              CL14:  PUSH     PSW
90CD" 7D              MOV      A,L
90CE" C6 06           ADI      6
90D0" 6F              MOV      L,A
90D1" 5E              MOV      E,M
90D2" 2C              INR      L
90D3" 56              MOV      D,M     ;(DE)=y(k-1)
90D4" 7D              MOV      A,L
90D5" DE 05           SBI      5
90D7" 6F              MOV      L,A     ;(HL)=adr[sr(k)]
90D8" CD 920B"        CALL     DIF     ;(A)=|w(k)-r(k)|
90DB" CD 9248"        CALL     MLT1    ;(A)=y(k-1)+/-378*|w(k)-r(k)|
90DE" 2C              INR      L
90DF" 2C              INR      L
90E0" 2C              INR      L     ;(HL)=adr[sr(k-1)]
90E1" CD 920B"        CALL     DIF     ;(A)=|w(k-1)-r(k-1)|
90E4" CD 929D"        CALL     MLT2    ;(DE)=y(k-1)+/-378*|w(k)-r(k)
                      ;-/+353*|w(k-1)-r(k-1)|
                      ;(HL)=adr[w(k-1)]
90E7" 7D              MOV      A,L
90E8" D6 0B           SUI      11
90EA" 6F              MOV      L,A     ;(HL)=adr[y(k)low]
90EB" 73              MOV      M,E     ;pune in tabel y(k)
90EC" 2C              INR      L
90ED" 72              MOV      M,D
90EE" 7D              MOV      A,L
90EF" C6 0B           ADI      11
90F1" 6F              MOV      L,A     ;(HL)=adr[y(k)] pt.motorul ur
90F2" F1              POP      PSW
90F3" 3D              DCR      A     ;contor 3x
90F4" C2 90CC"        JNZ     CL14
                      ;****compara & ordoneaza in stiva y(k)
90F7" 2A 2852         COMP:  LHLD     TABC
90FA" 44              MOV      B,H
90FB" 4D              MOV      C,L     ;y(k)pt.mot.1 -> EC
90FC" 2A 285E         LHLD     TABC+12

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90FF"  EB                XCHG                ;y(k)pt.mot.2 -> DE
9100"  2A 286A          LHLD                TABC+24 ;y(k)pt.mot.3 -> HL
9103"  7A                CMP0:  MOV            A,D
9104"  BC                CMP            H        ;ordinea in stiva va fi:
9105"  DA 9153"        JC            CMP1      ;      MSK (maxim)
9108"  C2 9110"        JNZ          CMP6      ;      y(k) maxim
910E"  7B                MOV            A,E      ;      MSK (intermediar)
910C"  BD                CMP            L        ;      y(k) intermediar
910D"  DA 9153"        JC            CMP1      ;      MSK (minim)
9110"  78                CMP6:  MOV            A,B      ;      y(k) minim
9111"  BA                CMP            D
9112"  DA 912C"        JC            CMP2
9115"  C2 911D"        JNZ          CMP7
9118"  7D                MOV            A,L
9119"  BB                CMP            E
911A"  DA 912C"        JC            CMP2
911D"  3E F6            CMP7:  MVI            A,MSKA
911F"  F5                PUSH           PSW
9120"  C5                PUSH           B
9121"  3E ED            MVI            A,MSKB
9123"  F5                PUSH           PSW
9124"  D5                PUSH           D
9125"  3E DB            MVI            A,MSKC
9127"  F5                PUSH           PSW
9128"  E5                PUSH           H
9129"  C3 9193"        JMP            CONST
912C"  3E ED            CMP2:  MVI            A,MSKB
912E"  F5                PUSH           PSW
912F"  D5                PUSH           D
9130"  78                MOV            A,B
9131"  BC                CMP            H
9132"  DA 9148"        JC            CMP4
9135"  C2 913D"        JNZ          CMP8
9138"  79                MOV            A,C
9139"  BD                CMP            L
913A"  DA 9148"        JC            CMP4
913D"  3E F6            CMP8:  MVI            A,MSKA
913F"  F5                PUSH           PSW
9140"  C5                PUSH           B
9141"  3E DB            MVI            A,MSKC
9143"  F5                PUSH           PSW
9144"  E5                PUSH           H
9145"  C3 9193"        JMP            CONST
9148"  3E DB            CMP4:  MVI            A,MSKC
914A"  F5                PUSH           PSW
914B"  E5                PUSH           H
914C"  3E F6            MVI            A,MSKA
914E"  F5                PUSH           PSW
914F"  C5                PUSH           B
9150"  C3 9193"        JMP            CONST
9153"  78                CMP1:  MOV            A,B
9154"  BC                CMP            H
9155"  DA 916F"        JC            CMP3
9158"  C2 9160"        JNZ          CMP9
915B"  79                MOV            A,C
915C"  BD                CMP            L

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915D"  DA 916F"          JC      CMP3
9160"  3E F6            CMP9:  MVI    A,MSKA
9162"  F5               PUSH   PSW
9163"  C5               PUSH   B
9164"  3E DE            MVI    A,MSKC
9166"  F5               PUSH   PSW
9167"  E5               PUSH   H
9168"  3E ED            MVI    A,MSKB
916A"  F5               PUSH   PSW
916B"  D5               PUSH   D
916C"  C3 9193"         JMP    CONST
916F"  3E DP            CMP3:  MVI    A,MSKC
9171"  F5               PUSH   PSW
9172"  E5               PUSH   H
9173"  78               MOV    A,B
9174"  BA               CMP    D
9175"  DA 918B"         JC      CMP5
9178"  C2 9180"         JNZ   CMP10
917B"  7D               MOV    A,L
917C"  BB               CMP    E
917D"  DA 918B"         JC      CMP5
9180"  3E F6            CMP10: MVI    A,MSKA
9182"  F5               PUSH   PSW
9183"  C5               PUSH   B
9184"  3E ED            MVI    A,MSKB
9186"  F5               PUSH   PSW
9187"  D5               PUSH   D
9188"  C3 9193"         JMP    CONST
918B"  3E ED            CMP5:  MVI    A,MSKB
918D"  F5               PUSH   PSW
918E"  D5               PUSH   D
918F"  3E F6            MVI    A,MSKA
9191"  F5               PUSH   PSW
9192"  C5               PUSH   B
;**** constructie tabel intreruperi
9193"  21 283E         CONST: LXI    H,TAB1
9196"  01 0000         LXI    B,0
9199"  3E 03            MVI    A,3
919B"  32 287E         STA    COCC ;COCC=3
919E"  D1              CONS1:  POP    D
919F"  D5               PUSH   D ;scoate y(k) in DE
91A0"  7A              MOV    A,D
91A1"  FE 3C            CPI    3CH ;(DE) > 3C00H ?
91A3"  D2 91BA"         JNC    CONS2
91A6"  CD 91FC"         CALL  DIPY ;calculeaza & pune in tabel d(
91A9"  C1               POP    B ;viitor Y(k)*
91AA"  36 00            MVI    M,0 ;cod I"C sau I"N
91AC"  2C              INR    L
91AD"  F1              POP    PSW
91AE"  77              MOV    M,A ;masca oprire
91AF"  2C              INR    L
91B0"  3A 287E         LDA    COCC ;COCC=COCC-1
91B3"  3D              DCR    A
91B4"  32 287E         STA    COCC
91B7"  C2 919E"         JNZ   CONS1
91BA"  11 3C00         CONS2: LXI    D,3C00H ;const.pt.T/2 = 5ms

```

```

91BD"  CD 91F0"      CALL  DIFY
91C0"  01 3C00      LXI  B,3C00H ;viitor y(k)* = 5ms
91C3"  36 01       MVI  M,1     ;cod ITN
91C5"  2C          INR  L
91C6"  2C          INR  L     ;nu se pune masca de oprire
91C7"  3A 287E     CONS3: LDA  COCC
91CA"  B7         ORA  A
91CB"  CA 91E4"     JZ   CONS4
91CE"  D1         POP  D
91CF"  D5         PUSH D     ;scoate y(k) in DE
91D0"  CD 91F0"     CALL  DIFY
91D3"  C1         POP  B     ;viitor y(k)*
91D4"  36 02      MVI  M,2     ;cod IOCC
91D6"  2C          INR  L
91D7"  F1         POP  PSW
91D8"  77         MOV  M,A     ;masca oprire
91D9"  2C          INR  L
91DA"  3A 287E     LDA  COCC   ;COCC=COCC-1
91DD"  3D         DCR  A
91DE"  32 287E     STA  COCC
91E1"  C3 91C7"     JMP  CONS3
91E4"  11 7800     CONS4: LXI  D,7800H ;const.pt.T=10ms
91E7"  CD 91F0"     CALL  DIFY
91EA"  36 03      MVI  M,3     ;cod ITC
91EC"  76         HLT
91ED"  76         HLT
91EE"  76         HLT
91EF"  76         HLT
91F0"  73         DIFY: MOV  A,E     ;subr.calcul d(k)=DE-BC
91F1"  91         SUB  C
91F2"  5F         MOV  E,A
91F3"  7A         MOV  A,D
91F4"  98         SBB  B
91F5"  57         MOV  D,A     ;DE=DE-BC
91F6"  DA 9202"     JC   DIY1   ;limitare inferioara:DE>=30
91F9"  C2 9206"     JNZ  DIY2
91FC"  7B         MOV  A,3
91FD"  FE 1E      CPI  30
91FF"  D2 9206"     JNC  DIY2
9202"  1E 1E      DIY1: MVI  E,30
9204"  16 00      MVI  D,0
9206"  73         DIY2: MOV  M,E     ;pune d(k) in tabel intr.
9207"  2C          INR  L
9208"  72         MOV  M,D
9209"  2C          INR  L
920A"  C9         RET
PAGE

```

```

; subroutine matematica
;**** scadere 1 octet (modul+semm)
920B" AF DIF: XRA A
920C" 32 287C STA SEMN
920F" 46 MOV B,M ;(B)=sr
9210" 23 INX H
9211" 7E MOV A,M ;(A)=sw
9212" A8 XRA B
9213" C2 9230" JNZ DIF2
9215" B0 ORA B ;acelasi semm
9217" 23 INX H ;w,r >0
9218" 46 MOV B,M
9219" 23 INX H
921A" 7E MOV A,M
921B" C2 922A" JNZ DIF3
921E" 90 SUB B ;(A)=|w|-|r|
921F" D0 DIF4: RNC
9220" 2F CMA
9221" 3C INR A
9222" 47 MOV B,A
9223" 3E 01 MVI A,1
9225" 32 237C STA SEMN
9228" 78 MOV A,B
9229" C9 RET
922A" 4F DIF3: MOV C,A ;w,r <0
922B" 78 MOV A,B
922C" 91 SUB C ;(A)=|r|-|w|
922D" C3 921F" JMP DIF4
9230" A8 DIF2: XRA B ;semne diferite
9231" 23 INX H
9232" 46 MOV B,M
9233" 23 INX H
9234" 7E MOV A,M
9235" C2 923D" JNZ DIF5
9238" 80 ADD B ;w>0,r<0 (A)=|r|+|w|
9239" D0 DIF6: RNC
923A" 3E FF MVI A,255 ;corectie
923C" C9 RET
923D" 80 DIF5: ADD B ;w<0,r>0
923E" 47 MOV B,A
923F" 3E 01 MVI A,1
9241" 32 287C STA SEMN
9244" 78 MOV A,B
9245" C3 9239" JMP DIF6
;****(DE)=(DE)+/-378*(A)
9248" D5 MLT1: PUSH D
9249" 47 MOV B,A
924A" 57 MOV D,A
924B" B7 ORA A
924C" 1F RAR
924D" 5F MOV E,A
924E" 3E 00 MVI A,C
9250" 1F RAR
9251" 4F MOV C,A

```

```

9252" 78          MOV     A,B
9253" 83          ADD     E
9254" 47          MOV     B,A
9255" 7A          MOV     A,D
9256" B7          ORA     A
9257" 17          RAL
9258" 5F          MOV     E,A
9259" 3E 00       MVI     A,0
925B" 17          RAL
925C" 57          MOV     D,A
925D" 79          MOV     A,C
925E" 93          SUB     E
925F" 4F          MOV     C,A
9260" 78          MOV     A,E
9261" 9A          SBB     D
9262" 47          MOV     B,A
9263" 7B          MOV     A,E
9264" B7          ORA     A
9265" 17          RAL
9266" 5F          MOV     E,A
9267" 7A          MOV     A,D
9268" 17          RAL
9269" 57          MOV     D,A
926A" 79          MOV     A,C
926B" 93          SUB     E
926C" 4F          MOV     C,A
926D" 78          MOV     A,B
926E" 9A          SBB     D
926F" 47          MOV     B,A
9270" D1          POP     D          ;(BC)=378*(A)
9271" 78          MOV     A,E
9272" 17          RAL          ;test depasire la inmultire
9273" DA 928A"    JC      ML14
9276" 3A 287C    LDA     SEMN
9279" B7          ORA     A
927A" CA 9284"    JZ      ML11
927D" 79          MOV     A,C
927E" 2F          CMA
927F" 4F          MOV     C,A
9280" 78          MOV     A,B
9281" 2F          CMA
9282" 47          MOV     B,A
9283" 03          INX     B          ;(BC)=+/-378*(A)
                          ;(functie de SEMN)
9284" EB          ML11: XCHG
9285" 09          DAD     B
9286" EB          XCHG          ;(DE)=(DE)+/-378*(A)
9287" D2 9295"    JNC     ML12
928A" 3A 287C    ML14: LDA     SEMN          ;depasire la adunare
928D" B7          ORA     A
928E" CA 9299"    JZ      ML13
9291" 11 0000    LXI     D,0          ;limitare inferioara
9294" C9          RET
9295" 7A          ML12: MOV     A,D
9296" FE 77     CPI     77H
9298" D8          RC

```

```

9299" 11 7700      ML13: LXI      D,7700H ;limitare superiara
929C"  C9          RET
;**** (DE)=(DE)-(+/-353*(A))
929D"  D5          MLT2: PUSH     D
929E"  47          MOV      B,A
929F"  4F          MOV      C,A
92A0"  B7          ORA      A
92A1"  1F          RAR
92A2"  5F          MOV      E,A
92A3"  3E 00       MVI      A,0
92A5"  1F          RAR
92A6"  57          MOV      D,A
92A7"  7B          MOV      A,E
92A8"  1F          RAR
92A9"  5F          MOV      E,A
92AA"  7A          MOV      A,D
92AB"  1F          RAR
92AC"  57          MOV      D,A
92AD"  81          ADD      C
92AE"  4F          MOV      C,A
92AF"  78          MOV      A,B
92B0"  8B          ADC      E
92B1"  47          MOV      B,A
92B2"  B7          ORA      A
92B3"  7B          MOV      A,E
92B4"  1F          RAR
92B5"  5F          MOV      E,A
92B6"  7A          MOV      A,D
92B7"  1F          RAR
92B8"  81          ADD      C
92B9"  4F          MOV      C,A
92BA"  78          MOV      A,B
92BB"  8B          ADC      E
92BC"  47          MOV      B,A ;(BC)=353*(A)
92BD"  D1          POP      D
92BE"  78          MOV      A,B
92BF"  17          RAL
;test depasire inmultire
92C0"  DA 92D7"    JC      ML24
92C3"  3A 287C    LDA     SEMN
92C6"  B7          ORA     A
92C7"  C2 92D1"    JNZ    ML21
92CA"  79          MOV     A,C
92CB"  2F          CMA
92CC"  4F          MOV     C,A
92CD"  78          MOV     A,B
92CE"  2F          CMA
92CF"  47          MOV     B,A
92D0"  03          INX     B ;(BC)=-(+/-353*(A))
;functie de SEMN
92D1"  EB          ML21: XCHG
92D2"  09          DAD     B
92D3"  EB          XCHG
92D4"  D2 92E2"    JNC    ML22 ;(DE)=(DE)-(+/-353*(A))
;functie de SEMN
92D7"  3A 287C    ML24: LDA     SEMN
92DA"  B7          ORA     A

```

```
92D5" C2 92E6"           JNZ    ML23
92D8" 11 0000           LXI    D,0      ;limitare inferioara
92E1" C9                RET
92E2" 7A                ML22: MOV    A,D
92E3" FE 77            CPI    77H
92E5" D8                RC
92E6" 11 7700          ML23: LXI    D,7700H ;limitare superioara
92E9" C9                RET
                        END
```

Macros:

Symbols:

287D	ADRTAB	88F0"	CALC	2876	CCR
9068"	CL11	906A"	CL12	90CC"	CL14
905E"	CLC1	90C7"	CLC2	9103"	CMP0
9153"	CMP1	9180"	CMP10	912C"	CMP2
916F"	CMP3	9148"	CMP4	918B"	CMP5
9110"	CMP6	911D"	CMP7	913D"	CMP8
9160"	CMP9	287E	COCC	90F7"	COMP
919E"	CONS1	91BA"	CONS2	91C7"	CONS3
91E4"	CONS4	9193"	CONST	88E4"	DAF
88E7"	DAF1	88DB"	DHLT	880C"	DIO
883D"	DIO1	884C"	DIO2	8841"	DIO3
88B0"	DI40	88C6"	DI41	88CE"	DI42
882A"	DIA0	8854"	DIA1	8866"	DIA2
8882"	DIA3	8893"	DIA4	28EE"	DIAL
920B"	DIF	9230"	DIF2	922A"	DIF3
921F"	DIF4	923D"	DIF5	9239"	DIF6
91F0"	DIFY	9202"	DIY1	9206"	DIY2
9059"	EINIT	28EB"	EITIM	2889"	ENUMR
9047"	INI1	9042"	INIT	28A7"	IOC
28D2"	IT1	28E2"	ITC	288A"	ITIM
28DB"	ITN	28D0"	ITNC	9284"	ML11
9295"	ML12	9299"	ML13	928A"	ML14
92D1"	ML21	92E2"	ML22	92E6"	ML23
92D7"	ML24	9248"	MLT1	929D"	MLT2
00F6	MSKA	00ED	MSKB	00DF	MSKC
2877	NRNOT	2883"	NUM	905D"	NUMR
28C5"	RCALC	28B5"	RN1	28B3"	RNUM
287C	SEMN	9017"	ST1	283E"	START
287A	SVIT	2852	TABC	283E	TABI
2878	VITPR	287B	VPRN		

No Fatal error(s)

ANEXA A2

PROGRAMELE DE SIMULARE PE CALCULATOR A METODEI
DE REGLARE NUMERICA MODAL-ALUNECATOARE A POZITIEI
APLICATA INTR-UN SISTEM DE ACTIONARE AL MOTOR DE
CURENT CONTINUU

- A5.1. PROGRAM CU 92 DE PASI DE SIMULARE
- A5.5. PROGRAM CU 247 DE PASI DE SIMULARE

```
PROGRAM simulare
DIMENSION th(85),th1(85),s(85),u(85),v(85)
REAL k1
C
C preluare Te
C
WRITE(3,101)
101 FORMAT(1X,'T =')
READ(4,102) Te
102 FORMAT(F15.7)
C
C parametri PCE
C
Ts=325.52E-9
Ta=1.8E-3
Tm=47.0E-3
A=0.457
d=0.1028
a1=1/A
a2=Tm/A
a3=Tm*Ta/A
Alfa=Te**2/4./d
C
C coeficienti simulare PCE
C
div=8*Ta*Tm+4*Te*Tm+2*Te*Te
Beta1=(24*Ta*Tm+4*Te*Tm-2*Te*Te)/div
Beta2=(24*Ta*Tm+4*Te*Tm+2*Te*Te)/div
Beta3=(8*Ta*Tm-4*Te*Tm+2*Te*Te)/div
Beta4=(A*Te**3)/div
C
C coeficienti estimator perturbatie
C
k1=0.6
Gama1=1/(1+k1)
Gama2=k1*Gama1
C
C preluare treapta referinta
C
WRITE(3,103)
103 FORMAT(1X,'w=')
READ(4,102) w
C
C preluare perturbatie
C
WRITE(3,104)
104 FORMAT(1X,'up=')
READ(4,102) up
```

```
C
C introducere estimator perturbatii
C
      WRITE(3,105)
105  FORMAT(1X,'INTRODUCEREA ESTIMATORULUI DE PERTURBATII (C/1):')
      READ (3,106) Kpert
106  FORMAT(I2)
      WRITE(3,107)

C
C preluare tip PCE
C
107  FORMAT(1X,'TIP PCE (1/2):')
      READ(3,106) Kpce

C
C preluare tip ARMA
C
      WRITE(3,108)
108  FORMAT(1X,'TIP ARMA (1/2):')
      READ(3,106) Karma
      IF(Karma.EQ.2) GOTO 1001

C
C preluare coeficienti ARMA
C
      WRITE(3,109)
109  FORMAT(1X,'C=')
      READ(1,102) C
      GOTO 1002
1001 WRITE(3,110)
110  FORMAT(1X,'b1=')
      READ(1,102) b1
      WRITE(3,111)
111  FORMAT(1X,'b2=')
      READ(1,102) b2
1002 WRITE(3,112)
112  FORMAT(1X,'P=')
      READ(1,102) P

C
C initializari
C
      DO 10 k=1,3
         th(k)=0.
         th1(k)=0.
         u(k)=0
         v(k)=0
10  CONTINUE
      th2k=0.
      vk2t=0.
```

```

C calcolare simulare
C
      DO 11 k=3,85
        IF(Karma.EQ.2) GOTO 1003
C algoritm ARMA-1
C
      th1(k)=(th(k)-th(k-1))/Te
      v(k-1)=u(k-1)-d*(th1(k)-th1(k-1))/Te
      vk2t=Gama1*v(k-1)+Gama2*vk2t
      s(k)=C*(th(k)-w)+th1(k)
      semm=-1.
      IF(s(k).GE.0) semm=1.
      u(k)=d*(-C*th1(k)-P*semm)+up+Kpert*vk2t
      GOTO 1004
C
C algoritm ARMA-2
C
1003  th1(k)=(th(k)-th(k-1))/Te
      th2k=(th1(k)-th1(k-1))/Te
      th3k=(th2k-th2k1)/Te
      th2k1=th2k
      v(k-1)=u(k-1)-a3*th3k-a2*th2k-a1*th1(k)
      vk2t=Gama1*v(k-1)+Gama2*vk2t
      s(k)=th(k)-w+b1*th1(k)+b2*th2k
      semm=-1.
      IF(s(k).GT.0) semm=1.
      th1Dk=-b1*th2k-b2*th3k-P*semm
      th2Dk=(th1Dk-th1(k))/Te
      th3Dk=(th2Dk-th2k)/Te
      u(k)=a3*th3Dk+a2*th2Dk+a1*th1Dk+up+Kpert*vk2t
C
C limitare !u(k)!
C
1004  IF(u(k).GT.40000.0) u(k)=40000.0
      IF(u(k).LT.-40000.0) u(k)=-40000.0
      IF(Kpoe.EQ.2) GOTO 1005
C
C model PCE-1
C
      th(k+1)=2*th(k)-th(k-1)+A1 fa*(u(k)+2*u(k-1)+u(k-2))
      GOTO 1006
C
C model PCE-2
C
1005  th(k+1)=Beta1*th(k)+Beta2*th(k-1)+Beta3*th(k-2)
      th(k+1)=th(k+1)+Beta4*(u(k)+3*u(k-1)+3*u(k-2)+u(k-3))
1006  CONTINUE
11    CONTINUE
      CALL grafic(th,'THETA')
      CALL grafic(th1,'OMEGA')
      CALL grafic(s,'S ')
      CALL grafic(u,'U ')
      CALL grafic(v,'PERT.')
      END

```

```

SUBROUTINE grafic(vect,mes)
BYTE line(100),mes(5)
INTEGER tras
REAL vect(85),ymin,ymax,deltay
;
WRITE(3,114) mes
114 FORMAT(2X,5A1,1X,'TRASARE (0/1):')
READ(1,115) tras
115 FORMAT(I2)
IF(tras.NE.1) GOTO 1007
;
WRITE(2,116) mes
116 FORMAT(2X,5A1,/)
ymin=vect(1)
ymax=vect(1)
DO 12 i=3,85
IF (vect(i).LT.ymin) ymin=vect(i)
IF (vect(i).GT.ymax) ymax=vect(i)
12 CONTINUE
WRITE(2,117) ymin,ymax
117 FORMAT (12X,'MIN=',G14.6,32X,'MAX=',G14.6,/)
deltay=(ymax-ymin)/99.
DO 14 i=3,85
DO 13 j=1,100
line(j)=' '
IF((i.EQ.3).OR.(i.EQ.85)) line(j)='- '
IF((j.EQ.1).OR.(j.EQ.100)) line(j)='I'
IF(((ymin).GE.((j-1)*deltay)).AND.((-ymin).LT.(j*deltay)))
* line(j)='I'
IF(((vect(i)-ymin).GE.((j-1)*deltay))
* .AND.((vect(i)-ymin).LT.(j*deltay)))
* line(j)='*'
13 CONTINUE
WRITE(2,118) vect(i),line
118 FORMAT (1X,G10.3,1X,100A1)
14 CONTINUE
1007 RETURN
END

```

```
PROGRAM simulare
DIMENSION th(850),th1(850),s(850),u(850),v(850)
REAL k1
C
C preluare Te
C
WRITE(3,101)
101  FORMAT(1X,'Te=')
READ(1,102) Te
102  FORMAT(F15.7)
C
C parametri PCE
C
Ts=325.52E-9
Ta=.0E-3
Tm=47.0E-3
A=0.457
d=0.1028
C
C coeficienti simulare PCE
C
Alfa=Te**2/4./d
div=8*Ta*Tm+4*Te*Tm+2*Te*Te
Beta1=(24*Ta*Tm+4*Te*Tm-2*Te*Te)/div
Beta2=( 24*Ta*Tm+4*Te*Tm+2*Te*Te)/div
Beta3=(8*Ta*Tm-4*Te*Tm+2*Te*Te)/div
Beta4=(A*Te**3)/div
C
C coeficienti ARMA
C
a1=1/A
a2=Tm/A
a3=Tm*Ta/A
C
C coeficienti estimator perturbatie
C
k1=0.6
Gama1=1/(1+k1)
Gama2=k1*Gama1
C
C preluare treapta referinta
C
WRITE(3,103)
103  FORMAT(1X,'w=')
READ(1,102) w
C
C preluare perturbatie
C
WRITE(3,104)
104  FORMAT(1X,'up=')
READ(1,102) up
```

```
C
C introducere estimator perturbatii
C
WRITE(3,105)
105 FORMAT(1X,'INTRODUCEREA ESTIMATORULUI DE PERTURBATII (0/1):')
READ(3,106) Kpert
106 FORMAT(I2)
WRITE(3,107)

C
C preluare tip PCE
C
107 FORMAT(1X,'TIP PCE (1/2):')
READ(3,106) Kpce

C
C preluare tip ARMA
C
WRITE(3,108)
108 FORMAT(1X,'TIP ARMA (1/2):')
READ(3,106) Karma
IF(Karma.EQ.2) GOTO 1001

C
C preluare coeficienti ARMA
C
WRITE(3,109)
109 FORMAT(1X,'C=')
READ(1,102) C
GOTO 1002
1001 WRITE(3,110)
110 FORMAT(1X,'b1=')
READ(1,102) b1
WRITE(3,111)
111 FORMAT(1X,'b2=')
READ(1,102) b2
1002 WRITE(3,112)
112 FORMAT(1X,'p=')
READ(1,102) P

G
C initializari
C
DO 10 k=1,3
th(k)=0.
th(k)=0.
u(k)=0
v(k)=C
10 CONTINUE
th2k=0.
vk2t=0.
```

```

C calcule simulare
C
      DO 11 k=3,850
      IF(Karma.EQ.2) GOTO 1003
C
C algoritm ARMA-1
C
      th1(k)=(th(k)-th(k-1))/Te
      v(k-1)=u(k-1)-i*(th1(k)-th1(k-1))/Te
      vk2t=Gama1*v(k-1)+Gama2*vk2t
      s(k)=C*(th(k)-w)+th1(k)
      semn=-1.
      IF(s(k).GE.0) semn=1.
      u(k)=d*(-C*th1(k)-P*semn)+up+Kpert*vk2t
      GOTO 1004
C
C algoritm ARMA-2
C
1003   th1(k)=(th(k)-th(k-1))/Te
      th2k=(th1(k)-th1(k-1))/Te
      th3k=(th2k-th2k1)/Te
      th2k1=th2k
      v(k-1)=u(k-1)-a3*th3k-a2*th2k-a1*th1(k)
      vk2t=Gama1*v(k-1)+Gama2*vk2t
      s(k)=th(k)-w+b1*th1(k)+b2*th2k
      semn=-1.
      IF(s(k).GT.0) semn=1.
      th1Dk=-b1*th2k-b2*th3k-P*semn
      th2Dk=(th1Dk-th1(k))/Te
      th3Dk=(th2Dk-th2k)/Te
      u(k)=a3*th3Dk+a2*th2Dk+a1*th1Dk+up+Kpert*vk2t
C
C limitare !u(k)!
C
1004   IF(u(k).GT.40000.0) u(k)=40000.0
      IF(u(k).LT.-40000.0) u(k)=-40000.0
      IF(Kpce.EQ.2) GOTO 1005
C
C model PCE-1
C
      th(k+ )=2*th(k)-th(k-1)+Alfa*(u(k)+2*u(k-1)+u(k-2))
      GOTO 1006
C
C model PCE-2
C
1005   th(k+ )=Beta1*th(k)+Beta2*th(k-1)+Beta3*th(k-2)
      th(k+1)=th(k+1)+Beta4*(u(k)+3*u(k-1)+3*u(k-2)+u(k-3))
1006   CONTINUE
11    CONTINUE
      CALL grafic(th,'THETA')
      CALL grafic(th1,'OMEGA')
      CALL grafic(s,'S')
      CALL grafic(u,'U')
      CALL grafic(v,'PERT.')
      END

```



```
SUBROUTINE grafic(vect,mes)
BYTE line(100),mes(5)
INTEGER tras
REAL vect(850),ymin,ymax,deltay
C
WRITE(3,114) mes
114 FORMAT(2X,5A1,1X,'TRASARE (0/1):')
READ(1,115) tras
115 FORMAT(I2)
IF(tras.NE.1) GOTO 1007
C
WRITE(2,116) mes
116 FORMAT(2X,5A1,/)
ymin=vect(1)
ymax=vect(1)
DO 12 i=3,850
  IF (vect(i).LT.ymin) ymin=vect(i)
  IF (vect(i).GT.ymax) ymax=vect(i)
112 CONTINUE
WRITE(2,117) ymin,ymax
117 FORMAT ('2X,'MIN=',G14.6,32X,'MAX=',G14.6,/)
deltay=(ymax-ymin)/99.
DO 14 i=1,92
  DO 13 j=1,100
    line(j)=' '
    IF((i.EQ.1).OR.(i.EQ.92)) line(j)='- '
    IF((j.EQ.1).OR.(j.EQ.100)) line(j)='I'
    IF(((ymin).GE.((j-1)*deltay)).AND.((-ymin).LT.(j*deltay)))
*   line(j)='I'
    IF(((vect(10*i-7)-ymin).GE.((j-1)*deltay))
*   .AND.((vect(10*i-7)-ymin).LT.(j*deltay)))
*   line(j)='*'
13 CONTINUE
WRITE(2,118) vect(10*i-7),line
118 FORMAT ('1X,G10.3,1X,100A1)
14 CONTINUE
1007 RETURN
END
```

ANEXA A6

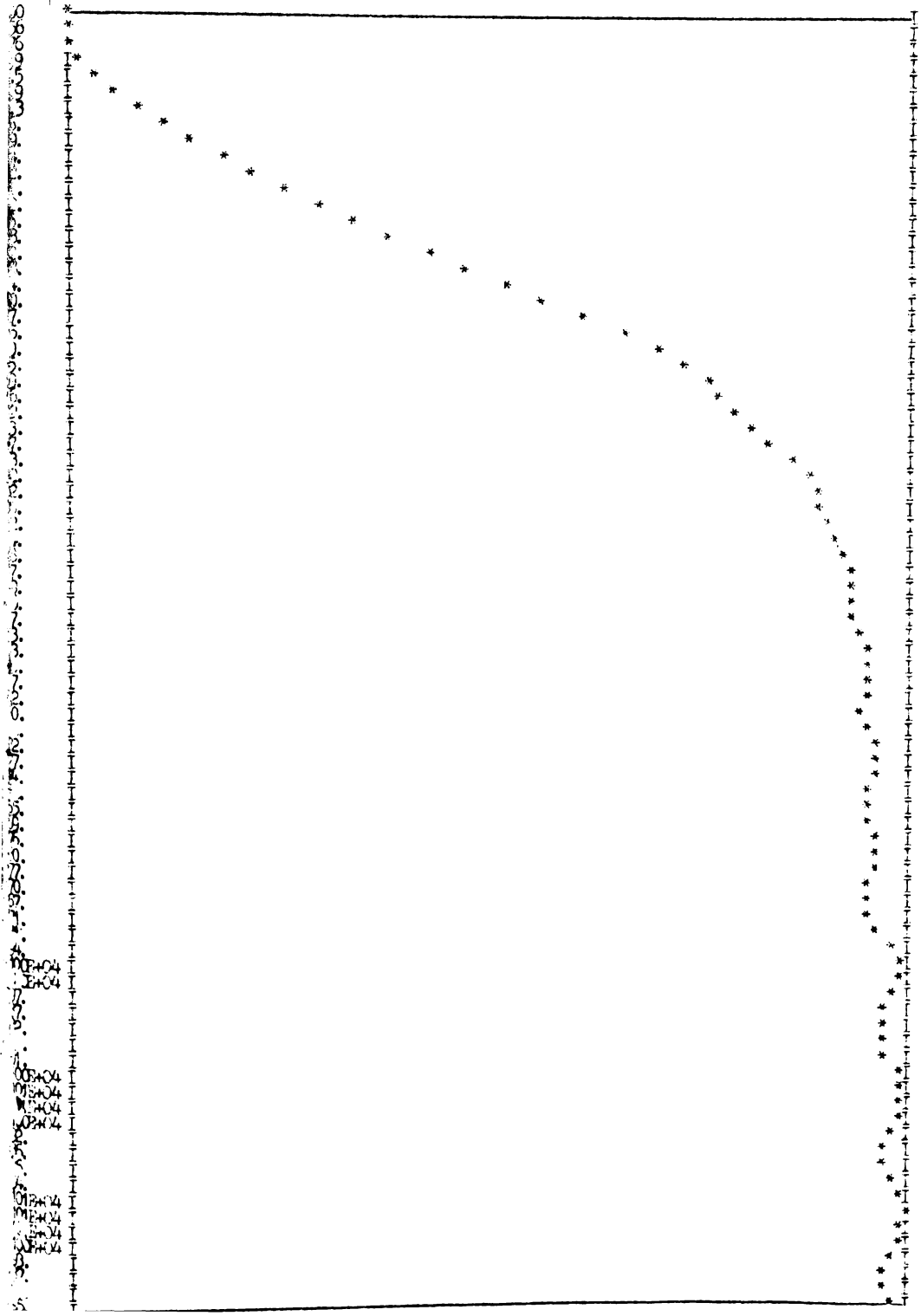
REZULTATE EXPERIMENTALE OBTINUTE PRII SIMULARE
PENTRU METODA DE REGLARE NUMERICA MODAL-ALUNECATOARE
APLICATA LA UN SISTEM DE ACTIONARE CU MOTOR DE
CURENT CONTINUU

Rezultatele programului de SIMULARE

- algoritma de reglare : tip ARMA - 1
 - fara compensarea perturbatiilor
 - fara limitarea modulului comenzii
 - C = 10
 - P = 40000
- modelul procesului condus extins : PCE - 1
- perioada de esantionare : $T_s = 12.5$ msec
- referinta de pozitie : treapta cu amplitudinea $w = 1000$
- perturbatia simulata : $u_p = 0$

ME = 0.0000

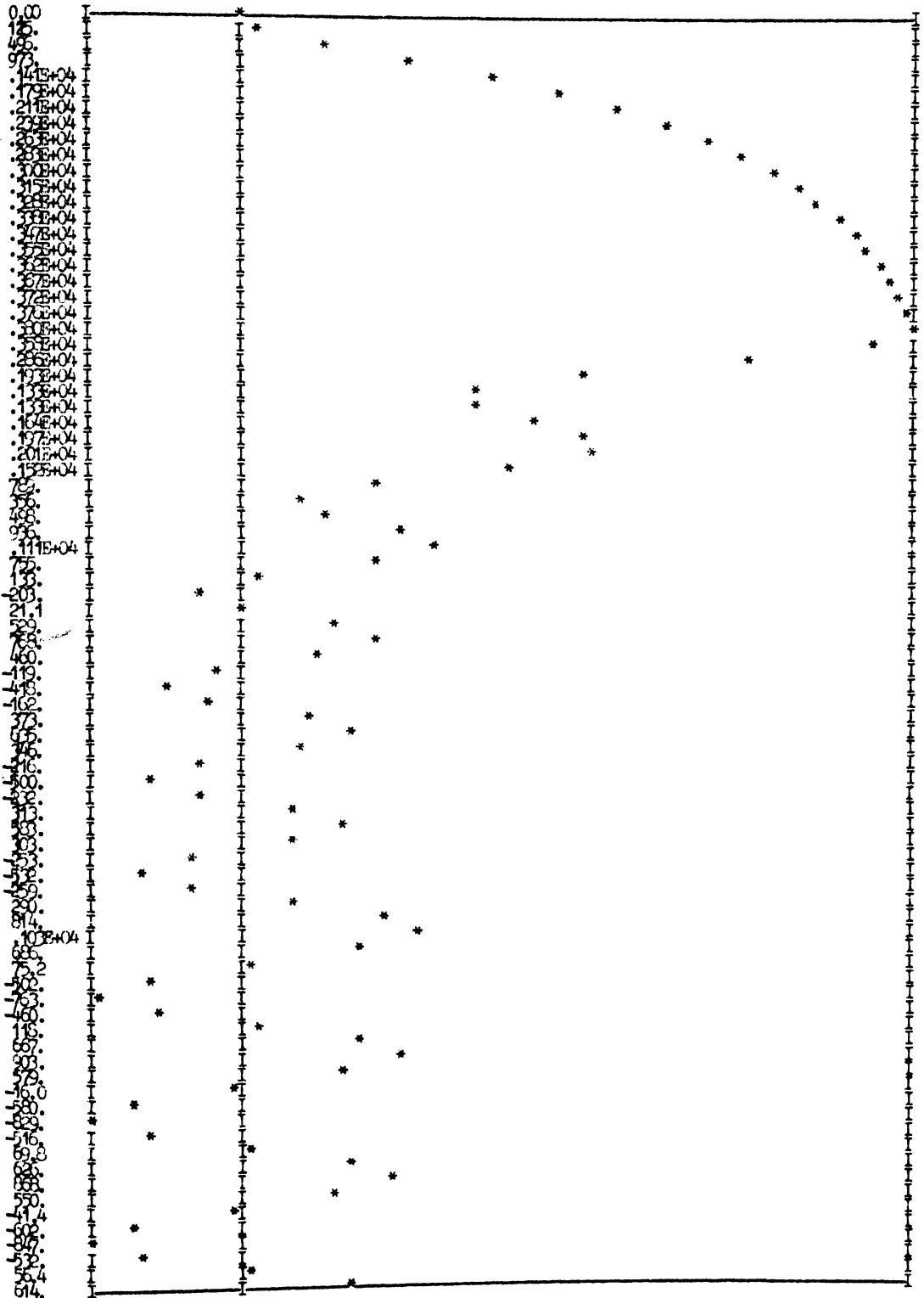
SAE = 1012.00



OMEGA

MIN= -847.358

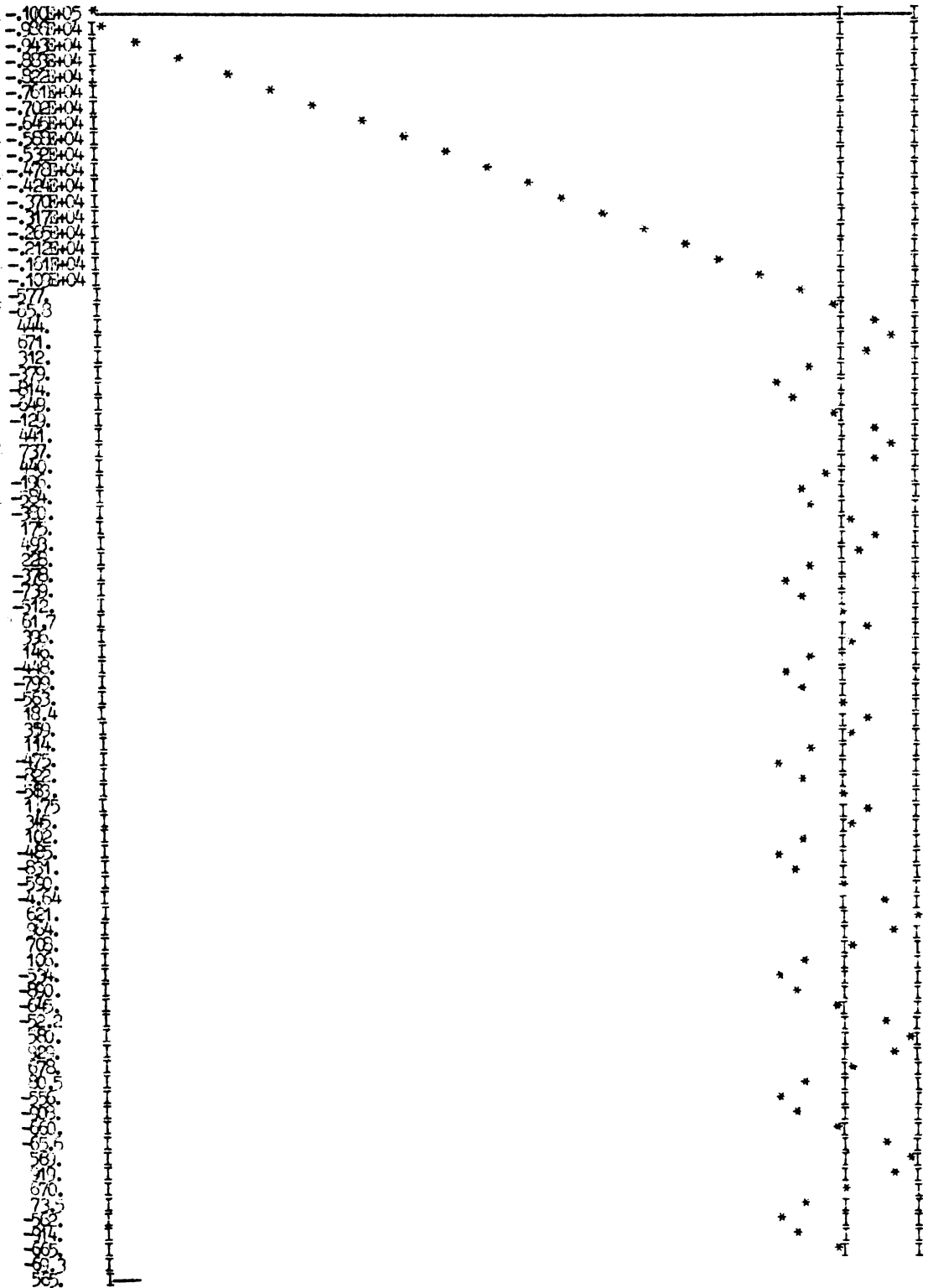
MAX= 3728.16



S

MIN= -10000.00

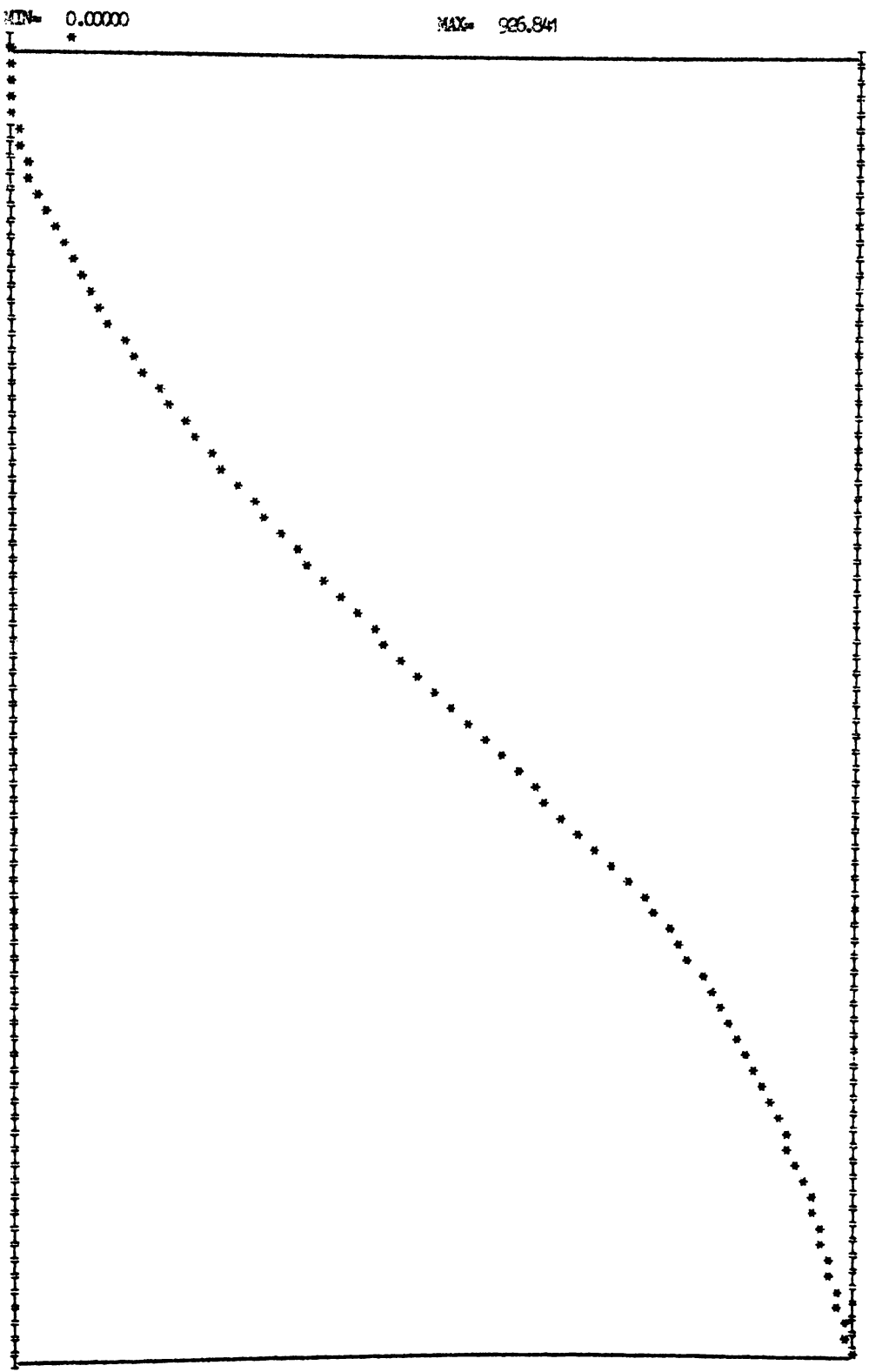
MAX= 963.940



Rezultatele programului de SIMULARE

- algoritm de reglare : tip ARMA - 1
fara compensarea perturbatiilor
fara limitarea modulului comenzii
s = 10
p = 40000
- modelul procesului condus extins : PCE - 1
- perioada de esantionare : $T_e = 5$ msec
- referinta de pozitie : treapta cu amplitudinea $w = 1000$
- perturbatia simulata : $u_p = 0$

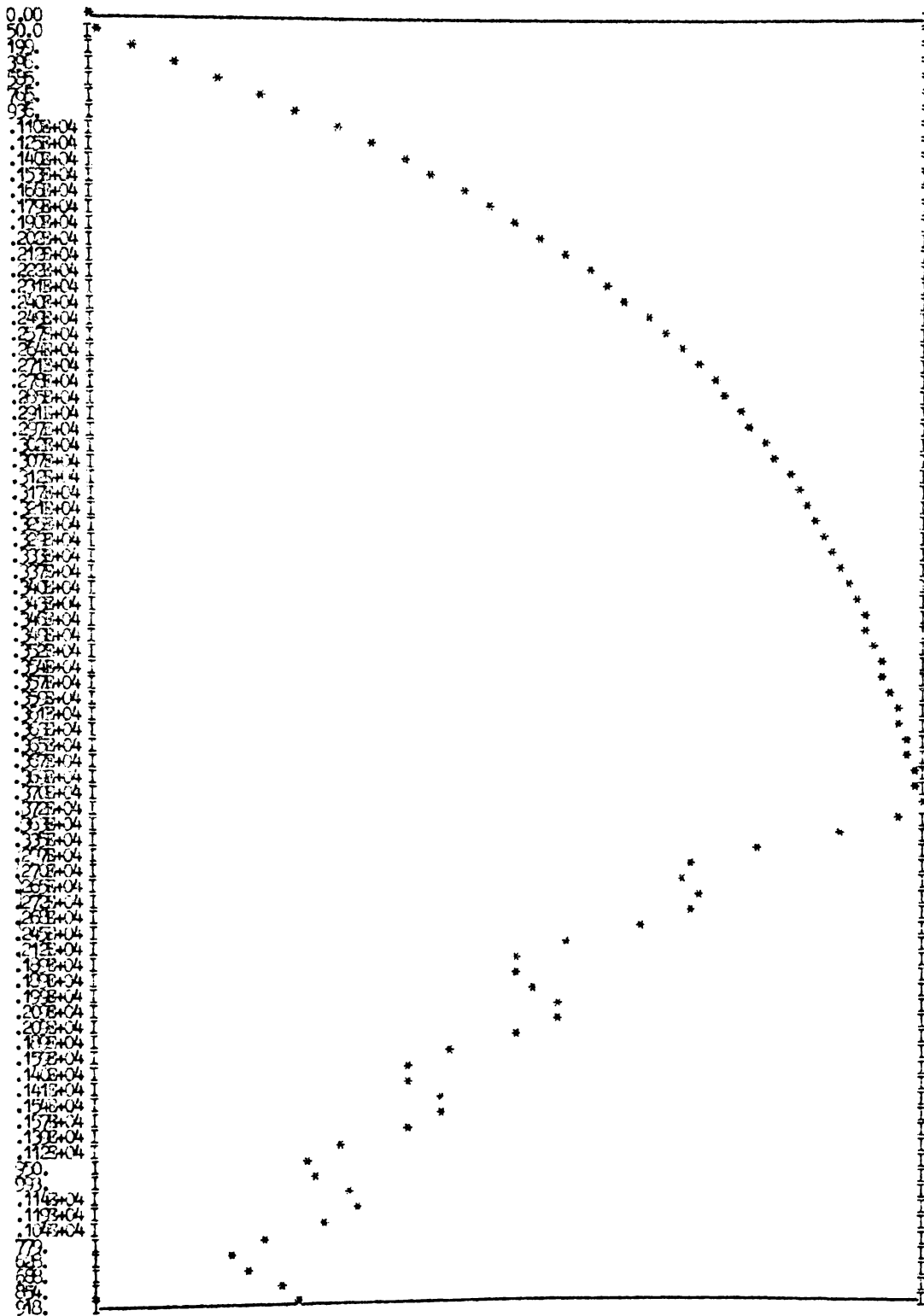
09
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19
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12
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10
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08
07
06
05
04
03
02
01
00



OMEGA

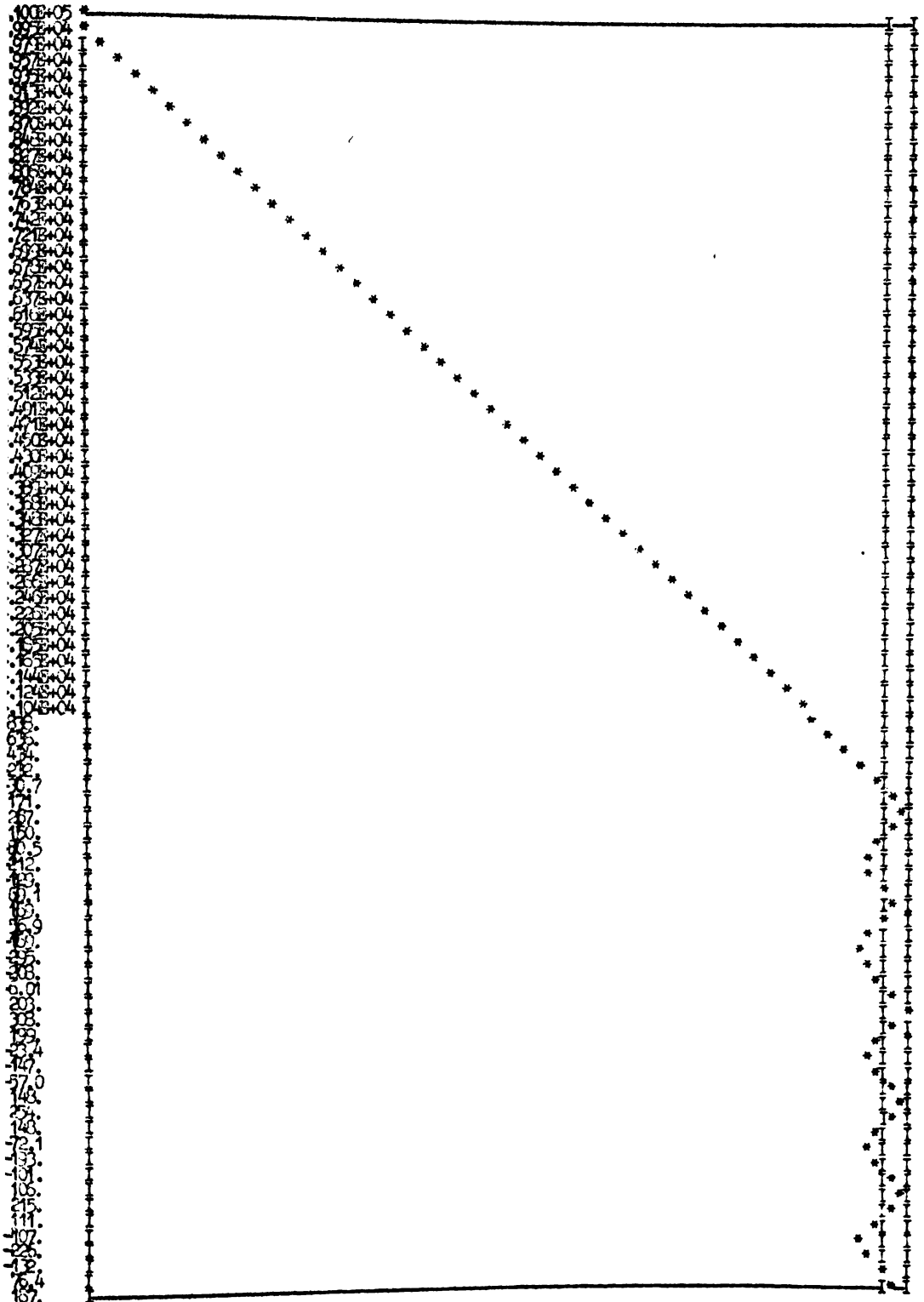
MIN= 0.0000

MAX= 3718.73



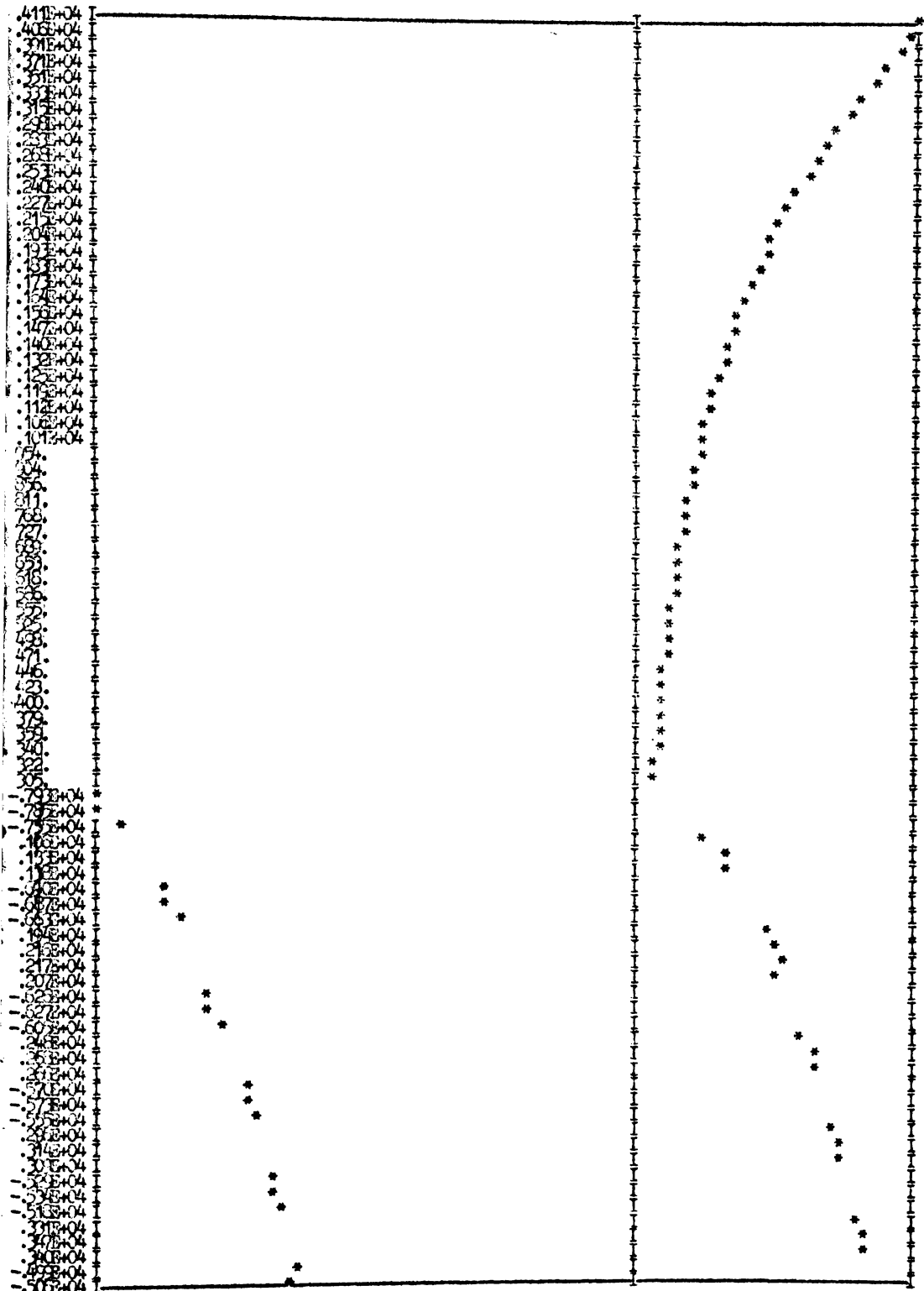
MIN= -10000.00

MAX= 308.179



MIN= -7994.85

MAX= 4112.00



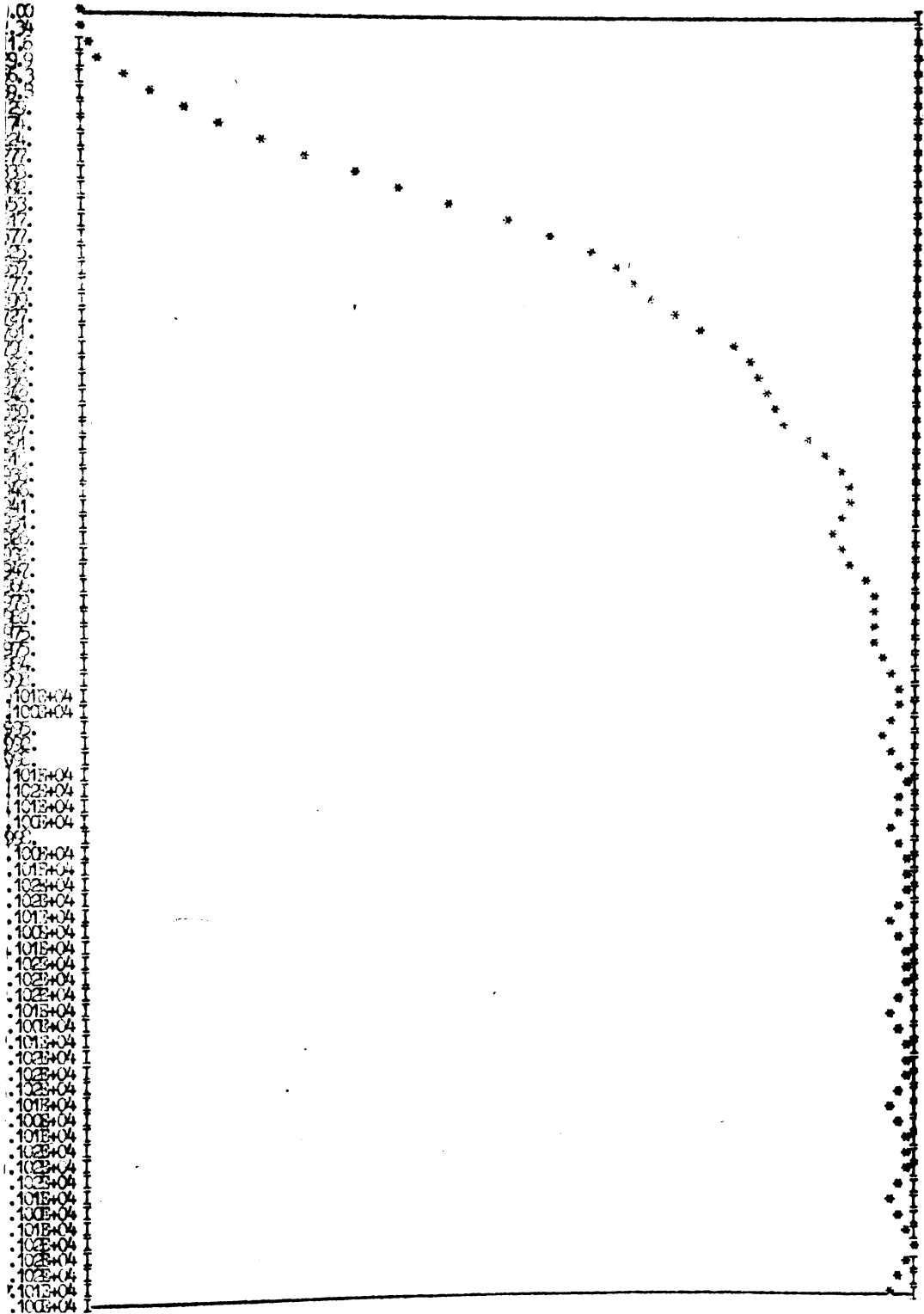
Rezultatele programului de SIMULARE

- algoritm de reglare : tip ARMA - 1
fara compensarea perturbatiilor
fara limitarea modulului comenzii
C = conform tabelului
P = conform tabelului
- modelul procesului condus extins : PCE - 1
- perioada de esantionare : $T_e = 12.5$ msec
- referinta de pozitie : treapta cu amplitudinea $w = 1000$
- perturbatia simulata : $u_p = 0$

grafic nr.	C	P	w
1	10	50000	1000
2	10	20000	1000
3	20	40000	1000
4	5	40000	1000
5	10	40000	2000
5	10	40000	500

MIN= 0.0000

MAX= 1022.79

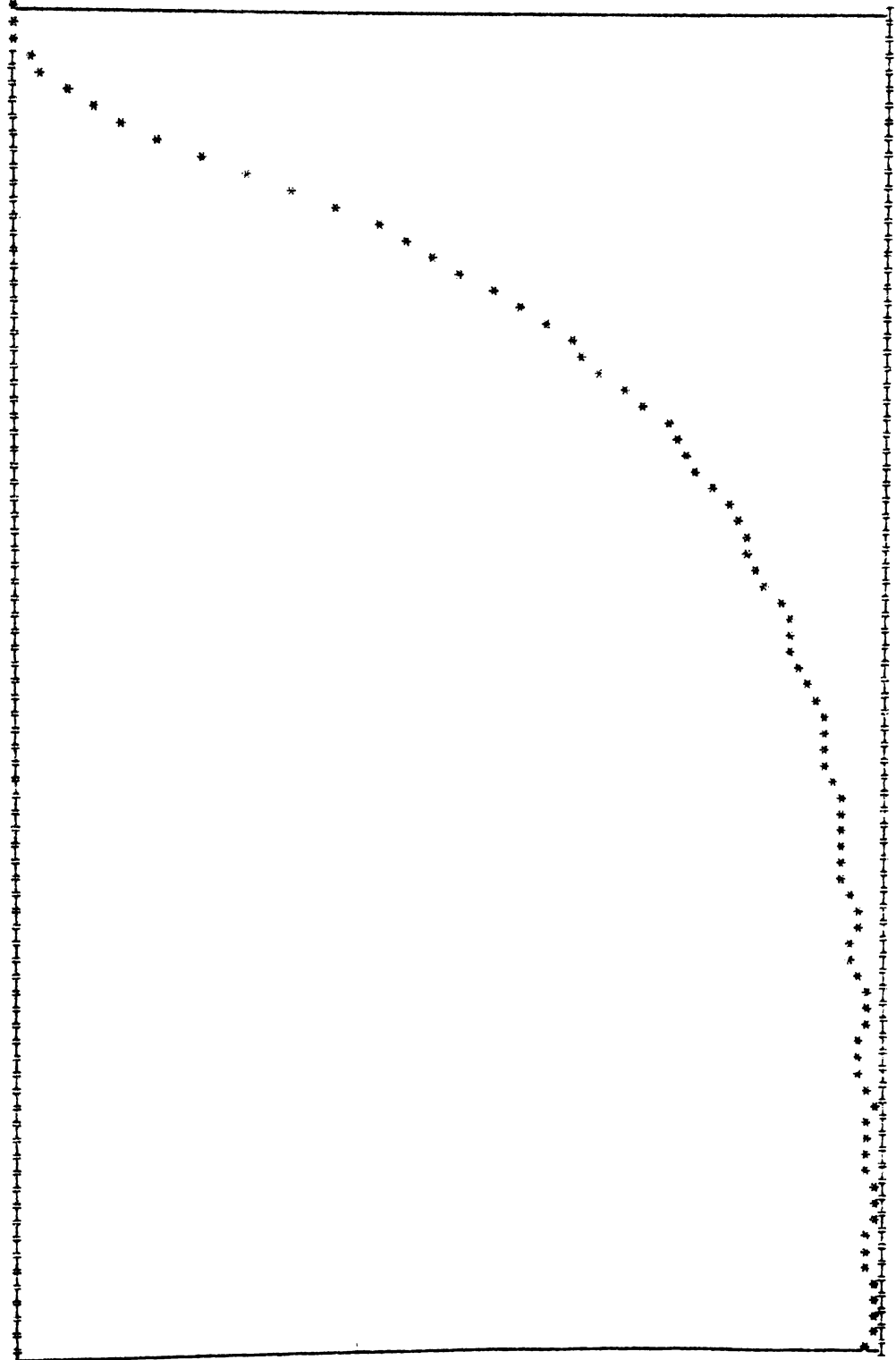


META

MIN= 0.0000

MAX= 950.804

0.1
1.1
2.1
3.1
4.1
5.1
6.1
7.1
8.1
9.1
10.1
11.1
12.1
13.1
14.1
15.1
16.1
17.1
18.1
19.1
20.1
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83.1
84.1
85.1
86.1
87.1
88.1
89.1
90.1
91.1
92.1
93.1
94.1
95.1
96.1
97.1
98.1
99.1
100.1

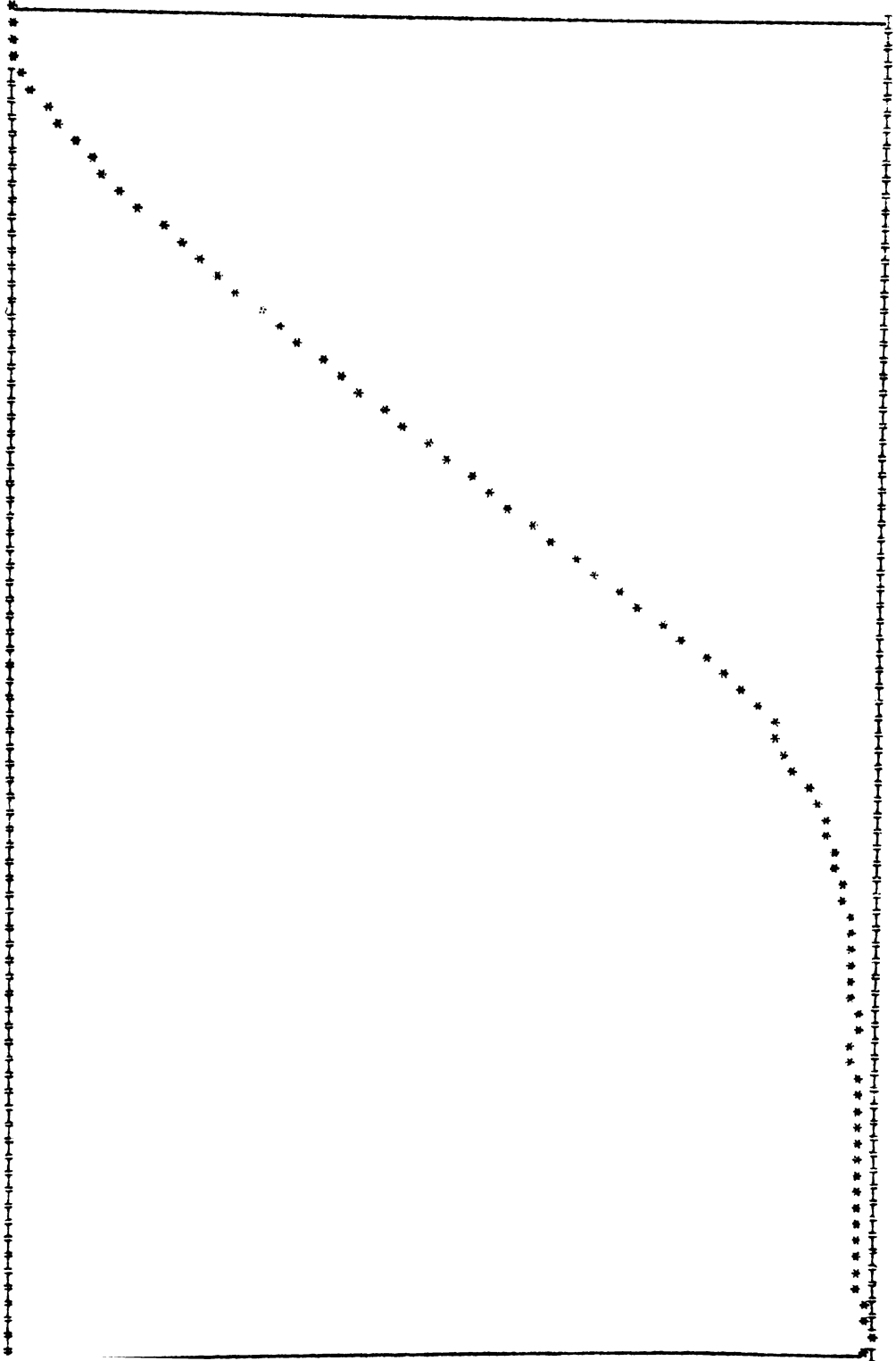


THETA

MIN= 0.0000

MAX= 2003.05

0.00
1.50
3.00
4.50
6.00
7.50
9.00
10.50
12.00
13.50
15.00
16.50
18.00
19.50
21.00
22.50
24.00
25.50
27.00
28.50
30.00
31.50
33.00
34.50
36.00
37.50
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42.00
43.50
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193.50
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196.50
198.00
199.50
2003.05

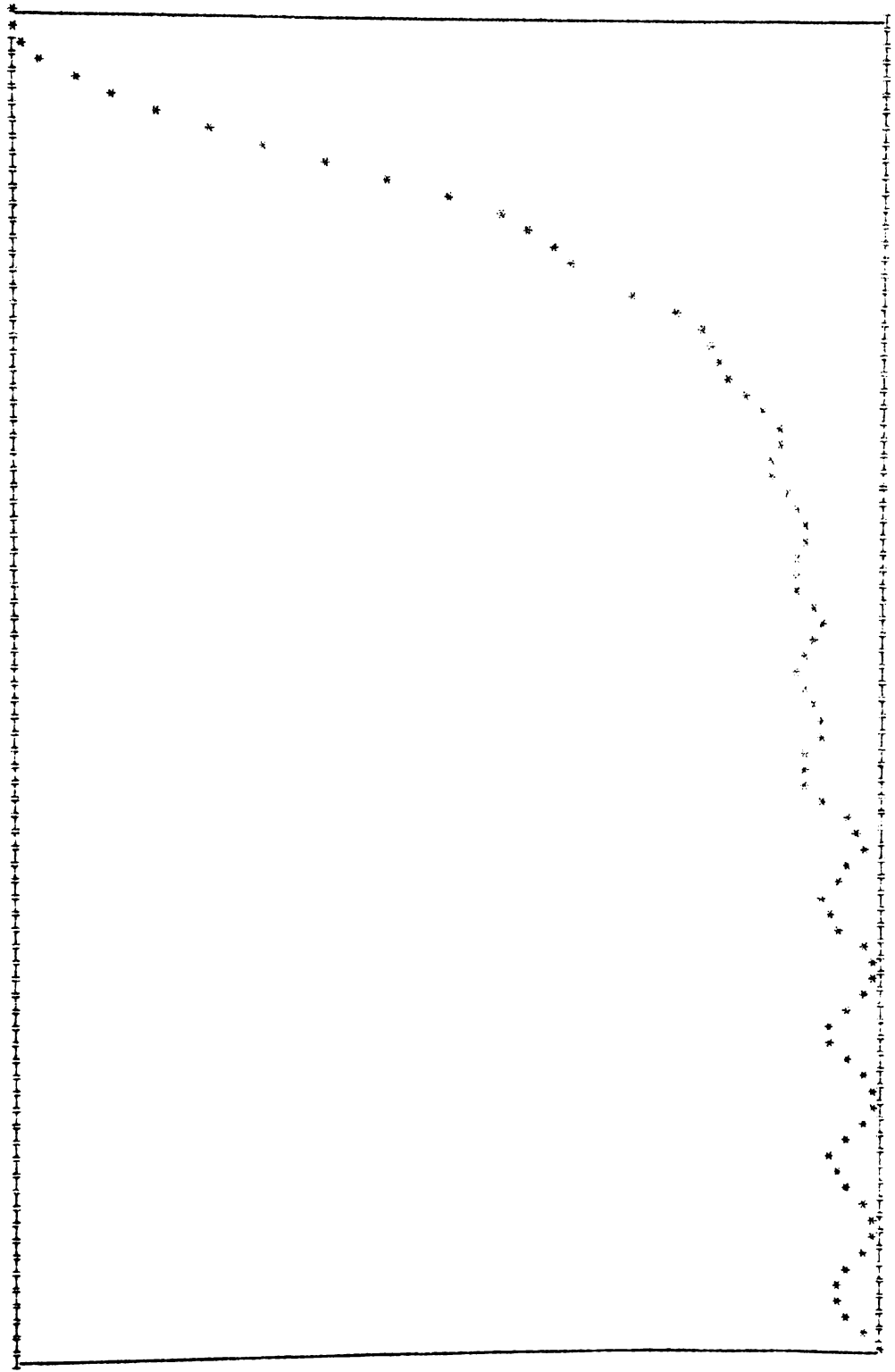


THEIA

TIME 0.0000

VAL= 512.773

0.00
1.7
1.9
2.0
2.1
2.2
2.3
2.4
2.5
2.6
2.7
2.8
2.9
3.0
3.1
3.2
3.3
3.4
3.5
3.6
3.7
3.8
3.9
4.0
4.1
4.2
4.3
4.4
4.5
4.6
4.7
4.8
4.9
5.0
5.1
5.2
5.3
5.4
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5.6
5.7
5.8
5.9
6.0
6.1
6.2
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6.4
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6.6
6.7
6.8
6.9
7.0
7.1
7.2
7.3
7.4
7.5
7.6
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7.8
7.9
8.0
8.1
8.2
8.3
8.4
8.5
8.6
8.7
8.8
8.9
9.0
9.1
9.2
9.3
9.4
9.5
9.6
9.7
9.8
9.9
10.0



Rezultatele programului de SIMULARE

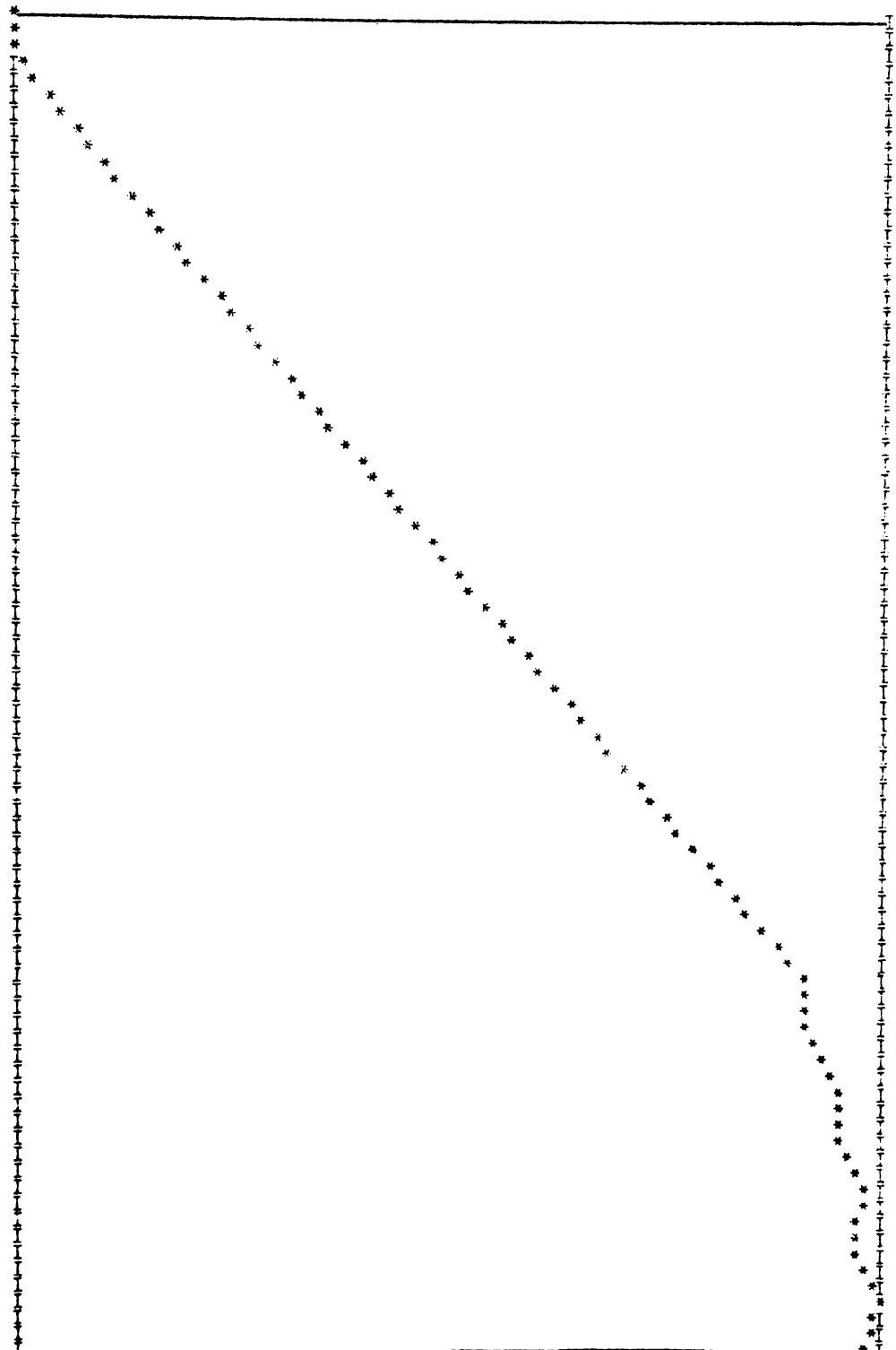
- algoritm de reglare : tip ARMA - 1
fara compensarea perturbatiilor
fara limitarea moduluii comenzii
N = 10
P = 40000
- modelul procesului condus extins : PCE - 2
- perioada de esantionare : $T_e = 12.5$ msec
- referinta de pozitie : treapta cu amplitudinea $w = 1000$
- perturbatia simulata : $u_p = 0$

TRISA

MIN= 0.0000

MAX= 097.048

0.00
 1.10
 2.10
 3.10
 4.10
 5.10
 6.10
 7.10
 8.10
 9.10
 10.00
 11.00
 12.00
 13.00
 14.00
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 97.00
 98.00
 99.00
 100.00



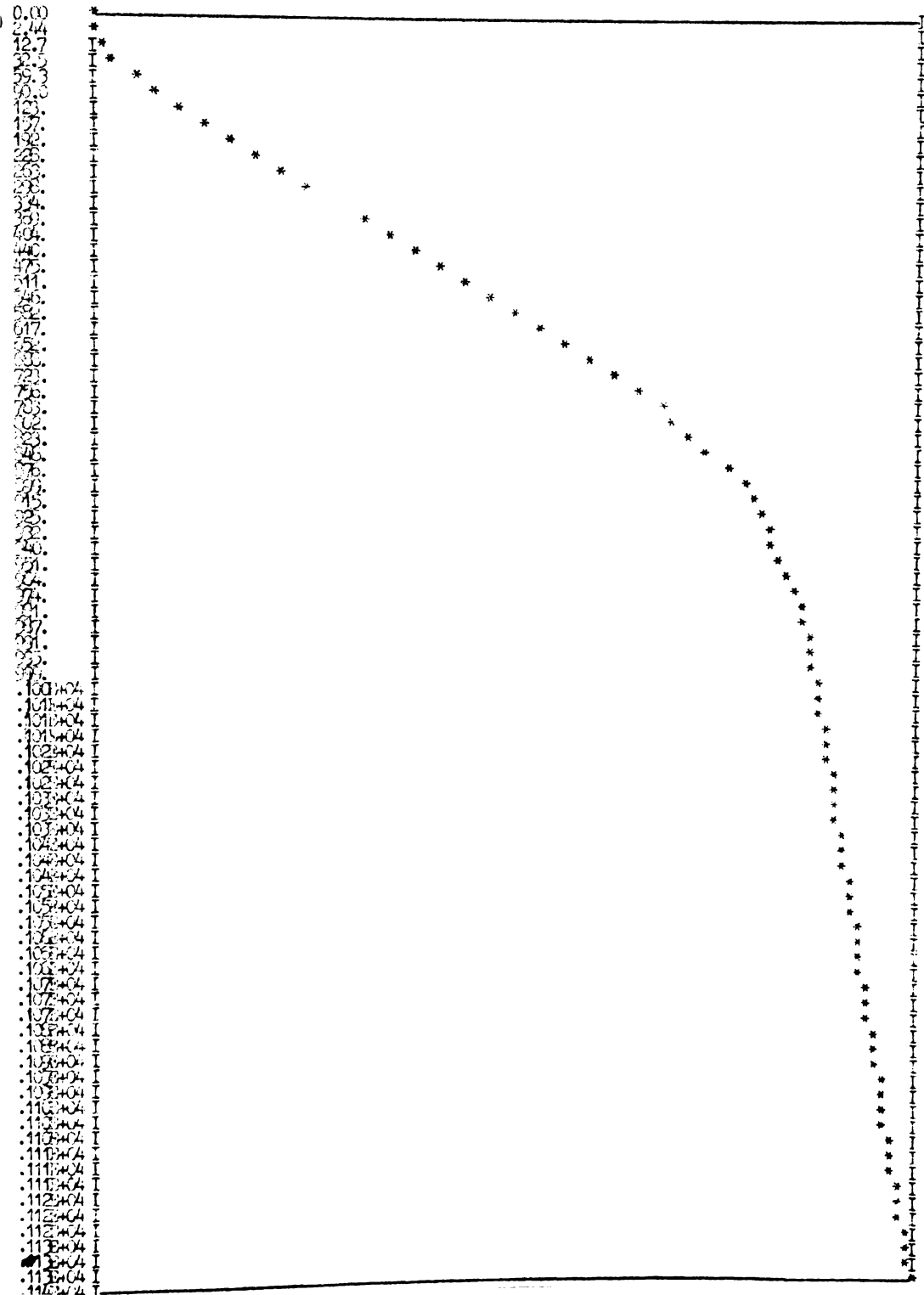
Rezultatele programului de SIMULARE

- algoritm de reglare : tip ANNA - 1
 - Sfara compensarea perturbatiilor
 - Sfara limitarea modulului comenzii
 - $\alpha = 10$
 - $\beta = 40000$
- modelul procesului cercuat extins : PCE - 2
- perioada de esantionare : $T_e = 12.5$ msec
- referinta de pozitie : treapta cu amplitudinea $w = 1000$
- perturbatia simulata : $u_p = 5000$

TESTA

MIN= 0.0000

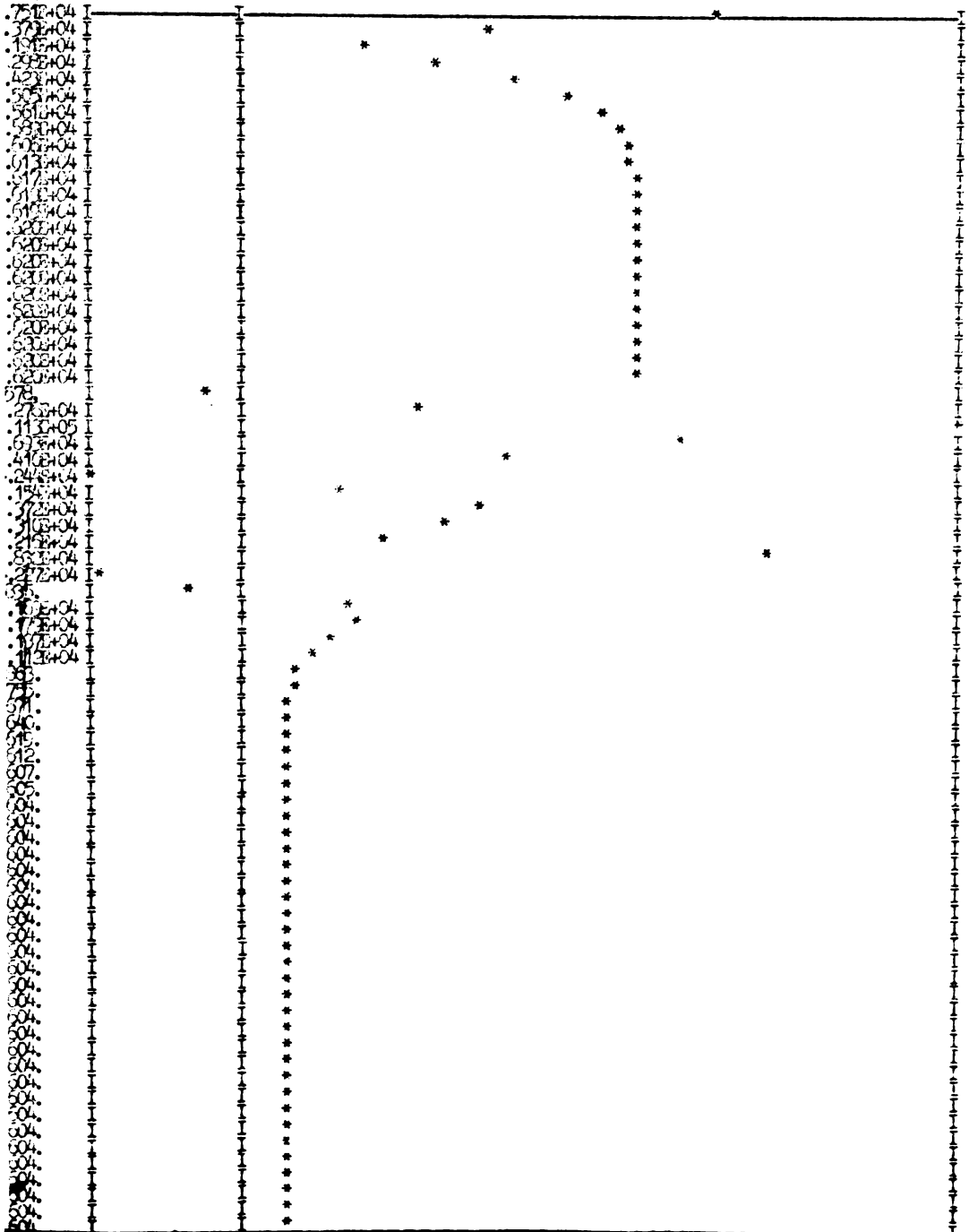
MAX= 1137.12



REF.

MIN= -2444.94

MAX= 11251.5



Rezultatele programului de SIMULARE

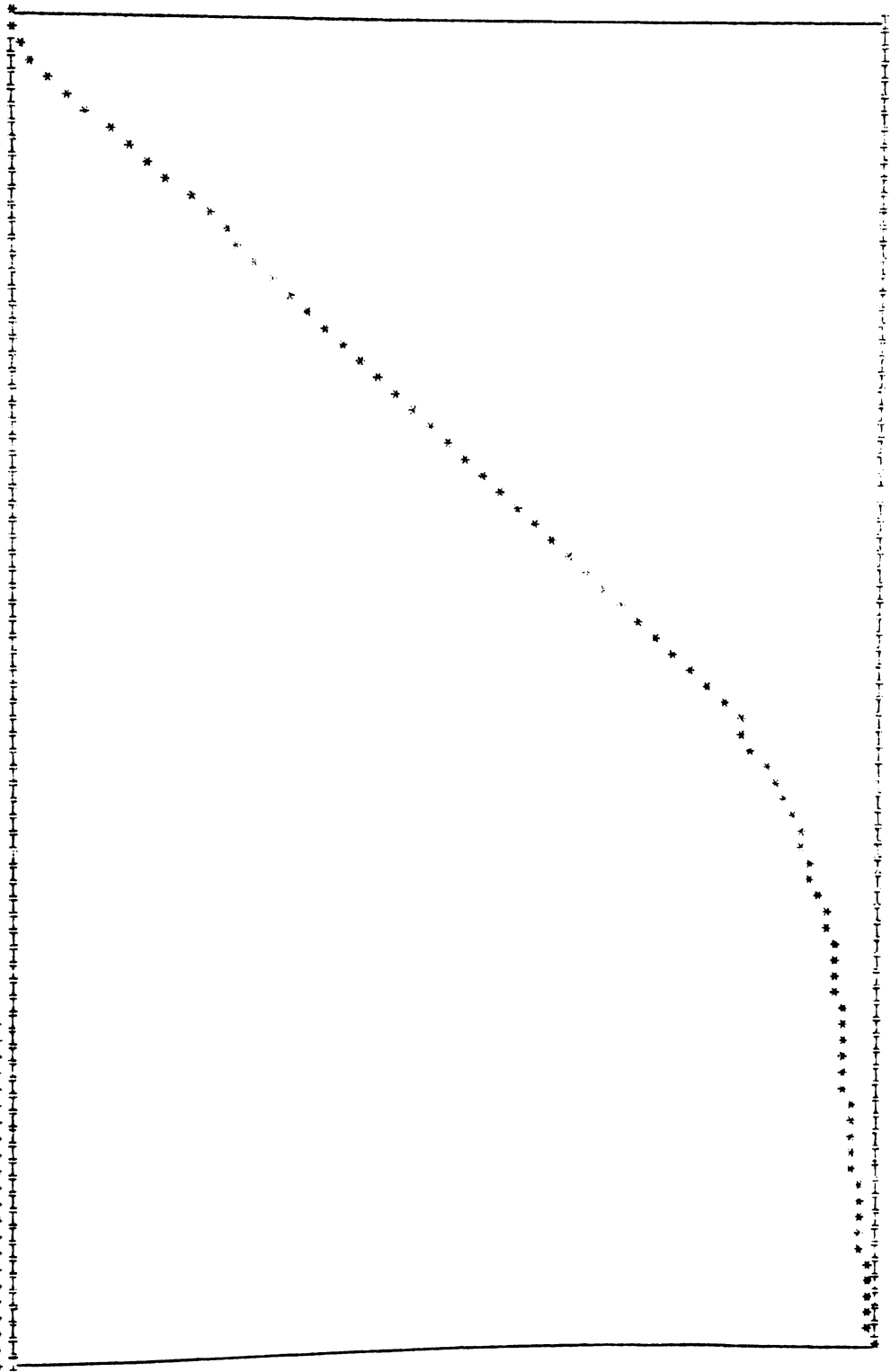
- algoritm de reglare : tip ARMA - 1
cu compensarea perturbatiilor
fara limitarea modulului comenzii
C = 10
P = 40000
- modelul procesului condus extins : PCE - 2
- perioada de esantionare : $T_e = 12.5$ msec
- referinta de pozitie : treapta cu amplitudine: $w = 1000$
- perturbatia simulata : $u_p = 5000$

THEIA

MEAN= 0.00000

MAX= 1041.17

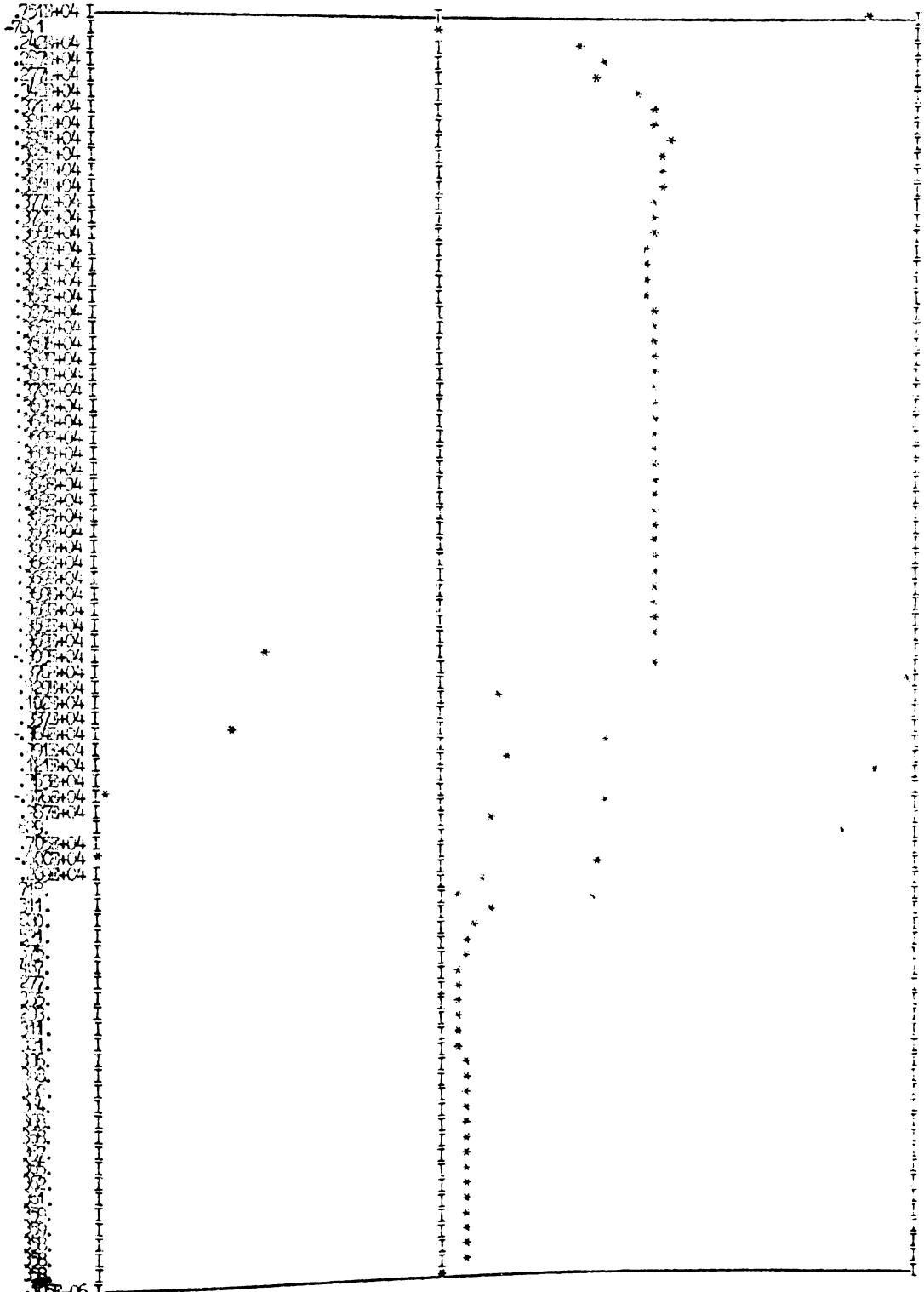
0.00
2.14
11.4
26.3
46.5
69.4
90.9
111.3
141.2
177.1
214.1
251.1
287.1
321.1
354.1
386.1
416.1
444.1
470.1
494.1
516.1
536.1
554.1
570.1
584.1
596.1
606.1
614.1
620.1
624.1
626.1
626.1
624.1
620.1
614.1
606.1
596.1
584.1
570.1
554.1
536.1
516.1
494.1
470.1
444.1
416.1
386.1
354.1
321.1
287.1
251.1
214.1
177.1
141.2
90.9
46.5
26.3
11.4
2.14
0.00
100.4
101.4
102.4
103.4
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186.4
187.4
188.4
189.4
190.4
191.4
192.4
193.4
194.4
195.4
196.4
197.4
198.4
199.4
200.4



PRPT.

MIN= -6002.07

MAX= 8205.13



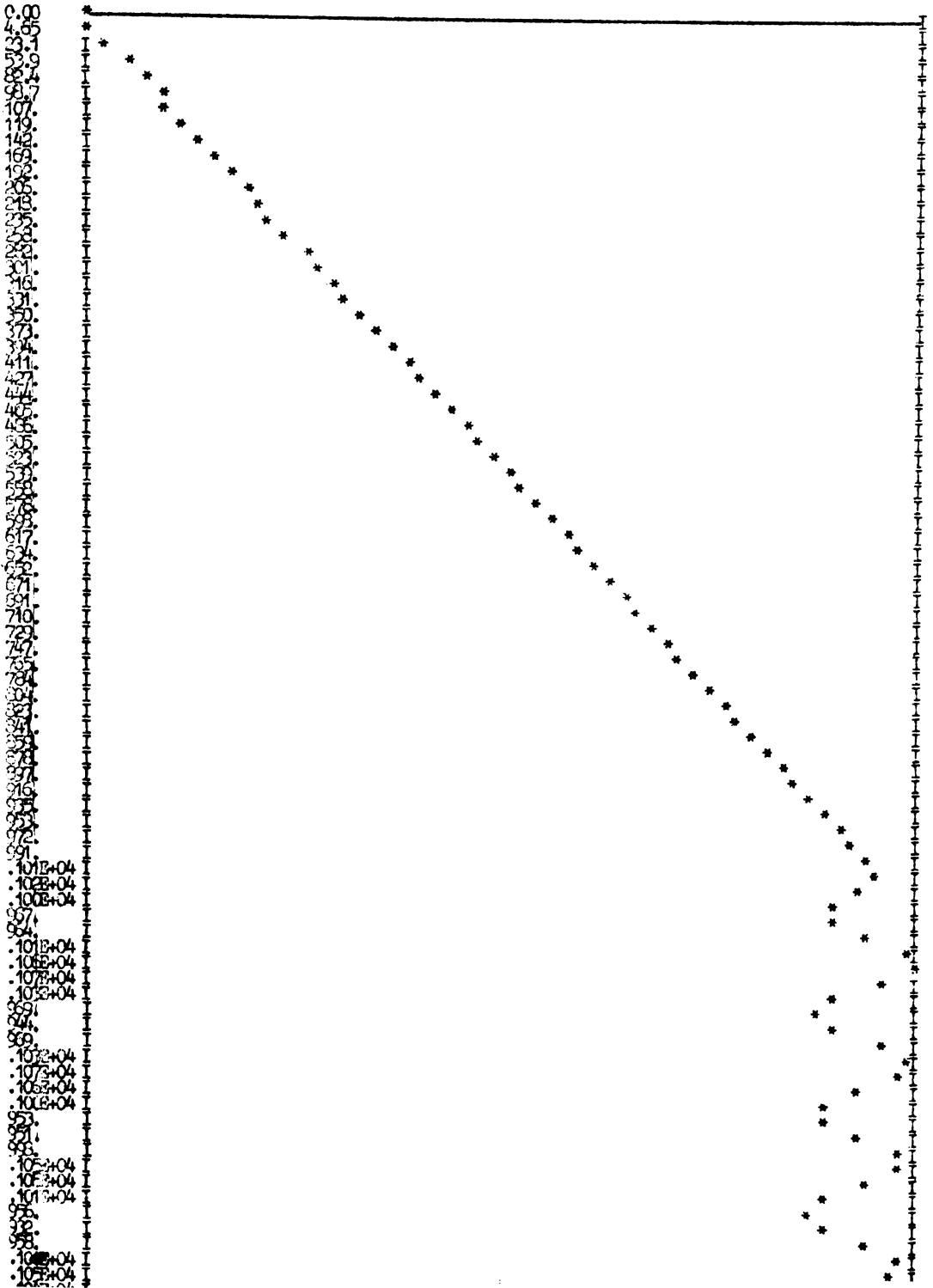
Rezultatele programului de SIMULARE

- algoritma de reglare : tip ARMA - 2
 - fara compensarea perturbatiilor
 - fara limitarea modulului comenzii
 - b1 = $7.81E-4$
 - b2 = $6.10E-7$
 - p = 1500
- modelul procesului condus extins : PCS - 2
- perioada de esantionare : $T_e = 12.5$ msec
- referinta de pozitie : treapta cu amplitudinea $w = 1000$
- perturbatia simulata : $u_p = 0$

HEA

MIN= 0.0000

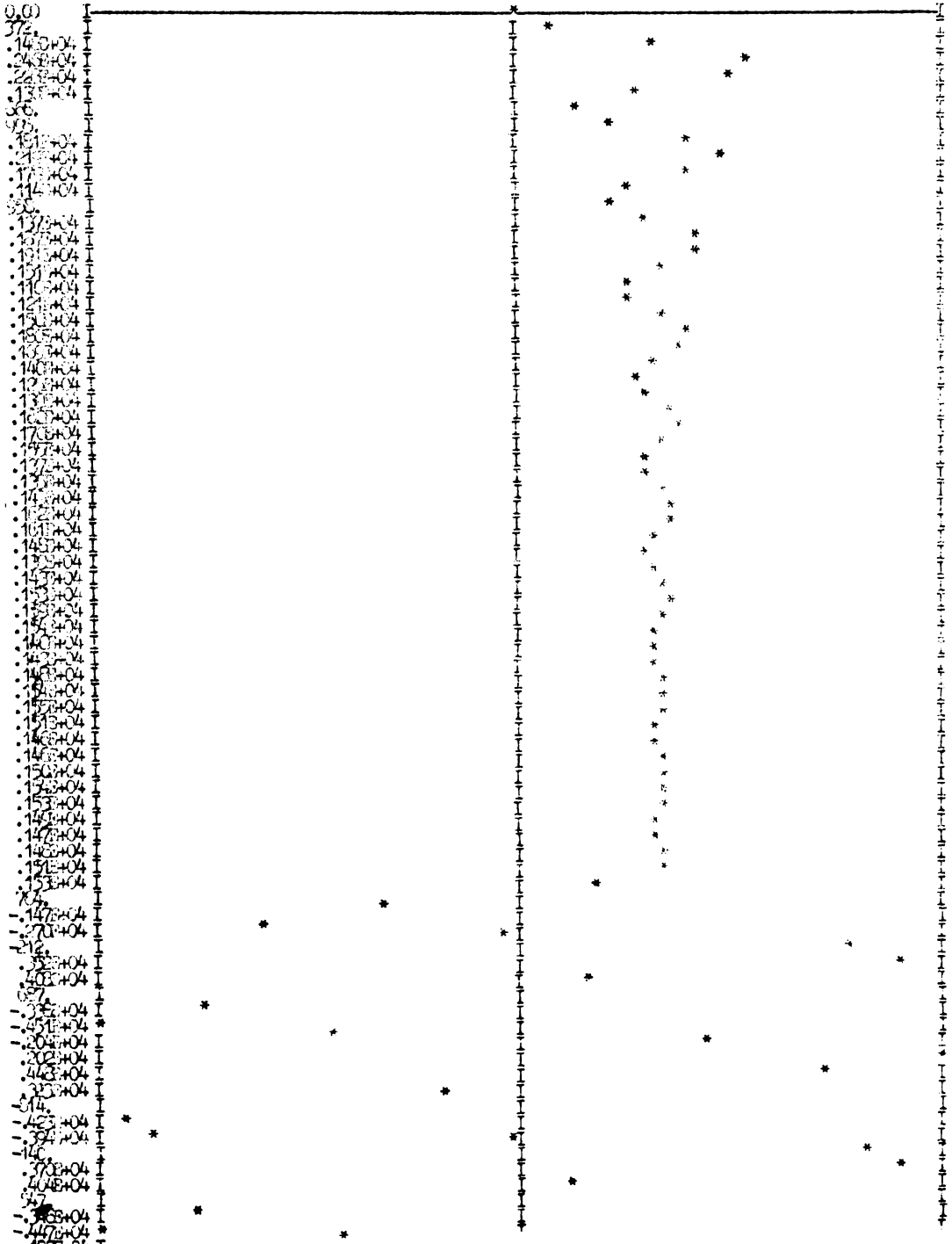
MAX= 1067.99



OMEGA

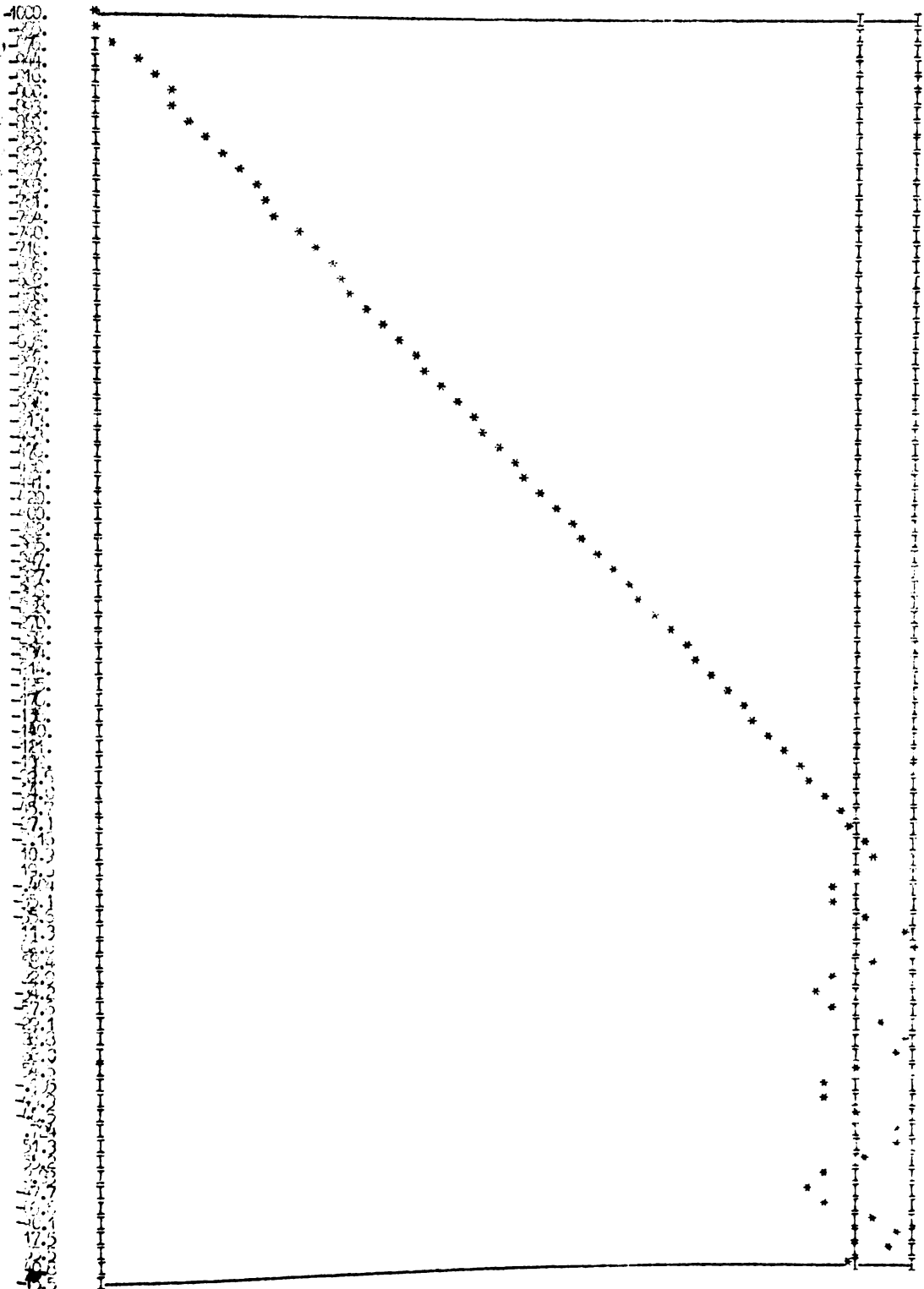
MIN = -4507.66

MAX = 4433.44



MIN = -1000.000

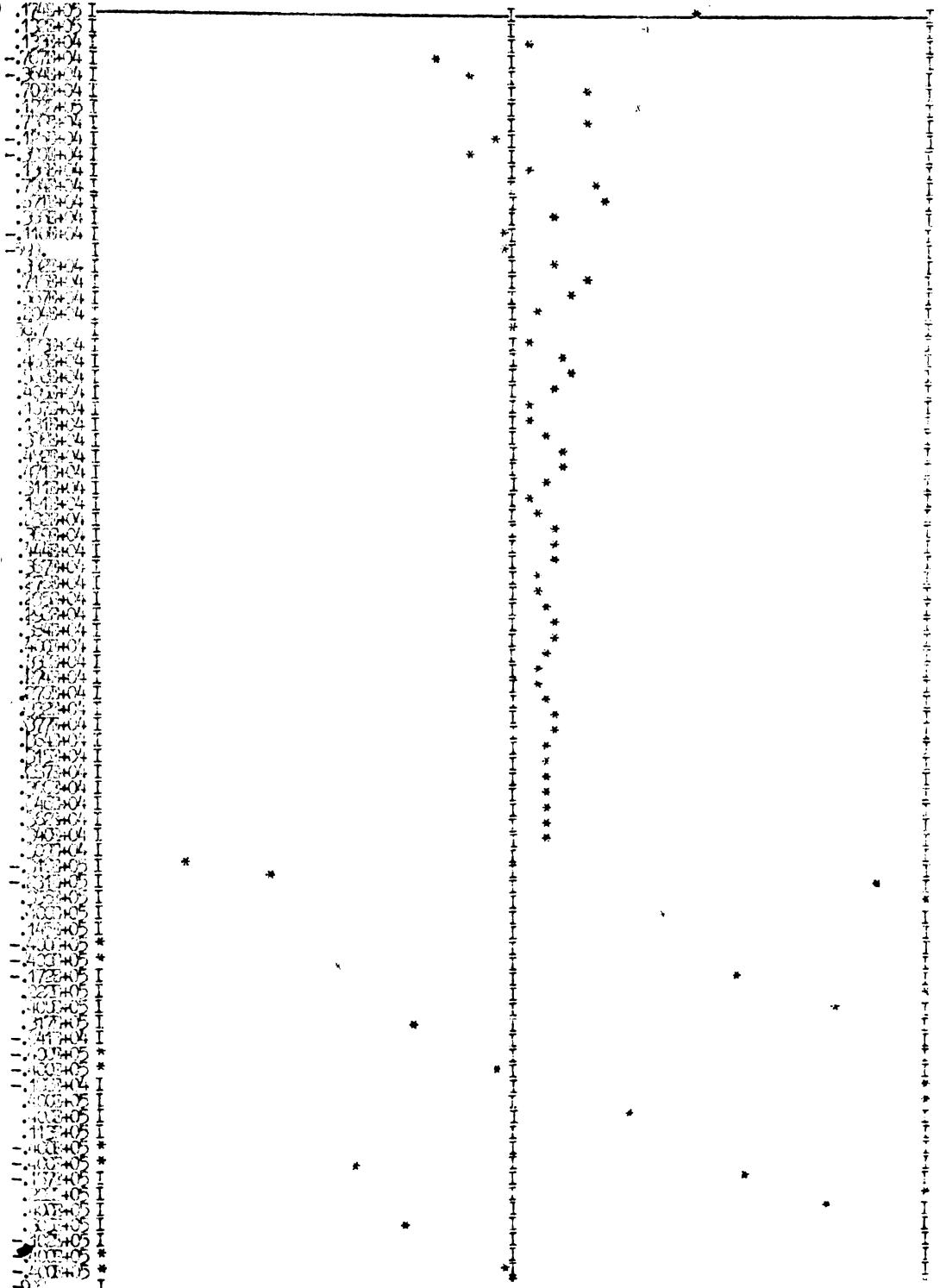
MAX = 68.393



U 1

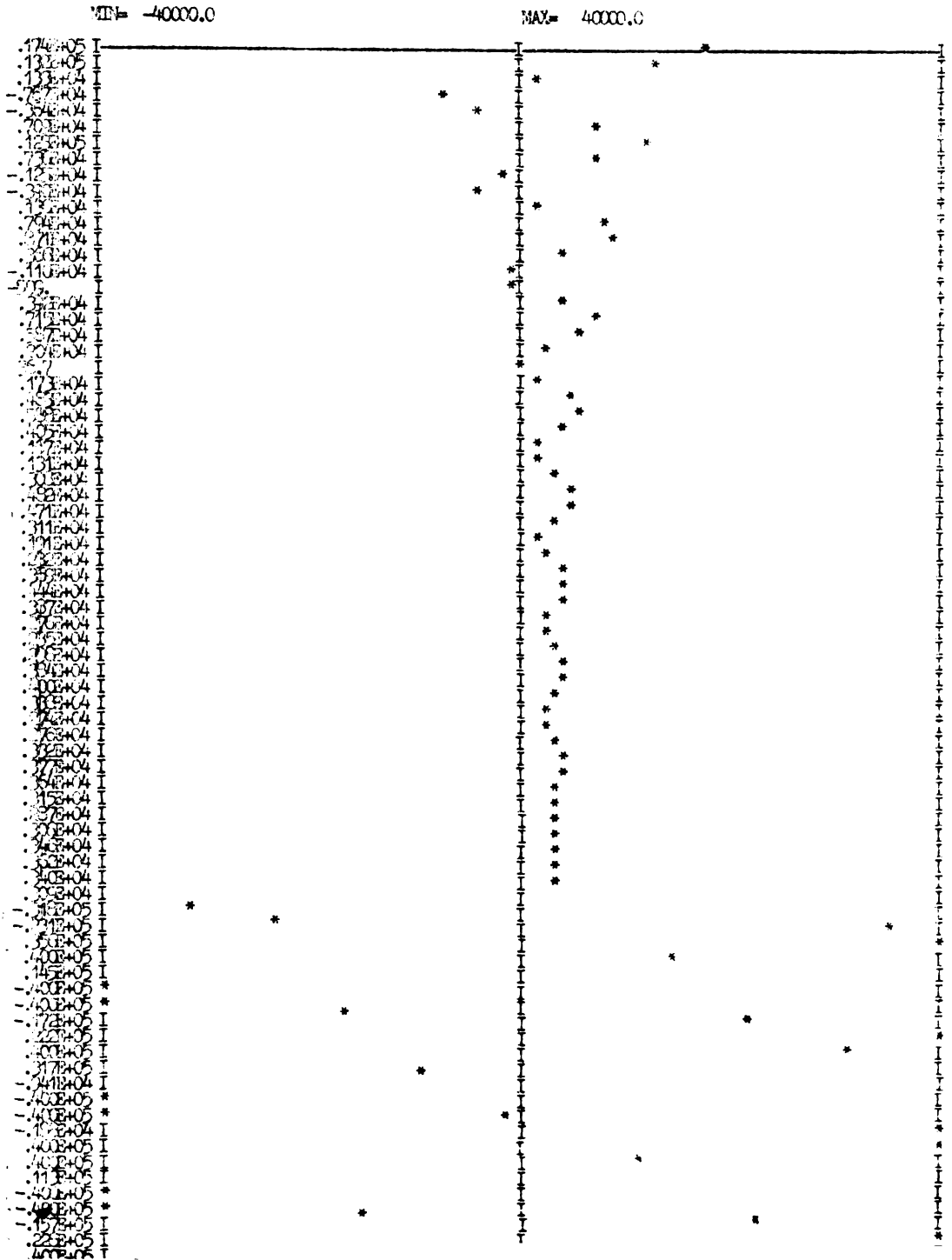
MIN= -40000.0

MAX= 40000.0



Rezultatele programului de SIMULARE

- algoritm de reglare : tip ARMA - 2
fara compensarea perturbatiilor
cu limitarea modulului cotezii
b1 = $7.81E-4$
b2 = $6.10E-7$
P = 1500
- modelul procesului condus extins : PCE - 2
- perioada de esantionare : $T_e = 12.5$ msec
- referinta de pozitie : treapta cu amplitudinea $w = 1000$
- perturbatia simulata : $u_p = 0$



Rezultatele programului de SIMULARE

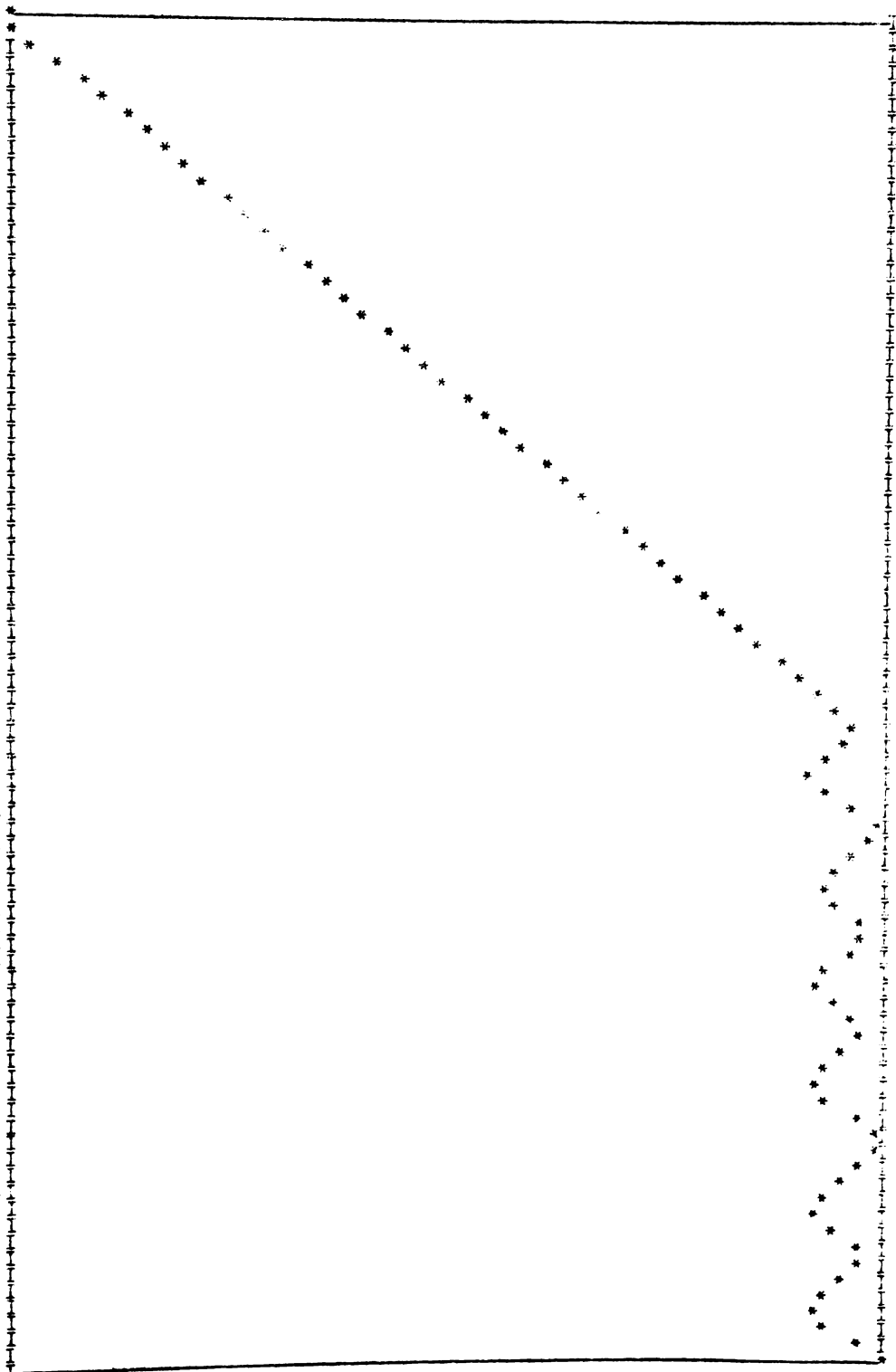
- algoritma de reglare : tip ARMA - 2
cu compensarea perturbatiilor
cu limitarea modulului comenzii
b1 = 7.81E-4
p2 = 6.10E-7
P = 1500
- modelul procesului condus extins : PCE - 2
- perioada de esantionare : Te = 12.5 msec
- referinta de pozitie : treapta cu amplitudinea w = 1000
- perturbatia simulata : up = 0

THEMA

MIN= 0.00000

MAX= 1051.01

0.00
10.00
20.00
30.00
40.00
50.00
60.00
70.00
80.00
90.00
100.00
110.00
120.00
130.00
140.00
150.00
160.00
170.00
180.00
190.00
200.00
210.00
220.00
230.00
240.00
250.00
260.00
270.00
280.00
290.00
300.00
310.00
320.00
330.00
340.00
350.00
360.00
370.00
380.00
390.00
400.00
410.00
420.00
430.00
440.00
450.00
460.00
470.00
480.00
490.00
500.00
510.00
520.00
530.00
540.00
550.00
560.00
570.00
580.00
590.00
600.00
610.00
620.00
630.00
640.00
650.00
660.00
670.00
680.00
690.00
700.00
710.00
720.00
730.00
740.00
750.00
760.00
770.00
780.00
790.00
800.00
810.00
820.00
830.00
840.00
850.00
860.00
870.00
880.00
890.00
900.00
910.00
920.00
930.00
940.00
950.00
960.00
970.00
980.00
990.00
1000.00



Rezultatele programului de SIMULARE

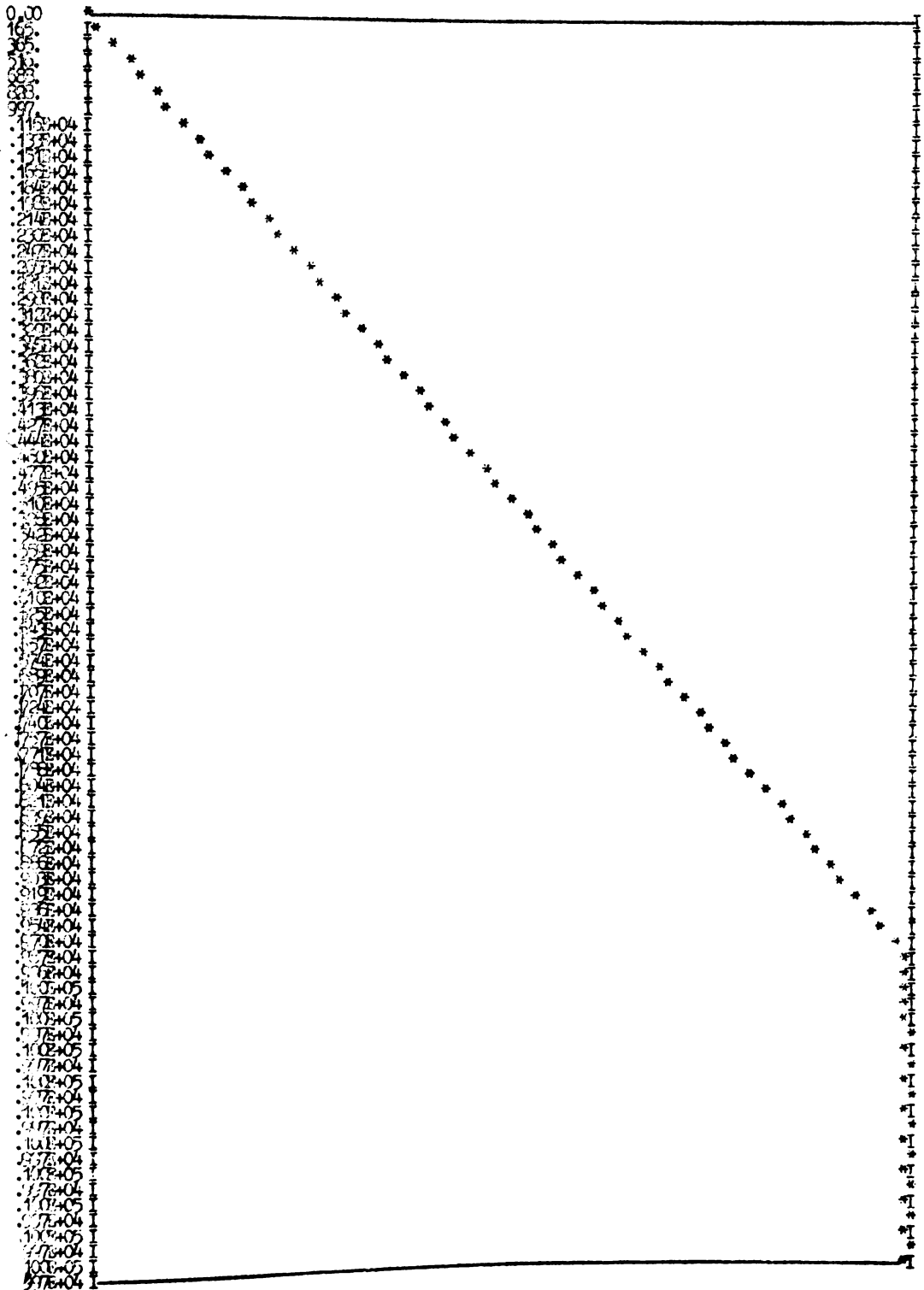
- algoritm de reglare : tip ARMA - 2
cu compensarea perturbatiilor
cu limitarea modulului comenzii
b1 = $7.81E-4$
b2 = $6.10E-7$
P = 1500
- modelul procesului condus extins : PCE - 2
- perioada de esantionare : $T_e = 12.5$ msec
- referinta de pozitie : treapta cu amplitudinea $w = 10000$
- perturbatia simulata : $u_p = 0$

obs. in grafice sint reprezentate valorile esantioanelor
din 10 in 10, astfel incit o linie corespunde unui
interval de timp $10 \cdot T_e = 125$ msec

MEMA

MIN= 0.00000

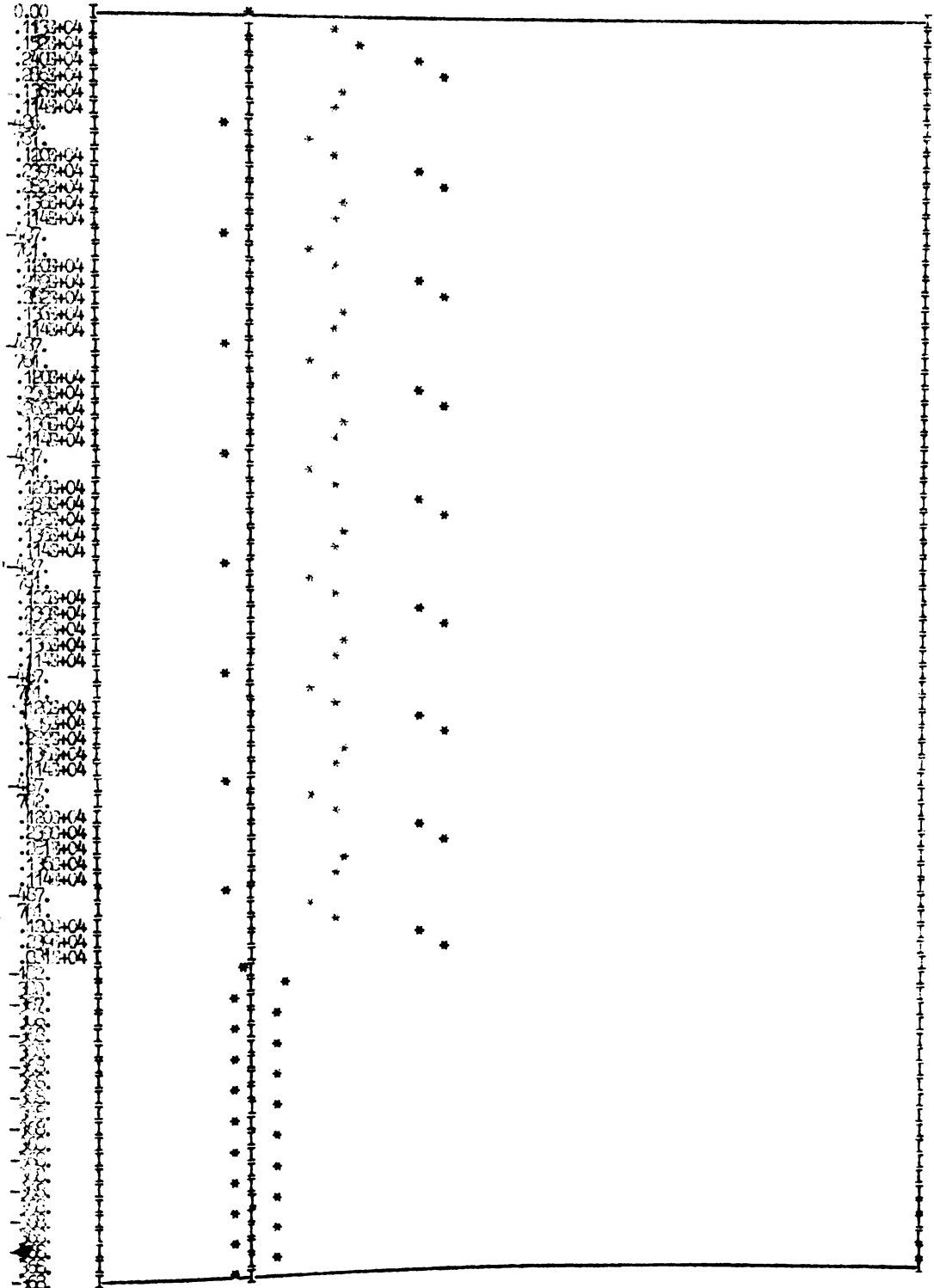
MAX= 10005.7



0.000A

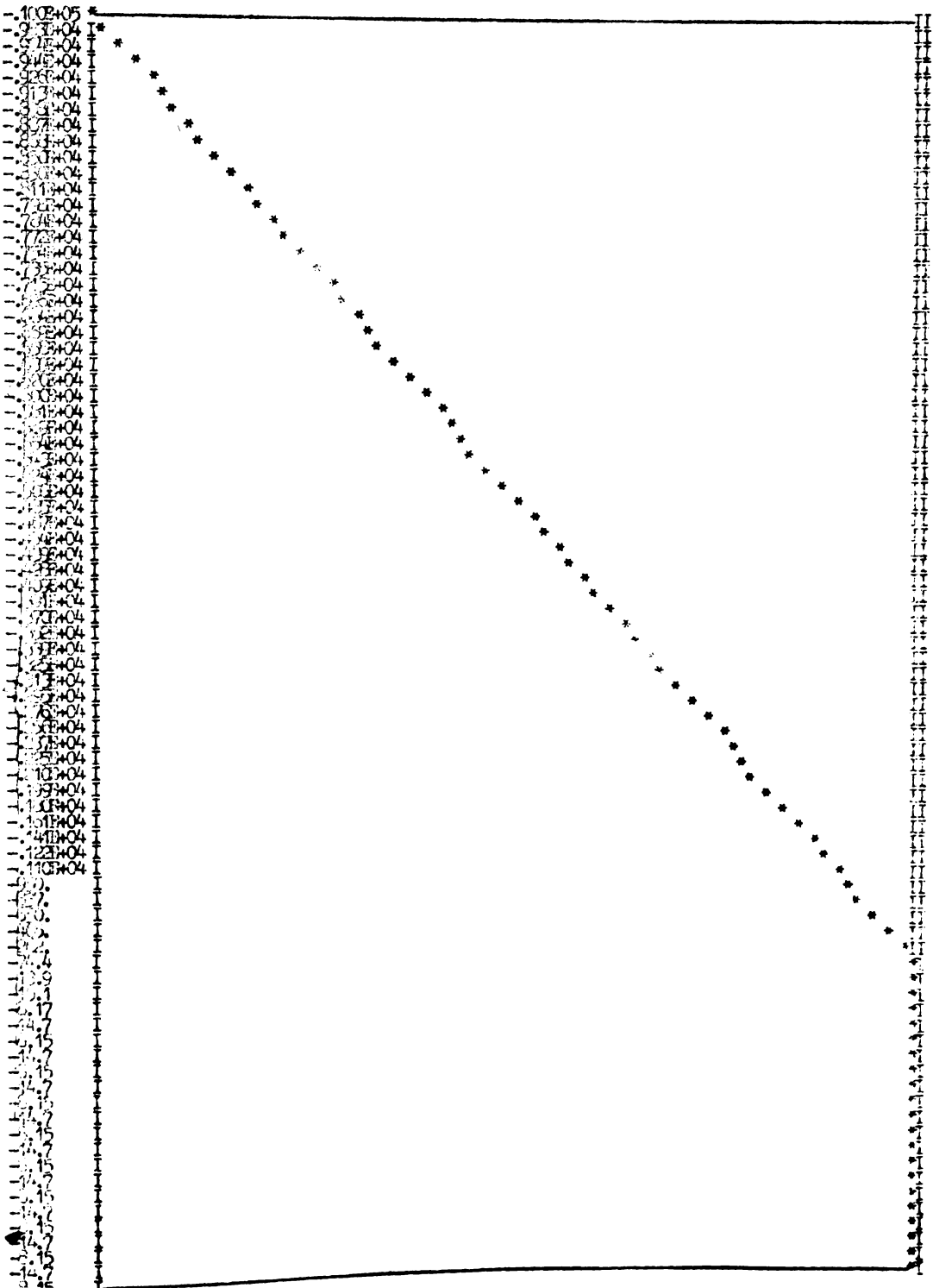
MIN= -3373.75

MAX= 10005.7



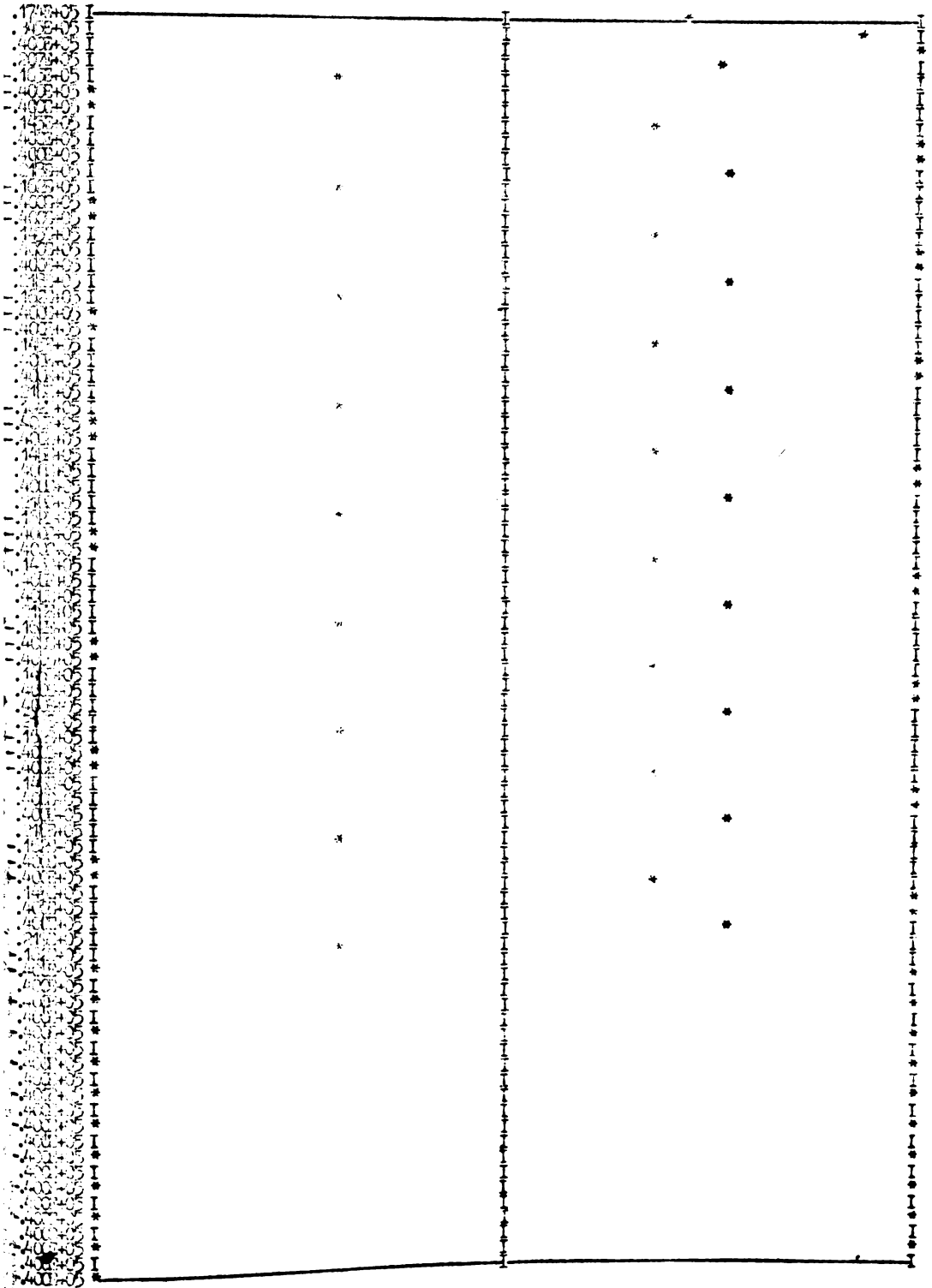
MIN= -10000.00

MAX= 64.0870



MIN= -40000.0

MAX= 40000.0



ANEXA A7

PROGRAMUL DE IMPLEMENTARE CONCRETA A METODEI DE
REGLARE NUMERICA MODAL-AMPLIFICARE A REZONANTEI
PENTRU UN SISTEM DE ACTIONARE CU MOTOR DE CURENT
CONTINUU

1. Executivul de timp real (STR)
2. Subprogramul de implementare a algoritmului ARMA-1
-cu neglijarea inertiei producerii actionii ponderomotoare
3. Subprogramul de implementare a algoritmului ARMA-2
-cu luarea in considerare a inertiei producerii
actionii ponderomotoare
4. Subprogramul din biblioteca matematica

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```

NAME      ('ETR')
EXT       ARNT
PUBLIC   TK,WK,UK,US,START,ETR
;
ORG       2016H
2016'    ADIN: DS      6      ;buffer caractere de la DAF
201C'    ADAD: DS      2      ;pointer buffer caractere
201E'    TABI: DS     10      ;tabel intreruperi
2028'    ADTAB: DS     2      ;pointer tabel intreruperi
202A'    SC:   DS      1      ;fanion sfirsit cuanta de
                        ;esantionare
202B'    SR:   DS      1      ;fanion sfirsit receptie
202C'    TK:   DS      2      ;theta(k)
202E'    WK:   DS      2      ;w(k)
2030'    UK:   DS      2      ;modul u(k)
2032'    US:   DS      1      ;semn u(k)
                        ORG     20E9H
20E9'    START: DS     1      ;fanion pornire (pentru TEST)
;
;subrutine monitor
4336     INSR  EQU     4336H   ;A(DAF)->B(ASCII)
4437     OUTEQ EQU     4437H   ;A(ASCII)->DAF
4441     CRLF  EQU     4441H   ;<CR>,<LF>->DAF
4534     ADRC  EQU     4534H   ;conversie sir cifre zecimale
                        ;(ASCII)->hexa
PAGE

```

```

;
;program principal ETR
;-----
;
;salt intrerupere DAF
8400'   C3 0151"   ORG   8400H
;initializari
;           ORG   8800H
;
8800'   CD 4441   ETR:  CALL  CRLF
8803'   3E 45     MVI   A,'E'
8805'   CD 4437   CALL  OUTFQ
8808'   CD 4441   CALL  CRIF ;semnalizeaza Executie
880B'   31 0000   LXI   SP,0 ;origine stiva
880E'   21 8400   LXI   H,8400H
8811'   22 20C9   SHLD  20C9H ;salt intrerupere DAF
;
8814'   AF       XRA   A
8815'   D3 02     OUT  2
8817'   D3 03     OUT  3
8819'   3E 01     MVI   A,1
881B'   D3 28     OUT  28H
881D'   3E 02     MVI   A,2
881F'   D3 0A     OUT  10 ;programare porturi
8821'   D3 08     OUT  8
8823'   AF       XRA   A
8824'   D3 08     OUT  8 ;CLEAR numarator
;
8826'   21 2016'  LXI   M,ADFN
8829'   22 201C'  SHLD  ADAD ;initializare pointer buffer
;caractere
;
882C'   06 1D     MVI   B,29
882E'   05       PR1:  DCR  B
882F'   77       MOV  M,A
8830'   23       INX  H
8831'   C2 882E' JNZ  PR1 ;initializare variabile cu adresa
8834'   C3 2033' PRC:  JMP  POZ ;in SRAM
;prelucrare pozitie curenta
2033'   DB 00     POZ:  IN   0
2035'   6F       MOV  L,A
2036'   DB 01     IN   1
2038'   67       MOV  H,A
2039'   DB 01     IN   1
203B'   BC       CMP  H
203C'   CA 2042' JZ   POZ1
203E'   DB 01     IN   1
2041'   67       MOV  H,A
2042'   DB 00     POZ1: IN   0
2044'   BD       CMP  L
2045'   C2 2033' JNZ  POZ
2048'   22 202C' SHLD  TK

```

```

204B'   C3 0000"
                                JMP     PR2     ;in DRAM
                                ;
204E'   ;constructie tabel intreruperi
0000"   DSRG
0003"   3A 2031'   PR2:   LDA     UK+1
0005"   FE 3C      CPI     3CH
0008"   DA 0085"   JC      PR3
0008"   FE 78      CPI     78H
000A"   DA 004F"   JC      PR4
000D"   FE 96      CPI     96H
000F"   DA 0018"   JC      PR5
0012"   21 9600   LXI     H,9600H ;u(k)>9600H
0015"   22 2030'   SHLD   UK
0018"   3E 3C      PR5:   MVI     A,3CH ;7800H < !u(k)! < 9600H
001A"   C6 80      ADI     80H
001C"   D3 2D      OUT    2DH
001E"   AF        XRA     A
001F"   D3 2C      OUT    2CH ;timer <- 3C00H
0021"   AF        XRA     A
0022"   32 201E'   STA     TABI
0025"   32 2021'   STA     TABI+3
0028"   3C        INR     A
0029"   32 2027'   STA     TABI+9
002C"   3C        INR     A
002D"   32 2024'   STA     TABI+6
0030"   21 3C00   LXI     H,3C00H
0033"   22 201F'   SHLD   TABI+1
0036"   2A 2030'   LHLD   UK
0039"   11 7800   LXI     D,7800H
003C"   CD 20EA"   CALL   HLDE
003F"   22 2022'   SHLD   TABI+4 ;!u(k)!-7800H
0042"   EB        XCHG
0043"   21 1E00   LXI     H,1E00H
0046"   CD 20EA"   CALL   HLDE ;9600H-!u(k)!
0049"   22 2025'   SHLD   TABI+7
004C"   C3 00BF"   JMP     PR6
004F"   3E 3C      PR4:   MVI     A,3CH ;3C00H < !u(k)! < 7E00H
0051"   C6 80      ADI     80H
0053"   D3 2D      OUT    2DH
0055"   AF        XRA     A
0056"   D3 2C      OUT    2CH ;timer <- 3C00H
0058"   AF        XRA     A
0059"   32 201E'   STA     TABI
005C"   32 2024'   STA     TABI+6
005F"   3C        INR     A
0060"   32 2027'   STA     TABI+9
0063"   3C        INR     A
0064"   32 2021'   STA     TABI+3
0067"   21 1E00   LXI     H,1E00H
006A"   22 2025'   SHLD   TABI+7
006D"   2A 2030'   LHLD   UK
0070"   11 3C00   LXI     D,3C00H
0073"   CD 20EA"   CALL   HLDE ;!u(k)!-3C00H
0076"   22 201F'   SHLD   TABI+1
0079"   EB        XCHG
007A"   21 3C00   LXI     H,3C00H

```

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```

007D"  CD 20EA"          CALL  HLMBE
0080"  22 2022'         SHLD  TABI+4 ;7800H-!u(k)!
0083"  C3 00BF"         JMP   PR6
0086"  3A 2031'         PR3:  LDA  UK+
0089"  C6 80            ADI  80H
008B"  D3 2D           OUT  2DH
008D"  3A 2030'         LDA  UK
0090"  FE 0A           CPI  1C
0092"  DA 0094"        JC   $+2
0095"  3E 0A           MVI  A,10 ;limitare !u(k)! > 10
0097"  D3 2C           OUT  2CH ;timer <- !u(k)!
0099"  AF             XRA  A
009A"  32 2021'         STA  TABI+3
009D"  32 2024'         STA  TABI+5
00A0"  3C             INR  A
00A1"  32 2027'         STA  TABI+9
00A4"  3C             INR  A
00A5"  32 201E'         STA  TABI
00A8"  21 1E00          LXI  H,1E00H
00AB"  22 2025'         SHLD  TABI+7
00AE"  21 3C00          LXI  H,3C00H
00B1"  22 2022'         SHLD  TABI+4
00B4"  EB             XCHG
00B5"  2A 2030'         INLD  UK
00B8"  EB             XCHG
00B9"  CD 20EA"        CALL  HLMBE
00BC"  22 201F'         SHLD  TABI+ ;3C00H-!u(k)!
00BF"  21 201E'         PR6:  LXI  H,TABI
00C2"  22 2028'         SHLD  ADTAB ;initializare pointer tabel
                                ;intreruperi

                                ;start chopper
00C5"  3A 2032'         LDA  US
00C8"  B7             ORA  A
00C9"  3E 04           MVI  A,4
00CB"  CA 00D0"        JZ   PR7
00CE"  C6 04           ADI  4
00D0"  D3 29           PR7:  OUT  2CH
                                ;validare intreruperi
00D2"  3E 09           MVI  A,9
00D4"  30             DI   30H ;codul instructiunii SEM

                                ;start trime
00D5"  3E C1           MVI  A,0C1H
00D7"  D3 28           OUT  28H
00D9"  FB             EI

                                ;apulare ARM
00DA"  CD 0000*        CALL  ARMT
00DD"  76             PR8:  HLH

                                ;testare fanioane
00DE"  3A 202A'         LDA  SC
00E1"  B7             ORA  A
00E2"  CA 00DD"        JZ   PR8
00E5"  AF             XRA  A
00E6"  32 202A'         STA  SC
00E9"  3A 2023'         LDA  SR
00EC"  B7             ORA  A
00ED"  CA 2033'         JZ   PR8

```

```

00F0"  AF                                XRA    A
00F1"  32 202B'                          STA    SR
                                           ;prelucrare w(k)
00F4"  01 2016'                          LXI    B,ADIN
00F7"  21 2016'                          LXI    H,ADIN
00FA"  22 201C'                          SHLD  ADAD ;initializare pointer
00FD"  CD 4534                          CALL  ADEC ;conversie ASCII->hexa
0100"  E5                                PUSH  H
0101"  22 202E'                          SHLD  WK
0104"  7C                                MOV   A,H
0105"  CD 456D                          CALL  456DH
0108"  E1                                POP   H
0109"  7D                                MOV   A,L
010A"  CD 456D                          CALL  456DH
010D"  3E 48                            MVI  A,'H'
010F"  CD 4437                          CALL  OUT8Q
0112"  CD 4441                          CALL  CRLF ;ecou w(k)
0115"  C3 2033'                          RETR:  JMP  POZ
                                           PAGE

```

```

;
;subrutina tratare intrerupere TIMER (RST 6.5)
;-----
;
20CE"  C3 0118"          ORG      20CEH
                        JMP      ITIM      ;salt intrerupere
;
0118"  F5                ORG      BETR+3
0119"  E5                ITIM:  PUSH   PSW
                        PUSH   H
;testare tip eveniment
011A"  2A 2028'         LHL    ADTAB
011D"  7E                MOV    A,M
011E"  1F                RAR
011F"  DA 0149"         JC     IT1
0122"  1F                RAR
0123"  D2 0129"         JNC   E2
;stop chopper
0126"  AF                XRA    A
0127"  D3 29            OUT   29H
;incalzare timer
0129"  23                IT2:  INX   H
012A"  7E                MOV   A,M
012B"  FE 0A            CPI   10
012D"  DA 012F"         JC    $+2
0130"  3E 0A            MVI  A,10 ;limitare !u(k)! > 10
0132"  D3 2C            OUT  2CH
0134"  23                INX   H
0135"  7E                MOV   A,M
0136"  C6 80            ADI  80H
0138"  D3 2D            OUT  2DH
013A"  23                INX   H
013B"  22 2028'         SHLD ADTAB ;valoarea incrementata a
                        ;pointerului
;validare intreruperi
013E"  3E 09            MVI  A,9
0140"  30                DB   30H ;codul instructiunii SIM
0141"  FB                EI
;start timer
0142"  E1                POP   H
0143"  3E C1            MVI  A,0C1H
0145"  D3 28            OUT  28H
0147"  F1                POP   PSW
0148"  C9                RET
0149"  3E 01            IT1: MVI  A,1
014B"  32 202A'         STA  3C
014E"  E1                POP   H
014F"  F1                POP   PSW
0150"  C9                RET
                        PAGE

```



```

;
;subrutina tratare intrerupere DAF (RST 7.5)
;
0151"  F5          IDAF:  PUSH    PSW
0152"  05          PUSH    B
0153"  E5          PUSH    H
0154"  2A 2010'    LHL D  ADAD    ;pointer
0157"  3A 7000    LDA     7000H
015A"  CD 4336    CALL   INER    ;preluare caracter
015D"  78          MOV     A,B
015E"  FE 0D      CPI     13      ;<CR>
0160"  CA 018F"   JZ     ED1
0163"  FE 53      CPI     'S'
0165"  CA 019E"   JZ     ED4
0168"  FE 51      CPI     'Q'
016A"  CA 430C    JZ     430CH
016D"  FE 18      CPI     24      ;<CLEAR>
016F"  C2 0178"   JNZ    ED2
0172"  CD 4437    CALL   OUT8Q
0175"  C3 018A"   JMP    ED3
0178"  FE 30      ED2:  CPI     30H
017A"  DA 018A"   JC     ED3
017D"  FE 3A      CPI     3AH
017E"  D2 018A"   JNC    ED3      ;testare cifra
0182"  CD 4437    CALL   OUT8Q    ;ecou
0185"  70          MOV     M,B
0186"  23          INX     H
0187"  22 2010'    SHLD  ADAD    ;pointer incrementat
018A"  E1          ED3:  POP    H
018B"  C1          POP    B
018C"  F1          POP    PSW
018D"  FB          EI
018E"  C9          RET
018F"  3E 3D      ED4:  MVI    A,'=' ;<CR>
019 "  CD 4437    CALL   OUT8Q
0194"  36 00      MVI    M,0
0196"  3E 01      MVI    A,1
0198"  32 202B'   STA    SR
019B"  C3 018A"   JMP    ED3
019E"  3E 01      ED4:  MVI    A,1   ;'S'
01A0"  32 20E9'   STA    START
01A3"  CD 4441    CALL   CRLF
01A6"  3E 53      MVI    A,'S'
01A8"  CD 4437    CALL   OUT8Q
01AB"  CD 4441    CALL   CRLF    ;semnalizeaza Start
01AE"  C3 018A"   JMP    ED3
;subrutina scadere
20EA"  7D          HLMDE: ORG    20EAH
20EB"  93          MOV    A,L
20EC"  6F          SUB    B
20ED"  7C          MOV    L,A
20EE"  9A          MOV    A,H
20EF"  67          SBB    D
                MOV    H,A

```

2070" 09

RET
END

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Macros:

Symbols:

201C'	ADAD	4534	ADEC	2016'	ADIN
2028'	ADTAB	00DB*	ARNT	4441	CRLF
018F"	ED1	0178"	ED2	018A"	ED3
019E"	ED4	0115"	EETR	8800I'	ETR
20EA"	HLMDE	0151"	IDAF	4336	IN8R
0149"	IT1	0129"	IT2	0118"	ITIM
4437	OUT8Q	2033'	POZ	2042'	POZ1
882E'	PR1	0000"	PR2	0086"	PR3
004F"	PR4	0018"	PR5	00BF"	PR6
00D0"	PR7	00DD"	PR8	8834'	PRC
202A'	SC	202B'	SR	20E9I'	START
201E'	TABI	202C'	TK	2030I'	UK
2032I'	US	202E'	WK		

No Fatal error(s)

```

NAME ('ARMA1')
;
;algorithm ARMA-1
;
PUBLIC ARMA1,K2,K3,K4
PUBLIC TK1,T1K1,UK1,VK2T,T1K
EXT MUL12,CPL3,MUL12M,CPL2,ADD3V,ADD3
EXT ROT3R,DIF2,COMP2,ROT3LV,WK,TK,UK,US
DSEG
;variable
TK1: DS 2 ;theta(k-1)
T1K: DS 2 ;omega(k)
T1K1: DS 2 ;omega(k-1)
UK1: DS 3 ;u(k-1)
VK2T: DS 3 ;v~(k-2)
;parametri
K2: DW 64 ;3.2*C
K3: DW 4000 ;C.1*P
K4: DW 10 ;-0.514*C
PAGE
0000'
0000"
0002"
0004"
0006"
0009"
000C" 0040
000E" 0FAC
0010" 000A

```

```

0012"                                CSECT
;program
APMA1: LHL D TK
0000' 2A 0000*                        XCHG
0003' EB                                LHL D TK1
0004' 2A 0000"                        CALL DIF2 ;DE=omega(k)=theta(k)-
0007' CD 0000*                        ; -theta(k-1)

000A' 2A 0000*                        LHL D TK
000D' 22 0000"                        SHLD TK1 ;theta(k-1) <- theta(k)
0010' EB                                XCHG
0011' 22 0002"                        SHLD T1K
0014' EB                                XCHG
0015' 2A 0004"                        LHL D T1K1
0018' CD 0000*                        CALL DIF2 ;DE=omega1(k)=omega(k)-
; -omega(k-1)

001B' 2A 0002"                        LHL D T1K
001E' 22 0004"                        SHLD T1K1 ;omega(k-1) <- omega(k)
0021' 42                                MOV B,D
0022' 63                                MOV H,E
0023' 2E 00                            MVI L,0 ;RHL=omega1(k)*2^8
0025' 4A                                MOV C,D
0026' 53                                MOV D,E
0027' 5D                                MOV E,L ;CDE=omega1(k)*2^8
0028' CD 0000*                        CALL ADD3V ;DHL=omega1(k)*2^9
002B' CD 0000*                        CALL ROT3R ;CDE=omega1(k)*2^7
002E' CD 0000*                        CALL ADD3V ;EHL=omega(k)*(2^7+2^9)
0031' CD 0000*                        CALL CPI3 ;BHL=-omega(k)*(2^7+2^9)
0034' EB                                XCHG
0035' 48                                MOV C,B ;CDE=-omega(k)*(2^7+2^9)
0036' 2A 0006"                        LHL D UK1
0039' 3A 0008"                        LDA UK1+2
003C' 47                                MOV B,A ;EHL=v(k-1)
003D' CD 0000*                        CALL ADD3V ;BHL=v(k-1)
0040' EB                                XCHG
0041' 48                                MOV C,B ;CDE=v(k-1)
0042' 21 0000                        LXI H,0
0045' 06 00                            MVI B,0 ;BHL=0
0047' CD 0000*                        CALL ROT3R
004A' CD 0000*                        CALL ADD3
004D' CD 0000*                        CALL ROT3R
0050' CD 0000*                        CALL ROT3R
0053' CD 0000*                        CALL ADD3 ;BHL=v(k-1)*(2^7+2^9-3)
0056' EB                                XCHG
0057' 2A 0009"                        LHL D VK2T
005A' EB                                XCHG
005B' 3A 000B"                        LDA VK2T+2
005E' 4F                                MOV C,A ;CDE=v^(k-2)
005F' CD 0000*                        CALL ROT3R
0062' CD 0000*                        CALL ROT3R
0065' CD 0000*                        CALL ADD3
0068' CD 0000*                        CALL ROT3R
006B' CD 0000*                        CALL ADD3 ;BHL=v^(k-1)
006E' 22 0009"                        SHLD VK2T
0071' 78                                MOV A,B

```

```

0072' 32 000B'' STA VK2T+2 ;v~(k-2) <- v~(k-1)
0075' 2A 0000* LHL D TK
0078' EB XCHG ;DE=theta(k)
0079' 2A 0000* LHL WK ;HL=w(k)
007C' CD 0000* CALL COMP2
007F' D2 0083' JNC ARN1 ;theta(k) > w(k)
0082' EB XCHG ;face DE > HL
0083' F5 ARM1: PUSH PSW ;CY=1 daca e(k) < 0
0084' CD 0000* CALL DIF2 ;DE= !e(k)!
0087' 3A 0000'' LDA K2
008A' 4F MOV C,A
008B' CD 0000* CALL MUL12 ;BHL=K2*!e(k)! > 0
008E' 6C MOV L,H
008F' 60 MOV H,B
0090' 06 00 MVI B,0 ;PHL=K2*!e(k)!*2^-8
0092' F1 POP PSW ;CY=1 daca e(k) < 0
0093' DC 0000* CC CPL3 ;PHL=K2*e(k)*2^-8
0096' EB XCHG
0097' 48 MOV C,B ;CDE=K2*e(k)*2^-8
0098' 2A 0002'' LHL D T1K ;HL=omega(k)
009E' 7C MOV A,H
009C' 17 RAL ;CY=1 daca HL < 0
009D' 3E 00 MVI A,0
009F' D2 00A3' JNC ARM2
00A2' 2F CMA
00A3' 47 ARM2: MOV B,A ;BHL=omega(k)
00A4' CD 0000* CALL ADD3 ;PHL=s(k)
00A7' 78 MOV A,B
00A8' 17 RAL ;CY=1 daca s(k) < 0
00A9' F5 PUSH PSW
00AA' 2A 0002'' LHL D T1K
00AD' EB XCHG ;DE=omega(k)
00AE' 3A 0010'' LDA K4
00B1' 4F MOV C,A
00B2' CD 0000* CALL MUL12 ;PHL=K4*omega(k)
00B5' CD 0000* CALL CPL3
00B8' 5D MOV E,L
00B9' 54 MOV D,H
00BA' 48 MOV C,B ;CDE=K4*omega(k)
00BB' CD 0000* CALL ROT3LV
00BE' CD 0000* CALL ROT3LV
00C1' CD 0000* CALL ROT3LV
00C4' CD 0000* CALL ROT3LV ;CDE=K4*omega(k)*2^-8
00C7' 2A 000E'' LHL D K3
00CA' 06 00 MVI B,0 ;BHL=K3
00CC' F1 POP PSW ;CY=1 daca s(k) < 0
00CD' D5 PUSH D
00CF' D4 0000* CNC CPL3 ;PHL=-K3*sgn{s(k)}
00D1' D1 POP D
00D2' CD 0000* CALL ADD3V ;BHL=omega1D(k)
00D5' EB XCHG
00D6' 48 MOV C,B ;CDE=omega1D(k)
00D7' 2A 0009'' LHL D VK2T
00DA' 3A 000B'' LDA VK2T+2
00DD' 47 MOV B,A ;BHL=v~(k-2)
00DE' CD 0000* CALL ADD3V ;PHL=u(k)

```

```
00E1' 22 0006"      SHLD  UK1
00E4' 78            MOV   A,B
00E5' 32 0008"      STA   UK1+2 ;u(k-1) <- u(k)
00E8' 17            RAL
00E9' 3E 00        MVI   A,0
00EB' 17            RAL ;A=1 daca u(k) < 0
00EC' 32 0000*     STA   US
00EF' 1F            RAR
00F0' DC 0000*     CC    CPL3 ;BHL=!u(k)!
00F3' 78            MOV   A,B
00F4' B7            ORA   A
00F5' CA 00FB'     JZ    ARN3
00F8' 21 FFFF      LXI   H,0FFFF ;limitare superiora
                                ; !u(k)!

00FB' 22 0000*     ARN3: SHLD  UK
00FE' C9            RET
                                END
```

↑
Macros:

Symbols:

00A5*	ADD3	00DF*	ADD3V	0000I'	ARNA1
00E3'	ARN1	00A3'	ARN2	00FB'	ARN3
007D*	COMP2	0000*	CPL2	00F1*	CPL3
00E5*	DIF2	0000I''	K2	000EI''	K3
0010I''	K4	00B3*	MUL/2	0000*	FILE2M
00C5*	ROT3LV	0069*	ROT3R	0002I''	T4K
0004I''	T4K1'	0076*	TK	0000I''	TK1
00FC*	UK	0006I''	UK1	00ED*	US
0009I''	VK2T	007A*	WK		

No Fatal error(s)


```

                                NAME ('ARMA2')
;
;algorithm ARMA-2
;
    PUBLIC ARMA2,K1
    PUBLIC T2K1
    EXT    TK,WK,UK,US
    EXT    UK1,T1K,T1K1,TK1,VK2T
    EXT    MUL12,CPL3,MUL12I,CPL2,ADD3V,ADD3
    EXT    ROT3R,DIF2,COMP2,ROT3LV
;parametri
    DSEG
0000'      K1:    DW    60      ;0.0125*P
0000"      003C
;variabile
0002"      T2K:   DS    2      ;theta2(k)
0004"      T3K:   DS    2      ;theta3(k)
0006"      T2K1:  DS    2      ;theta2(k-1)
0008"      T1DK:  DS    3      ;theta1D(k)
000B"      T2DK:  DS    3      ;theta2D(k)
                                PAGE
```

```

;program
000E"          CSEG
0000'  2A 0000*  ARMA2:  LHLD  TK
0003'  EB          XCHG
0004'  2A 0000*  LHLD  TK1
0007'  CD 0000*  CALL  DIF2  ;DE=theta1(k)
000A'  2A 0000*  LHLD  TK
000D'  22 0000*  SHLD  TK1  ;theta(k-1) <
- theta(k)
0010'  EB          XCHG
0011'  22 0000*  SHLD  T1K
0014'  EB          XCHG
0015'  2A 0000*  LHLD  T1K1
0018'  CD 0000*  CALL  DIF2  ;DE=theta2(k)
001B'  2A 0000*  LHLD  T1K
001E'  22 0000*  SHLD  T1K1  ;theta1(k-1) <- theta1(k)
0021'  EB          XCHG
0022'  22 0002"  SHLD  T2K
0025'  EB          XCHG
0026'  2A 0006"  LHLD  T2K1
0029'  CD 0000*  CALL  DIF2  ;DE=theta3(k)
002C'  2A 0002"  LHLD  T2K
002F'  22 0006"  SHLD  T2K1  ;theta2(k-1) <- theta2(k)
0032'  EB          XCHG
0033'  22 0004"  SHLD  T3K
0036'  4C          MOV  C,H
0037'  55          MOV  D,L
0038'  1E 00       MVI  E,0  ;CDE=theta3(k)*2<8
003A'  21 0000     LXI  H,C
003D'  43          MOV  B,E  ;BHI=0
003E'  CD 0000*  CALL  ROT3R
0041'  CD 0000*  CALL  ROT3R
0044'  CD 0000*  CALL  ADD3
0047'  CD 0000*  CALL  ROT3R
004A'  CD 0000*  CALL  ADD3  ;BHL=a3*theta3(k)
004D'  3A 0003"  LDA  T2K+
0050'  4F          MOV  C,A
0051'  3A 0002"  LDA  T2K
0054'  57          MOV  D,A
0055'  1E 00       MVI  E,0  ;CDE=theta2(k)*2^8
0057'  CD 0000*  CALL  ROT3R
005A'  CD 0000*  CALL  ADD3
005D'  CD 0000*  CALL  ROT3LV
0060'  CD 0000*  CALL  ROT3LV
0063'  CD 0000*  CALL  ADD3V  ;BHL=a3*theta3(k)+
; +a2*theta2(k)
0066'  3A 0001*  LDA  T1K+1
0069'  4F          MOV  C,A
006A'  3A 0000*  LDA  T1K
006D'  57          MOV  D,A
006E'  1E 00       MVI  E,0  ;CDE=theta1(k)*2^8
0070'  CD 0000*  CALL  ROT3R
0073'  CD 0000*  CALL  ROT3R
0076'  CD 0000*  CALL  ADD3V
0079'  CD 0000*  CALL  ROT3R

```

```

0070'   CD 0000*           CALL   ADD3V           ;BHL=a3*theta3(k)+
                                           ; +a2*theta2(k)+a1*theta1(k)
007F'   CD 0000*           CALL   CPL3
0082'   EB                XCHG
0083'   2A 0000*          LHL    UK1
0086'   EB                XCHG
0087'   3A 0002*          LDA     UK1+2
008A'   4F                MOV     C,A           ;CDE=u(k-1)
008B'   CD 0000*          CALL   ADD3V       ;BHL=v(k-1)
008E'   EB                XCHG
008F'   48                MOV     C,B           ;CDE=v(k-1)
0090'   21 0000          LXI     H,0
0093'   06 00            MVI     B,0           ;BHL=0
0095'   CD 0000*          CALL   ROT3R
0098'   CD 0000*          CALL   ADD3V
009B'   CD 0000*          CALL   ROT3R
009E'   CD 0000*          CALL   ROT3R
00A1'   CD 0000*          CALL   ADD3V
00A4'   EB                XCHG
00A5'   2A 0000*          LHL    VK2T
00A8'   EB                XCHG
00A9'   3A 0002*          LDA     VK2T+2
00AC'   4F                MOV     C,A           ;CDE=v~(k-2)
00AD'   CD 0000*          CALL   ROT3R
00B0'   CD 0000*          CALL   ROT3R
00B3'   CD 0000*          CALL   ADD3V
00B6'   CD 0000*          CALL   ROT3R
00B9'   CD 0000*          CALL   ADD3V       ;BHL=v~(k-2)
00BC'   22 0000*          SHLD   VK2T
00BF'   78                MOV     A,B
00C0'   32 0002*          STA     VK2T+2       ;v~(k-2) <- v~(k-1)
00C3'   2A 0000*          LHL    TX
00C6'   EB                XCHG
00C7'   2A 0000*          LHL    WK
00CA'   CD 0000*          CALL   COMP2       ;CY=1 dacc. e(k)<0
00CD'   D2 00D1'         JNC   ARN4
00D0'   EB                XCHG
00D1'   F5                ARN4:  PUSH  PSW
00D2'   CD 0000*          CALL   DIF2       ;DF=!e(k)!
00D5'   EB                XCHG
00D6'   06 00            MVI     B,0           ;BHL=!e(k)!
00D8'   F1                POP    PSW
00D9'   DC 0000*          CC     CPL3       ;BHL=e(k)
00DC'   EB                XCHG
00DD'   2A 0000*          LHL    T1K
00E0'   EB                XCHG
00E1'   7A                MOV     A,D
00E2'   0E 00            MVI     C,0
00E4'   17                RAL
00E5'   D2 00EA'         JNC   ARN5
00E8'   0E FF            MVI     C,OFFH      ;CDE=theta'(k)
00EA'   CD 0000*          ARN5:  CALL  ADD3V
00ED'   EB                XCHG
00EF'   2A 0002"         LHL    T2K
00F1'   EB                XCHG
00F2'   7A                MOV     A,D

```

```

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00F3'  0E 00          MVI    C,0
00F5'  17            RAL
00F6'  D2 00FB'     JNC    ARN6
00F9'  0E FF          MVI    C,OFFH ;CDE=theta2(k)
00FB'  CD 0000*     CALL   ADD3V ;BHL=s(k)
00FE'  78            MOV    A,B
00FF'  17            RAL          ;CY=1 daca s(k) < 0
0100'  2A 0000''    LHL    K1
0103'  06 00          MVI    B,0 ;BHL=K1
0105'  DC 0000*     CC      CPL3 ;BHL=K1*sign{s(k)}
0108'  EB            XCHG
0109'  2A 0002''    LHL    T2K
010C'  EB            XCHG
010D'  7A            MOV    A,D
010E'  0E 00          MVI    C,0
0110'  17            RAL
0111'  D2 0116'     JNC    ARN7
0114'  0E FF          MVI    C,OFFH ;CDE=theta2(k)
0116'  CD 0000*     CALL   ADD3V
0119'  EB            XCHG
011A'  2A 0004''    LHL    T3K
011D'  EB            XCHG
011E'  7A            MOV    A,D
011F'  0E 00          MVI    C,0
0121'  17            RAL
0122'  D2 0127'     JNC    ARN8
0125'  0E FF          MVI    C,OFFH ;CDE=theta3(k)
0127'  CD 0000*     CALL   ADD3V
012A'  CD 0000*     CALL   CPL3 ;BHL=theta4D(k)
012D'  22 0008''    SHLD  T1DK
0130'  78            MOV    A,B
0131'  32 000A''    STA   T1DK+2
0134'  EB            XCHG
0135'  2A 0000*     LHL    T1K
0138'  CD 0000*     CALL   CPL2
013B'  EB            XCHG ;DE=-theta1(k)
013C'  7A            MOV    A,D
013D'  0E 00          MVI    C,0
013F'  17            RAL
0140'  D2 0145'     JNC    ARN9
0143'  0E FF          MVI    C,OFFH ;CDE=-theta1(k)
0145'  CD 0000*     CALL   ADD3V ;BHL=theta2D(k)
0148'  22 000B''    SHLD  T2DK
014B'  78            MOV    A,B
014C'  32 000D''    STA   T2DK+2
014F'  EB            XCHG
0150'  2A 0002''    LHL    T2K
0153'  CD 0000*     CALL   CPL2
0156'  EB            XCHG ;DE=theta2(k)
0157'  7A            MOV    A,D
0158'  0E 00          MVI    C,0
015A'  17            RAL
015B'  D2 0160'     JNC    ARN10
015E'  0E FF          MVI    C,OFFH ;CDE=theta2(k)
0160'  CD 0000*     CALL   ADD3V ;BHL=theta3D(k)
0163'  EB            XCHG

```

```

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0164'  48          MOV     C,B           ;CDE=theta3D(k)
0165'  21 0000    LXI     H,0
0168'  06 00      MVI     B,0           ;BHL=0
016A'  CD 0000*   CALL    ROT3R
016D'  CD 0000*   CALL    ROT3R
0170'  CD 0000*   CALL    ALD3V
0173'  CD 0000*   CALL    ROT3R
0176'  CD 0000*   CALL    ADD3V           ;BHL=a3*theta3D(k)
0179'  EB          XCHG
017A'  2A 000B'' LHLD   T2DK
017D'  EB          XCHG
017E'  3A 000D'' LDA    T2DK+2
0181'  4F          MOV     C,A           ;CDE=theta2D(k)
0182'  CD 0000*   CALL    ROT3R
0185'  CD 0000*   CALL    ADD3V
0188'  CD 0000*   CALL    ROT3LV
018B'  CD 0000*   CALL    ROT3LV
018E'  CD 0000*   CALL    ADD3V           ;BHL=a3*theta3D(k)+
                                ; +a2*theta2D(k)

0191'  EB          XCHG
0192'  2A 000B'' LHLD   T1DK
0195'  EB          XCHG
0196'  3A 000A'' LDA    T1DK+2
0199'  4F          MOV     C,A
019A'  CD 0000*   CALL    ROT3R           ;CDE=theta1D(k)
019D'  CD 0000*   CALL    ADD3V
01A0'  CD 0000*   CALL    ROT3R
01A3'  CD 0000*   CALL    ROT3R
01A6'  CD 0000*   CALL    ADD3V
01A9'  CD 0000*   CALL    ROT3R
01AC'  CD 0000*   CALL    ADD3V           ;BHL=a3*theta3D(k)+
                                ; +a2*theta2D(k)+a1*theta1D(k)

01AF'  EB          XCHG
01B0'  2A 0000*   LHLD   VK2I
01B3'  EB          XCHG
01B4'  3A 0002*   LDA    VK2I+2
01B7'  4F          MOV     C,A           ;CDE=v~(k-2)
01B8'  CD 0000*   CALL    ADD3V           ;BHL=u(k)
01BB'  22 0000*   SHLD  UK1
01BE'  78          MOV     A,B
01BF'  32 0002*   STA   UK1+2           ;u(k-1) <- u(k)
01C2'  17          RAL
01C3'  AF          XRA     A
01C4'  CE 00      ACI     0           ;A=1 dac a u(k) < 0
01C6'  32 0000*   STA   US
01C9'  78          MOV     A,B
01CA'  17          RAL
01CB'  DC 0000*   CC     CPL3           ;BHL=!u(k)!
01CE'  78          MOV     A,B
01CF'  B7          ORA     A
01D0'  CA 01D6'   JZ     ARN11
01D3'  21 0FFF    LXI     H,0FFFH           ;limitare !u(k)!
01D6'  22 0000*   SHLD  UK
01D9'  C9          RET
                                END
                                ARN11:

```

Macros:

Symbols:

005B*	ALB3	0189*	ATTN	00001*	ARMAE
0160'	ARM10	0126'	ARM	0021'	ARMA
009A'	ARM5	0081'	ARM6	0145'	ARMA
0127'	ARM8	0145'	ARM8	0007*	ARMAE
0154*	CPL2	0100*	CELE	0001*	ARMA
00001"	K1	0000*	CELE	0000*	ARMAE
0180*	ROT3LV	014A*	ROE3E	0000"	ARMA
0136*	T4K	0002*	T4K	0000"	ARMA
0002"	T2K	0000"	T2K	0004"	ARMA
0004-	TK	0000*	TK	0000*	ARMA
0100*	UK1	0100*	UK		
0008*	WK				

No Fatal error(s)

```

;
;subrutine matematice
;
PUBLIC MUL12,CPL3,MUL12M,CPL2,ADD3V,ADD3
PUBLIC ROT3R,DIF2,COMP2,ROT3LV
;
0000' CSEG
;
;MUL12 inmultire 1o(M) * 2o(C2) -> 3o(C2)
;          C * DE -> BHL
;          modifica A,F
;
0000' 7A MUL12: MOV A,D
0001' 17 RAL
0002' F5 PUSH PSW
0003' D2 000B' JNC MODUL
0006' EB XCHG
0007' CD 0038' CALL CPL2
000A' EB XCHG
000B' 41 MODUL: MOV B,C
000C' 0E 08 MVI C,8 ;contor
000E' 21 0000 LXI H,0
0011' 29 LOOP: DAD H ;rotire stinga BHL
0012' 78 MOV A,B
0013' 17 RAL
0014' 47 MOV B,A
0015' D2 001D' JNC NEXT
0018' 19 DAD D
0019' D2 001D' JNC NEXT
001C' 04 INR B
001D' 0D NEXT: DCR C
001E' C2 0011' JNZ LOOP
0021' F1 POP PSW
0022' D0 RNC ;subrutina continua cu CPL3
;
;CPL3 complementare 3o
;          BHL <- -(BHL)
;          modifica A,F,D,E
0023' 7D CPL3: MOV A,L
0024' 2F CMA
0025' 6F MOV L,A
0026' 7C MOV A,H
0027' 2F CMA
0028' 67 MOV H,A
0029' 78 MOV A,B
002A' 2F CMA
002B' 11 0001 LXI D,1
002E' 19 DAD D
002F' CE 00 ACI 0
0031' 47 MOV B,A
0032' C9 RET
;
;MUL12M inmultire 1o(M) * 2o(M) -> 3o(M)
;          C * DE -> BHL
;          modifica A,F
0033' B7 MUL12M: ORA A ;CY=C

```

```

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0034'  F5
0035'  C3 000B'

                                PUSH   PSW
                                JMP     MODUL ;subrutina continua in MUL12
                                ;
                                ;CPL2 complementare 2o
                                ;                               HL <- -(HL)
                                ;
                                ;                               NU modifica B,C,D,E
                                CPL2: MOV     A,H
                                0038' 7C
                                0039' 2F
                                003A' 67
                                003B' 7D
                                003C' 2F
                                003D' 6F
                                003E' 23
                                003F' C9
                                MOV     A,H
                                MOV     H,A
                                MOV     A,L
                                CMA
                                MOV     L,A
                                INX     H
                                RET

                                ;
                                ;ADD3V adunare 3o(C2) + 3o(C2) -> 3o(C2)
                                ;       cu verificarea depasirii si limitare
                                ;       BHL + CDE -> BHL
                                ;       modifica A,F
                                ;       pastreaza CDE
                                ADD3V: MOV     A,B
                                XRA     C
                                RAL     ;CY=B7(+)+C7
                                JC      SUM1
                                CALL   ADD3
                                MOV     A,B
                                0040' 78
                                0041' A9
                                0042' 17
                                0043' DA 0062'
                                0046' CD 0066'
                                0049' 78
                                004A' D2 004F'
                                004D' C6 80
                                004F' 17
                                0050' D0
                                0051' 79
                                0052' 17
                                0053' DA 005C'
                                0056' 21 FFFF
                                0059' 06 7F
                                005B' C9
                                005C' 21 0000
                                005F' 06 80
                                0061' C9
                                0062' CD 0066'
                                0065' C9
                                SUM2: RAL     ;CY= 0VF=B7(+)+CY
                                RNC     ;rezultat corect in BHL
                                MOV     A,C
                                RAL     ;CY=sgn{CDE}
                                JC      SUM3
                                LXI    H,0FFFFH ;limitare superioara
                                MVI    B,7FH
                                RET
                                SUM3: LXI    H,0 ;limitare inferioara
                                MVI    B,80H
                                RET
                                SUM1: CALL   ADD3 ;nu poate aparea deasire
                                RET

                                ;
                                ;ADD3 adunare 3o + 3o = 3o
                                ;       BHL + CDE -> BHL
                                ;       modifica A,F
                                ;       pastreaza CDE
                                ADD3: DAD     D
                                MOV     A,B
                                ADC     C
                                MOV     B,A
                                RET

                                ;
                                ;ROT3R rotire dreapta 3o(C2)
                                ;       CDE/2 -> CDE
                                ;       NU distruge BHL
                                ROT3R: XRA     A ;CY=0

```



```

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006C'  79                MOV    A,C
006D'  17                RAL
006E'  79                MOV    A,C
006F'  1F                RAR
0070'  4F                MCV   C,A
0071'  7A                MOV    A,D
0072'  1F                RAR
0073'  57                MOV    D,A
0074'  7B                MOV    A,E
0075'  1F                RAR
0076'  5F                MCV   E,A
0077'  C9                RET

;
;DIF2   scadere 2o
;                DE - HL -> DE
;
;                NU distruge B,C
DIF2:   CALL   CPL2
        DAD    D
        XCHG
        RET

;
;COMP2  comparare 2o
;                CY=1 daca DE < HL
;                modifica A,F
COMP2:  MOV    A,D
        CMP   H
        RNZ
        MOV   A,E
        CMP   L
        RET

;
;ROT3LV rotire stinga 3o(C2)
;                cu verificarea depasirii si limitare
;                2 * CDE -> CDE
ROT3LV: MOV    A,C
        ANI   C00H    ;1100 0000 B
        JPO   DEP
        XCHG
        DAD   H
        XCHG
        MOV   A,C
        RAL
        MOV   C,A
        RET
DEP:    RAL                ;CY=1 daca CDE<0
        JC   DEPINF
        LXI  D,0FFFFH
        MVI  C,7FH    ;depasire superioara
        RET
DEPINF: LXI  D,C
        MVI  C,80H    ;depasire inferioara
        RET
        END

```

Macros:

Symbols:

0066I'	ADD3	0040I'	ADD3V	007EI'	COMP2
0038I'	CPL2	0023I'	CPL3	009I'	DEF
009B'	DEPINF	0078I'	DIF2	0011'	LOOP
000B'	MODUL	0000I'	MUL12	0033I'	MUL12M
001D'	NEXT	0084I'	ROT3LV	006BI'	ROT3R
0062'	SUM1	004F'	SUM2	005C'	SUM3

No Fatal error(s)

ANEXA AS

PROGRAMUL DE IMPLEMENTARE CONCRETA A PROCEDURII
DE UTILIZARE A ALGORITMELOR DE REGLARE NUMERICA
IN MOD COMBINAT

1. Algoritm de reglare numeric, clasic PI
2. Combinatia algoritmilor ARMA-1 si ARS-PI
3. Combinatia algoritmilor ARMA-2 si ARS-PI

```

NAME ('ARMPI')
;
;algorithm de reglarea PI
;
;
PUBLIC ARMPI
EXT TK,WK,UK,US
EXT TK1,T4K,T4K1,TK1
EXT MUL12,CPL3,MUL121,CPL2,ADD3V,ADD3
EXT ROT3R,DLP2,COMP2,ROT3LV
;
0000' DSEG
0000' WK1: DS 2
;
0002' CSEG
0000' 2A 0000* ARMPI: LLD TK
0003' EB XCHG
0004' 0E 00 MVI C,0
0006' 2A 0000* LLD TK1
0009' 06 00 MVI B,0
000B' D5 PUSH D
000C' CD 0000* CALL CPL3
000F' D1 POP D
0010' CD 0000* CALL ADD3
0013' 22 0000* SHLD T4K ;DF=theta1(k)=theta1(k)-
; -theta1(k-1)
;
0016' E5 PUSH H
0017' 44 MOV B,H
0018' 65 MOV H,L
0019' 2E 00 MVI L,0 ;BHL=256*theta1(k)
001B' 4C MOV C,E
001C' 54 MOV D,H
001D' 5D MOV E,L
001E' CD 0000* CALL ROT3R ;CFE=28*theta1(k)
0021' CD 0000* CALL ADD3 ;FHL=(256+128)*theta1(k)
0024' E3 XTHL ;HL=theta1(k)
0025' C5 PUSH B
0026' EB XCHG
0027' 0E 11 MVI C,17
0029' CD 0000* CALL MUL12 ;BHL=17*theta1(k)
002C' D1 POP D
002D' 4A MOV C,D
002E' D1 POP D
002F' CD 0000* CALL ADD3
0032' CD 0000* CALL CPL3 ;BHL=-401*theta1(k)
;
0035' EB XCHG
0036' 2A 0000* LLD TK1
0039' EB XCHG
003A' D5 PUSH D
003B' 4A MOV C,D
003C' 53 MOV D,E
003D' 1E 00 MVI E,0 ;CDE=256*theta1(k-1)
003F' CD 0000* CALL ADD3V
0042' E3 XTHL

```

2

```

0043' C5          PUSH      B
0044' EB          XCHG
0045' OE 5E       MVI        C,94
0047' CD 0000*   CALL      MUL12  ;BHL=94*theta1(k-1)
004A' D1          POP       D
004B' 4A         MOV       C,D
004C' D1          POP       D
004D' CD 0000*   CALL      ADD3V  ;BHL=-40*theta1(k)+
                  ; +350*theta1(k-1)

;
0050' E5          PUSH      H
0051' C5          PUSH      B
0052' 2A 0000*   LHLD     WK
0055' EB          XCHG
0056' OE 1A       MVI        C,26
0058' CD 0000*   CALL      MUL12M ;BHL=26*w(k)
005B' D1          POP       D
005C' 4A         MOV       C,D
005D' D1          POP       D
005E' CD 0000*   CALL      ADD3V  ;BHL=-40*theta1(k)+
                  ; +350*theta1(k-1)+26*w(k)

;
0061' E5          PUSH      H
0062' C5          PUSH      B
0063' 2A 0000*   LHLD     WK1
0066' EB          XCHG
0067' OE 18       MVI        C,24
0069' CD 0000*   CALL      MUL12M ;BHL=24*w(k-1)
006C' CD 0000*   CALL      CPL3   ;BHL=-24*w(k-1)
006E' D1          POP       D
0070' 4A         MOV       C,D
0071' D1          POP       D
0072' CD 0000*   CALL      ADD3V  ;BHL=-40*theta1(k)+
                  ; +350*theta1(k-1)+26*w(k)-
                  ; -24*w(k-1)

;
0075' E5          PUSH      H
0076' C5          PUSH      B
0077' 2A 0000*   LHLD     TK1
007A' EB          XCHG
007B' OE 02       MVI        C,2
007D' CD 0000*   CALL      MUL12M ;BHL=2*theta(k-1)
0080' CD 0000*   CALL      CPL3   ;BHL=-2*theta(k-1)
0083' D1          POP       D
0084' 4A         MOV       C,D
0085' D1          POP       D
0086' CD 0000*   CALL      ADD3V  ;BHL=-40*theta1(k)+
                  ; +350*theta1(k-1)+26*w(k)-
                  ; -24*w(k-1)-2*theta(k-1)

;
0089' E5          PUSH      H
008A' C5          PUSH      B          ;sum->stiva
008B' 2A 0000*   LHLD     UK
008E' 06 00       MVI        B,0    ;BHL=!u(k)!
0090' 3A 0000*   LDA      US
0093' B7         ORA      A
0094' C4 0000*   CPL     B        ;BHL=u(k)
0097' D1          POP       D

```

3

```

0093' 4A
0099' D1
009A' CD 0000*

                                MOV    C,D
                                POP    D
                                CALL   ADD3V
                                ;CDE=suna
                                ;BHL= 40!*theta1(k)+
                                ; +350*theta1(k-1)+26*w(k)-
                                ; -24*w(k-1)-2*theta(k-1)+
                                ; +u(k-1)=u(k)

009D' 22 0000*
00A0' 78
00A1' 32 0002*

                                SHLD  UK1
                                MOV   A,B
                                STA   UK1+2 ;u(k-1) <- u(k)

                                ;

00A4' 17
00A5' 3E 00
00A7' 17
00A8' 32 0000*
00AB' 1F
00AC' DC 0000*
00AF' 78
00B0' 17
00B1' CA 00B7'
00B4' 21 FFFF
00B7' 22 0000*

                                RAL
                                MVI   A,0
                                RAL
                                STA   US ;semi
                                RAR
                                CC    CPL3 ;BHL=!u(k)!
                                MOV   A,B
                                ORA   A
                                JZ    ARM1
                                LXI   H,0FFFFH ;limitare
                                ARM1: SHLD UK

                                ;

00BA' 2A 0000*
00BD' 22 0000H
00C0' 2A 0000*
00C3' 22 0000*
00C6' 2A 0000*
00C9' 22 0000*
00CC' 09

                                SHLD  UK
                                SHLD  UK1 ;w(k-1) <- w(k)
                                SHLD  TK
                                SHLD  TK1 ;theta(k-1) <- theta(k)
                                SHLD  TK
                                SHLD  TK1 ;theta1(k-1) <- theta1(k)
                                RST
                                END

```

Macros:

Symbols:

0030*	ADD3	0093*	ADD3V	0000I'	ARNP1
00B7'	ARP1	0000*	COMP2	0000*	CPL2
00AD*	CTL3	0000*	DIF2	0048*	MIL12
007B*	MIL12M	0000*	RCT3LV	001F*	RAT3R
0007*	T1K	000A*	T1K1	0001*	TK
0004*	TK1	0018*	UK	00A2*	UK1
00A9*	US	002B*	UK	0000"	UK1

No Fatal error(s)

```

NAME ('ARNC1')
;
;algorithm combinat ARMA1 + ARN-PI
;-----
;
PUBLIC ARNC1,PRAG
EXT ARMA1,ARNPI
EXT TK,WK,UK,US
EXT TK1,UK1,VK2T,T1K1,T2K1,WK1
EXT MUL12,CPL3,MUL12M,CPL2,ADD3V,ADD3
EXT ROT3R,DIF2,COMP2,ROT3LV
;variabile
DSEG
FLAG: DS 1 ;fanion comutare
; (0:ARMA; 1:ARNPI)
;parametri
PRAG: DI 200
;program
CSEG
ARNC1: LHL D TK
XCHG
LHL D WK
CALL COMP2
JNC ARN13
XCHG
ARN13: CALL DIF2 ;DE=!e(k)!
LHL D PRAG
CALL COMP2 ;CY=1 daca !e(k)! < PRAG
LDA FLAG
RAL ;A=00 sau 01 daca se
;pastreaza tipul alg.
;A=10 sau 01 daca se
;scriba tipul alg.
;pozitioneaza fanionul F
ADI 0
JPO CHANGE
RAR ;CY=1 pentru ARNPI
JC ARNPI
JMP ARMA1
CHANGE: RAR
CMA
ANI 1
STA FLAG
CHPI CHPI
LXI H,0 ;comutare ARNPI -> ARMA1
SHLD T1K1
SHLD VK2T
MOV A,H
STA VK2T+2
JMP ARMA1
CHPI: LHL D WK ;comutare ARMA1 -> ARNPI
SHLD WK1
JMP ARNPI
END
0000' DSEG
0000" FLAG: DS 1 ;fanion comutare
; (0:ARMA; 1:ARNPI)
0001" 00C8 ;parametri
PRAG: DI 200 ;program
0003" CSEG
0000' 2A 0000* ARNC1: LHL D TK
0003' EB XCHG
0004' 2A 0000* LHL D WK
0007' CD 0000* CALL COMP2
000A' D2 000E' JNC ARN13
000D' EB XCHG
000E' CD 0000* ARN13: CALL DIF2 ;DE=!e(k)!
0011' 2A 0001" LHL D PRAG
0014' CD 0000* CALL COMP2 ;CY=1 daca !e(k)! < PRAG
0017' 3A 0000" LDA FLAG
001A' 17 RAL ;A=00 sau 01 daca se
;pastreaza tipul alg.
;A=10 sau 01 daca se
;scriba tipul alg.
;pozitioneaza fanionul F
001B' C6 00 ADI 0
001D' E2 0027' JPO CHANGE
0020' 1F RAR ;CY=1 pentru ARNPI
0021' DA 0000* JC ARNPI
0024' C3 0000* JMP ARMA1
0027' 1F CHANGE: RAR
0028' 2F CMA
0029' E6 0 ANI 1
002B' 32 0000" STA FLAG
002F' C2 0041' CHPI
0031' 21 0000 LXI H,0 ;comutare ARNPI -> ARMA1
0034' 22 0000* SHLD T1K1
0037' 22 0000* SHLD VK2T
003A' 7C MOV A,H
003B' 32 0002* STA VK2T+2
003E' C3 0000* JMP ARMA1
0041' 2A 0000* CHPI: LHL D WK ;comutare ARMA1 -> ARNPI
0044' 22 0000* SHLD WK1
0047' C3 0000* JMP ARNPI
END

```




Macros:

Symbols:

0000*	ADD3	0000*	ADD3V	003F*	ARMA1
000E'	ARN13	0000I'	ARNC1	0048*	ARNPJ
0027'	CHANGE	0041'	CHPJ	0015*	COMP2
0000*	CPL2	0000*	CPL3	000F*	DIF2
0000"	FLAG	0000*	MUL' 2	0000*	MUL12M
0001I''	PRAG	0000*	ROT3LV	0000*	ROT3R
0035*	T1K1	0000*	T2K1	0001*	TK
0000*	TK1	0000*	UK	0000*	UK1
0000*	US	0030*	VK2T'	0042*	WK
0045*	WK1				

No Fatal error(s)

```

NAME ('ARNC2')
;
;algorithm combinat ARMA2 + ARN-PI
;-----
;
PUBLIC ARNC2
EXT PRAG
EXT ARMA2,ARNPI
EXT TK,WK,UK,US
EXT TK1,UK1,VK2T,T1K1,T2K1,WK1
EXT MUL12,CPL3,MUL12M,CPL2,ADD3V,ADD3
EXT ROT3R,DIF2,COMP2,ROT3LV
;variabile
DSEG
FLAG: DS 1 ;fanion comutare
; (0:ARMA; 1:ARNPI)
;program
CSEG
ARNC2: LHL D TK
XCHG
LHL D UK
CALL COMP2
JNC ARN23
XCHG
ARN23: CALL DIF2 ;DF=!e(k)!
LHL D PRAG
CALL COMP2 ;CY=1 daca !e(k)! < PRAG
LDA FLAG
RAL ;A=00 sau '1' daca se
;pastreaza tipul alg.
;A=10 sau 01 daca se
;schimba tipul alg.
;pozitioneaza fanionul P
ADI 0
JPO CHANG2
RAR ;CY=' pentru ARNPI
JC ARNPI
JMP ARMA2
CHANG2: RAR
CMA
ANI 1
STA FLAG
JNZ CHPI2
LXI H,0 ;comutare ARNPI -> ARMA-2
SHLD T1K1
SHLD T2K1
SHLD VK2T
MOV A,H
STA VK2T+2
JMP ARMA2
CHPI2: LHL D WK ;comutare ARMA-2 -> ARNPI
SHLD WK1
JMP ARNPI
END
0000'
0000"
0001"
0000' 2A 0000*
0003' EB
0004' 2A 0000*
0007' CD 0000*
000A' D2 000E'
000D' EB
000E' CD 0000*
0011' 2A 0000*
0014' CD 0000*
0017' 3A 0000"
001A' 17
001B' C6 00
001D' E2 0027'
0020' 1F
0021' DA 0000*
0024' C3 0000*
0027' 1F
0028' 2F
0029' E6 01
002B' 32 0000"
002E' C2 0044'
0031' 21 0000
0034' 22 0000*
0037' 22 0000*
003A' 22 0000*
003D' 7C
003E' 32 0002*
0041' C3 0000*
0044' 2A 0000*
0047' 22 0000*
004A' C3 0000*

```



Macros:

Symbols:

0000*	ADD3	0000*	ADD3V	0042*	ARMA2
000E'	ARN23	0000I'	ARNC2	004B*	ARNPI
0027'	CHANG2	0044'	CHPI2	0015*	COMP2
0000*	CPL2	0000*	CPL3	000F*	DIF2
0000"	FLAG	0000*	MUL12	0000*	MUL12M
0012*	FRAG	0000*	ROT3LV	0000*	ROT3R
0035*	T1K1	0038*	T2K1	0001*	TK
0000*	TK1	0000*	UK	0000*	UK1
0000*	US	003F*	VK2T'	0045*	WK
004S*	WK1				

No Fatal error(s)

ANEXA A9

PROGRAMUL TEST
DE IMPLEMENTARE SI TESTARE PE MODEL EXPERIMENTAL
A ALGORITMILOR DE REGLARE NUMERICA CLASICE
SI MODAL ALUNECATOARE

1. Algoritm de reglare numeric, clasic PI
2. Combinatia algoritmilor ARMA-1 si ARN-PI
3. Combinatia algoritmilor ARMA-2 si ARN-PI

```

;
;programul de testare
;-----
;
PUBLIC TEST,ARNT,ARNC
EXT ETR,ARMA1,ARMA2,ARNPI,ARNC1,ARNC2
EXT K1,K2,K3,K4,PRAG
EXT TK,WK,WK,US,START,T1K,COMP2
EXT CPL2,DIF2

;rutinele de monitor
4429 IN8 EQU 4429H ;DAF -> B(ASCII)
4437 OUT8 EQU 4437H ;A(ASCII) -> DAF
4534 ADEC EQU 4534H ;conversie sir cifre
;zecimale(ASCII) -> HL(hexa)
4441 CRLF EQU 4441H ;<CR>,<LF> -> DAF
4584 DOUT EQU 4584H ;A(hexa) -> DAF(zecimal)
450C BIN1 EQU 450CH ;A low (hexa) -> A(ASCII)

;date
0000' DSEG
0000" TABW: DS 400H ;tabel w
0400" TABUP: DS 400H ;tabel up
0800" TABT: DS 400H ;tabel theta
0C00" TABO: DS 400H ;tabel omega
1000" TABU: DS 400H ;tabel u

;
1400" 0000* TABCON: DW ARMA1 ;tabel adrese subr.ARN
1402" 0000* DW ARMA2
1404" 0000* DW ARNPI
1406" 0000* DW ARNC1
1408" 0000* DW ARNC2
140A" DS 8 ;pentru extinderi ulterioare

;
1412" ADNR: DS 5 ;buffer caractere receptionate
1417" MEM1: DS 2
1419" MEM2: DS 2
141B" MEM3: DS 2
141D" MEM4: DS 2
141F" MEM5: DS 2 ;locatii temporare
1421" ACON: DS 3 ;conversie hexa -> zecimal
1424" SOYM: DS 1
1425" SOYN: DS 1
1426" GRAFX: DS 1 ;variabile pentru GRAF
1427" MOD: DS 1 ;mod rulare
1428" SENSP: DS 1 ;sens perturbatie
1429" K5: DS 1 ;tip ARN
142A" STAB: DS 1 ;pointer tabele
PAGE

```

```

;
;mesaje
M1:      DB      'REGIM DE RULARE',ODH
142B"    52 45 47 49
142F"    4D 20 44 45
1433"    20 52 55 4C
1437"    41 52 45 0D
143B"    20 20 20 20
143F"    41 3A 20 41
1443"    43 4F 52 44
1447"    41 52 45 20
144B"    41 4C 47 4F
144F"    52 49 54 4D
1453"    49 0D
1455"    20 20 20 20
1459"    44 3A 20 45
145D"    58 45 43 55
1461"    54 49 45 20
1465"    43 55 20 50
1469"    52 45 53 43
146D"    52 49 45 52
1471"    45 20 44 45
1475"    20 4C 41 20
1479"    44 41 46 0D
147D"    20 20 20 20
1481"    54 3A 20 45
1485"    58 45 43 55
1489"    54 49 45 20
148D"    49 4F 20 52
1491"    45 47 49 4D
1495"    20 44 45 20
1499"    54 45 53 54
149D"    41 52 45 0D
14A1"    20 20 20 20
14A5"    51 3A 20 54
14A9"    45 52 4D 49
14AD"    4F 41 52 45
14B1"    20 50 52 4F
14B5"    47 52 41 4D
14B9"    3B
14BA"    4F 50 45 52
14BE"    41 54 49 49
14C2"    20 50 45 4E
14C6"    54 52 55 20
14CA"    54 45 53 54
14CE"    41 52 45 0D
14D2"    20 20 20 20
14D6"    47 3A 20 47
14DA"    45 4E 45 52
14DE"    41 52 45 20
14E2"    54 41 42 45
14E6"    4C 45 0D
14E9"    20 20 20 20
14ED"    45 3A 20 45
14F1"    58 45 43 55
M2:      DB      'OPERATII PENTRU TESTARE',ODH
          DB      '      A: ACORDARE ALGORITMI',ODH
          DB      '      D: EXECUTIE CU PRESCRIERE DE LA I
          DB      '      T: EXECUTIE IN REGIM DE TESTARE'
          DB      '      Q: TERMINARE PROGRAM;'
          DB      '      G: GENERARE TABELE',ODH
          DB      '      E: EXECUTIE ALGORITMI',ODH

```

14F5"	54 49 45 20		
14F9"	41 4C 47 4F		
14FD"	52 49 54 4D		
1501"	49 OD		
1503"	20 20 20 20	DB	' A: AFISARE TABELE',ODH
1507"	41 3A 20 41		
150B"	46 49 53 41		
150F"	52 45 20 54		
1513"	41 42 45 4C		
1517"	45 OD		
1519"	20 20 20 20	DB	' Q: IESIRE DIN MENUU;'
151D"	51 3A 20 49		
1521"	45 53 49 52		
1525"	45 20 44 49		
1529"	4E 20 4D 45		
152D"	4E 49 55 3B		
1531"	47 45 4E 45	M3: DB	'GENERARE TABELE',ODH
1535"	52 41 52 45		
1539"	20 54 41 42		
153D"	45 4C 45 OD		
1541"	20 20 20 20	DB	' W: REFERINTA POZITIE',ODH
1545"	57 3A 20 52		
1549"	45 46 45 52		
154D"	49 4E 54 41		
1551"	20 50 4F 5A		
1555"	49 54 49 45		
1559"	OD		
155A"	20 20 20 20	DB	' P: PERTURBATIE',ODH
155E"	50 3A 20 50		
1562"	45 52 54 55		
1566"	52 42 41 54		
156A"	49 45 OD		
156D"	20 20 20 20	DB	' Q: IESIRE DIN MENUU;'
1571"	51 3A 20 49		
1575"	45 53 49 52		
1579"	45 20 44 49		
157D"	4E 20 4D 45		
1581"	4E 49 55 3B		
1585"	41 46 49 53	M4: DB	'AFISARE TABELE',ODH
1589"	41 52 45 20		
158D"	54 41 42 45		
1591"	4C 45 OD		
1594"	20 20 20 20	DB	' W: REFERINTA POZITIE',ODH
1598"	57 3A 20 52		
159C"	45 46 45 52		
15A0"	49 4E 54 41		
15A4"	20 50 4F 5A		
15A8"	49 54 49 45		
15AC"	OD		
15AD"	20 20 20 20	DB	' P: PERTURBATIE',ODH
15B1"	50 3A 20 50		
15B5"	45 52 54 55		
15B9"	52 42 41 54		
15BD"	49 45 OD		
15C0"	20 20 20 20	DB	' T: POZITIE',ODH
15C4"	54 3A 20 50		

1508"	4F 5A 49 54			
150C"	49 45 0D			
150F"	20 20 20 20	DE	'	O: VITEZA',ODH
15D3"	4F 3A 20 56			
15D7"	49 54 45 5A			
15DB"	41 0D			
15DD"	20 20 20 20	DE	'	U: COMANDA',ODH
15E1"	55 3A 20 43			
15E5"	4F 4D 41 4E			
15E9"	44 41 0D			
15EC"	20 20 20 20	DE	'	Q: IESIRE DIN MENU;',
15FO"	51 3A 20 49			
15F4"	45 53 49 52			
15F5"	45 20 44 49			
15FC"	4E 20 4D 45			
1600"	4E 49 55 3B			
1604"	50 45 52 54	M5:	DE	'PERTURBATIE',ODH
1608"	55 52 42 41			
160C"	54 49 45 0D			
1610"	20 20 20 20	DE	'	P: IN SENS POZITIV',ODH
1614"	50 3A 20 49			
1618"	4E 20 53 45			
161C"	4E 53 20 50			
1620"	4F 5A 49 54			
1624"	49 56 0D			
1627"	20 20 20 20	DE	'	N: IN SENS NEGATIV',ODH
162B"	4E 3A 20 49			
162F"	4E 20 53 45			
1633"	4E 53 20 4E			
1637"	45 47 41 54			
163B"	49 56 0D			
163E"	20 20 20 20	DE	'	A: IN ANEALIE SUNSURI;',
1642"	41 3A 20 49			
1646"	4E 20 41 4D			
164A"	42 45 4C 45			
164E"	20 53 45 4E			
1652"	53 55 52 49			
1656"	3B			
1657"	4B 31 3D 3E	M6:	DE	'K1=;',
165B"	4B 32 3D 3E	M7:	DE	'K2=;',
165F"	4B 33 3D 3E	M8:	DE	'K3=;',
1663"	4B 34 3D 3E	M9:	DE	'K4=;',
1667"	4B 35 3D 3E	M10:	DE	'K5=;',
166B"	46 4F 52 4D	M11:	DE	'FORMA',ODH
166F"	41 3A 0D			
1672"	20 20 20 20	DE	'	C: CONSTANTA',ODH
1676"	43 3A 20 43			
167A"	4F 4E 53 54			
167E"	41 4E 54 41			
1682"	0D			
1683"	20 20 20 20	DE	'	T: TREATA',ODH
1687"	54 3A 20 54			
168B"	52 45 41 50			
168F"	54 41 0D			
1692"	20 20 20 20	DE	'	R: RAMPA;',
1696"	52 3A 20 52			

169A"	41 4D 50 41			
169E"	3B			
169F"	56 41 4C 4F	M12:	DB	'VALOAREA=;'
16A3"	41 52 45 41			
16A7"	3D 3B			
16A9"	4E 52 2E 20	M13:	DB	'NR. CUANTEI IN CARE INCEPE TREAPTA =
16AD"	43 55 41 4E			
16B1"	54 45 49 20			
16B5"	49 4E 20 43			
16B9"	41 52 45 20			
16BD"	49 4E 43 45			
16C1"	50 45 20 54			
16C5"	52 45 41 50			
16C9"	54 41 20 3D			
16CD"	3E			
16CF"	4E 52 2E 20	M14:	DB	'NR. CUANTEI IN CARE INCEPE RAMPA =;'
16D2"	43 55 41 4E			
16D6"	54 45 49 20			
16DA"	49 4E 20 43			
16DE"	41 52 45 20			
16E2"	49 4E 43 45			
16E6"	50 45 20 52			
16EA"	41 4D 50 41			
16EE"	20 3D 3B			
16F1"	56 41 4C 4F	M15:	DB	'VALOAREA INITIALA =;'
16F5"	41 52 45 41			
16F9"	20 49 4E 49			
16FD"	54 49 41 4C			
1701"	41 20 3D 3B			
1705"	56 41 4C 4F	M16:	DB	'VALOAREA FINALA =;'
1709"	41 52 45 41			
170F"	20 46 49 4E			
1711"	41 4C 41 20			
1715"	3D 3E			
1717"	50 41 4E 54	M17:	DB	'PANTA RAMPEI =;'
171B"	41 20 52 41			
171F"	4D 50 45 49			
1723"	20 3D 3E			
1726"	4E 52 2E 20	M18:	DB	'NR. INTERVALE PE OY = 2**N',ODH
172A"	49 4E 54 45			
172E"	52 56 41 4C			
1732"	45 20 50 45			
1736"	20 4F 59 20			
173A"	3D 20 32 2A			
173E"	2A 4E 0D			
1741"	20 20 20 20		DB	' N =;'
1745"	4E 20 3D 3E			
1749"	41 46 49 53	M19:	DB	'AFISARE INTERVAL M',ODH
174D"	41 52 45 20			
1751"	49 4E 54 45			
1755"	52 56 41 4C			
1759"	20 4D 0D			
175C"	20 20 20 20		DB	' N =;'
1760"	4D 20 3D 3E			
1764"	41 46 49 53	M20:	DB	'AFISARE TABEL DIN K IN K VALORI',ODH
1768"	41 52 45 20			

1760" 54 41 42 45
1770" 4C 20 44 49
1774" 4E 20 4B 20
1778" 49 4E 20 4B
177C" 20 56 41 4C
1780" 4F 52 49 0D
1784" 20 20 20 20
1788" 4B 3D 3B
178B" 50 52 41 47
178F" 20 43 4F 4D
1793" 55 54 41 52
1797" 45 20 3D 3B

DB ' K=;'

M21: DB 'PRAG COMPUTARE =;'

PAGE

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;
;interpretorul de comenzi
179B"
0000' 3E 18
0002' CD 4437
0005' 3E 01
0007' CD 052F'
000A' CD 4429
000D' 78
000E' FE 41
0010' CA 0025'
0013' FE 44
0015' CA 0070'
0018' FE 54
001A' CA 0078'
001D' FE 51
001F' CA 430C
0022' C3 0000'
0025' 3F 06
0027' CD 052F'
002A' CD 0505'
002D' 22 0000*
0030' CD 4441
0033' 3E 07
0035' CD 052F'
0038' CD 0505'
003B' 22 0000*
003E' CD 4441
0041' 3E 08
0043' CD 052F'
0046' CD 0505'
0049' 22 0000*
004C' 3E 09
004E' CD 052F'
0051' CD 0505'
0054' 22 0000*
0057' 3E 0A
0059' CD 052F'
005C' CD 0505'
005F' 22 1429"
0062' 3E 15
0064' CD 052F'
0067' CD 0505'
006A' 22 0000*
006D' C3 0000'

                                CSEG
TEST: MVI    A,18H    ;<CLEAR>
       CALL  OUT8Q
       MVI    A,1
       CALL  MES
       CALL  INS
       MOV    A,B
       CPI    'A'
       JZ     M1A
       CPI    'D'
       JZ     M1D
       CPI    'T'
       JZ     M1T
       CPI    'Q'
       JZ     430CH
       JMP    TEST
M1A:  MVI    A,6     ;preluare K1 - K5
       CALL  MES
       CALL  PRNR
       SHLD  K1
       CALL  ORLF
       MVI    A,7
       CALL  MES
       CALL  PRNR
       SHLD  K2
       CALL  ORLF
       MVI    A,8
       CALL  MES
       CALL  PRNR
       SHLD  K3
       MVI    A,9
       CALL  MES
       CALL  PRNR
       SHLD  K4
       MVI    A,10
       CALL  MES
       CALL  PRNR
       SHLD  K5
       MVI    A,21
       CALL  MES
       CALL  PRNR
       SHLD  PRAG
       JMP    TEST

;
0070' 3E 00                    M1D: MVI    A,0     ;executie cu prescriere de
                                ;la DAF
0072' 32 1427"                STA    MOD
0075' C3 0000*                JMP    ETR

;
0078' 3E 01                    M1T: MVI    A,1     ;executie in regim de testare
007A' 32 1427"                STA    MOD
007D' 3E 18                    AM2: MVI    A,18H    ;<CLEAR>

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007F' CD 4437          CALL OUT8Q
0082' 3E 02           MVI A,2
0084' CD 052F'       CALL MES
0087' CD 4429          CALL IN8
008A' 78              MOV A,B
008B' FE 47           CPI 'G'
008D' CA 00A2'       JZ M2G
0090' FE 45           CPI 'E'
0092' CA 0150'       JZ EXE
0095' FE 41           CPI 'A'
0097' CA 0100'       JZ M2A
009A' FE 51           CPI 'Q'
009C' CA 0000'       JZ TEST
009F' C3 007D'       JMP AM2

;
00A2' 3E 18           M2G: MVI A,18H ;generare tabelle
00A4' CD 4437          CALL OUT8Q
00A7' 3E 03           MVI A,3
00A9' CD 052F'       CALL MES
00AC' CD 4429          CALL IN8
00AF' 78              MOV A,B
00B0' FE 57           CPI 'W'
00B2' CA 00C2'       JZ M3W
00B5' FE 50           CPI 'P'
00B7' CA 00C8'       JZ M3P
00BA' FE 51           CPI 'Q'
00BC' CA 007D'       JZ AM2
00BF' C3 00A2'       JMP M2G
00C2' 21 0000''      M3W: LXI H,TABW ;generare tabel w
00C5' C3 00FA'       JMP M5CAL
00C8' 3E 18           M3P: MVI A,18H ;generare tabel up
00CA' CD 4437          CALL OUT8Q
00CD' 3E 05           MVI A,5
00CF' CD 052F'       CALL MES
00D2' CD 4429          CALL IN8
00D5' 78              MOV A,B
00D6' FE 50           CPI 'P'
00D8' CA 00E8'       JZ M5P
00DB' FE 4E           CPI 'N'
00DD' CA 00ED'       JZ M5N
00E0' FE 41           CPI 'A'
00E2' CA 00F2'       JZ M5A
00E5' C3 00C8'       JMP M3P
00E8' 3E 00           M5P: MVI A,0
00EA' C3 00F4'       JMP M5CON
00ED' 3E 02           M5N: MVI A,2
00EF' C3 00F4'       JMP M5CON
00F2' 3E 01           M5A: MVI A,1
00F4' 32 1428''      M5CON: STA SENSP
00F7' 21 0400''      LXI H,TABUP
00FA' CD 0256'       M5CAL: CALL GTAR
00FD' C3 00A2'       JMP M2G

;
0100' 3E 18           M2A: MVI A,18H ;afisare tabelle
0102' CD 4437          CALL OUT8Q
0105' 3E 04           MVI A,4

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0107'  CD 052F'          CALL  RES
010A'  CD 4429          CALL  IN8
010D'  78              MOV   A,B
010E'  FE 57           CPI   'W'
0110'  CA 012F'       JZ    M4W
0113'  FE 50           CPI   'P'
0115'  CA 0135'       JZ    M4P
0118'  E 54           CPI   'T'
011A'  CA 013B'       JZ    M4T
011D'  FE 4F           CPI   'Q'
011F'  CA 0141'       JZ    M4O
0122'  FE 55           CPI   'U'
0124'  CA 0147'       JZ    M4U
0127'  FE 51           CPI   'Q'
0129'  CA 007D'       JZ    AM2
012C'  C3 0100'       JMP   M2A
012F'  21 0000"      M4W:  LXI  H,TAEW
0132'  C3 014A'       JMP   M4CON
0135'  21 0400"      M4P:  LXI  H,TAEUP
0138'  C3 014A'       JMP   M4CON
013B'  21 0800"      M4T:  LXI  H,TAET
013E'  C3 014A'       JMP   M4CON
0141'  21 0C00"      M4O:  LXI  H,TAEO
0144'  C3 014A'       JMP   M4CON
0147'  21 1000"      M4U:  LXI  H,TAEU
014A'  CD 04BC'      M4CON: CALL  APPAR
014D'  C3 0100'       JMP   M2A
;
;mulare in regim de testare
;
0150'  21 0000      EXE:  LXI  H,0
0153'  22 142A"    SHLD  STAB ;STAB <- 0
0156'  7C          MOV   A,H
0157'  32 0000*    STA  START ;START <- 0
015A'  C3 0000*    JMP  BTR
PAGE

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;
015D' 3A 1427"      ARNT: LDA      MOD      ;aici incepe segmentul
;                                     intercalat intre ETR si ARN
;                                     ;testare MOD
0160' B7            ORA      A
0161' CA 0246'     JZ       ARNC
0164' 3A 0000*     LDA      START
0167' B7            ORA      A      ;testare START
0168' CA 017C'     JZ       EXE1
016B' 2A 142A"     LHL D     STAB
016E' 23            INX      H
016F' 23            INX      H
0170' 22 142A"     SHLD     STAB      ;incrementare pointer tabele
0173' 11 0400      LXI      D,400H
0176' CD 0000*     CALL     COMP2      ;verificare limita
0179' DA 0234'     JC       EXE2      ;salt daca STAB>400H
017C' 21 0000"     EXE1: LXI      H,TABV      ;WK <- (TABW+STAB)
017F' EB            XCHG
0180' 2A 142A"     LHL D     STAB
0183' 19            DAD      D
0184' 7E            MOV      A,M
0185' 32 0000*     STA      WK
0188' 23            INX      H
0189' 7E            MOV      A,M
018A' 32 0001*     STA      WK+1
018D' 21 0400"     LXI      H,TABUP      ;simulare perturbatie
0190' EB            XCHG
0191' 2A 142A"     LHL D     STAB
0194' 19            DAD      D
0195' 5E            MOV      E,M
0196' 23            INX      H
0197' 56            MOV      D,M
0198' 3A 1428"     LDA      SENSF      ;DE = up
019B' B7            ORA      A
019C' CA 01A8'     JZ       SENS0
019F' 3D            DCR      A
01A0' CA 01D9'     JZ       SENS1
01A3' EB            XCHG
01A4' CD 0000*     CALL     CPL2
01A7' EB            XCHG      ;DE = --up
01A8' 2A 0000*     SENS0: LHL D     UK
01AB' 7A            MOV      A,D
01AC' 17            RAL
;CY=1 daca up<0
01AD' 3A 0000*     LDA      US      ;US=1 daca UK<C
01B0' 88            ADC      0
01E1' E6 01        ANI      1      ;A=1 daca up si UK au semne
;diferite

01B3' C2 01C0'     JNZ     SENSF
01B6' 19            DAD      D      ;HL=UK+up
01B7' D2 01E9'     JNC     SENSF
01BA' 21 9600      LXI      H,9600H      ;limitare superioara
01BD' C3 01E9'     JMP     SENSF
01C0' CD 0000*     SENSF: CALL     COMP2      ;CY=1 daca UK>up
01C3' DA 01D1'     JC       SENS1
01C6' EB            XCHG

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01C7' 3A 0000*          LDA    US
01CA' C6 01            ADI    1
01CC' E6 01            ANI    1          ;schimbare US
01CE' 32 0000*        STA    US
01D1' EB              SENS1: XCHG
01D2' CD 0000*        CALL  DIF2
01D5' EB              XCHG          ;HL= !UK-US!
01D6' C3 01E9'        JMP    SENSC
01D9' 2A 0000*        SENS1: LHLD  UK
01DC' EB              XCHG
01DD' CD 0000*        CALL  DIF2
01E0' EB              XCHG          ;HL=u(k)-up
01E1' 7C              MOV    A,H
01E2' 17              RAL
01E3' CA 01E9'        JZ     SENSC
01E6' 21 0000          LXI    B,0          ;limitare
01E9' 22 0000*        SENS1: SHLD  UK
01EC' CD 0246'        CALL  ARNC          ;apelare ARM
01EF' 21 0000"        LXI    H,TAB0
01F2' E3              XCHG
01F3' 2A 142A"        LHLD  STAB
01F6' 35              PUSH  H
01F7' 19              DAD   D          ;HL=adresa
01F8' E5              PUSH  H
01F9' 2A 0000*        LHLD  TAB
01FC' 11 8000          LXI    D,8000H
01FF' 19              DAD   D          ;HL=theta1(k)+8000H
0200' EF              XCHG
0201' E1              POP   H
0202' 73              MOV   M,E
0203' 23              INX   H
0204' 72              MOV   M,D
0205' 21 1000"        LXI    H,TAB1
0208' D1              POP   D          ;DE=STAB
0209' D5              PUSH  D
020A' 19              DAD   D          ;HL=adresa
020B' E5              PUSH  H
020C' 2A 0000*        LHLD  UK          ;HL=!u(k)!
020F' B7              ORA   A          ;CY=0
0210' 7C              MOV   A,H
0211' 1F              RAR
0212' 67              MOV   H,A
0213' 7D              MOV   A,L
0214' 1F              RAR
0215' 6F              MOV   L,A          ;HL=!u(k)!/2
0216' 3A 0000*        LDA   US
0219' B7              ORA   A
021A' C4 0000*        CHZ  CPL2          ;HL=u(k)/2
021E' 11 8000          LXI    D,8000H
0220' 19              DAD   D
0221' EB              XCHG          ;DE=8000H+u(k)/2
0222' E1              POP   H
0223' 73              MOV   M,E
0224' 23              INX   H
0225' 72              MOV   M,D
0226' 21 0800"        LXI    H,TAB2

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0229' D1 POP D
022A' 19 DAD D ;HL=adresa
022B' EB XCHG
022C' 2A 0000* LHLD TK
022F' EB XCHG
0230' 73 MOV M,R
0231' 23 INX H
0232' 72 MOV M,D
0233' C9 RET
0234' AF EXE2: XRA A
0235' D3 29 OUT 29H ;stop choopper
0237' 3E BF INI A,0BFH
0239' 32 20C9 STA 20C9H
023C' 3E 49 MVI A,49H
023E' 32 20CA STA 20CAH ;refacere adresa intr.timer
0241' 33 INX SP
0242' 33 INX SP ;refacere stiva
0243' C3 007D JMP AM2

;
;comutarea algoritailor
;
0246' 3A 1429" ARNC: LDA K5
0249' 57 ADD A
024A' 6F MOV L,A
024B' 26 00 MVI H,0
024D' 11 1400" LXI D,TABCON
0250' 19 DAD D ;HL=adresa din tabel
0251' 5B MOV E,M
0252' 23 INX H
0253' 56 MOV D,M
0254' EB XCHG ;HL=adresa subr. ARN
0255' 59 PCHL

;
PAGE

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;subrutina generare tabele
; intrare: HL=adresa de inceput a tabelului
0256' 22 1417'' GTAB: SHLD MEM1
0259' 3E 18 GTAB1: MVI A,18H ;<CLEAR>
025B' 0D 4437 CALL OUTSQ
025E' 3E 0B MVI A,11
0260' 0D 052F' CALL MBS
0263' 0D 4429 CALL INB ;preluare caracter
0266' 78 MOV A,B
0267' 0D 4437 CALL OUTSQ ;ecou
026A' 78 MOV A,B
026B' FE 43 CPI 'C'
026D' CA 027D' JZ GTC
0270' FE 54 CPI 'T'
0272' CA 029D' JZ GTT
0275' FE 52 CPI 'R'
0277' CA 02FA' JZ GTR
027A' C3 0259' JMP GTAB1
027D' 0D 4441 GTC: CALL CRLF
0280' 3E 0C MVI A,12
0282' 0D 04FB' CALL MBSROR
0285' 44 MOV B,H
0286' 4D MOV C,L ;BC=x1
0287' 2A 1417'' LHLD MEM1 ;N1
028A' 11 0400 LXI D,400H
028D' 3B XCHG
028E' 19 DAD D
028F' 2F DCX H
0290' 2B DCX H
0291' 3B XCHG ;DE=11+4000H-2
0292' 71 GTT1: MOV M,C
0293' 23 INX H
0294' 70 MOV M,B
0295' 23 INX H ;(HL) <- x1
0296' 0D 0000* CALL COMP2
0299' D2 0292' JNC GTC1
029C' 09 RET

;
029D' 0D 4441 GTT: CALL CRLF
02A0' 3E 0F MVI A,15
02A2' 0D 04FB' CALL MBSROR
02A5' 22 1419'' SHLD MEM4 ;x1
02A8' 3E 0D GTT1: MVI A,13
02AA' 0D 04FB' CALL MBSROR ;N/2 (nr. cuanta = adresa/2)
02AD' 7C MOV A,H
02AE' FE 02 CPI 2
02B0' D2 02A8' JNC GTT1 ;verificare HL<1FFFH
02B3' 2B DCX H
02B4' 2B DCX H
02B5' 22 141B'' SHLD MEM3 ;(N-1)/2
02B8' 3E 10 MVI A,16
02BA' 0D 04FB' CALL MBSROR
02BD' 22 141D'' SHLD MEM4 ;x2
02C0' 22 141B'' SHLD MEM3 ;(N-1)/2

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02C3' 29 DAD H ;nr. octeti din tabel=
; =2*nr. cuante
02C4' EB XCHG
02C5' 2A 1417" LHLD MEM1 ;N1
02C8' 19 DAD D ;HL=N1+N-1
02C9' 3B XCHG ;DE=N1+N-1
02CA' D5 PUSH D
02CB' 2A 1419" LHLD MEM2 ;x1
02CE' 44 MOV B,H
02CF' 4D MOV C,L ;BC=x1
02D0' 2A 1417" LHLD MEM1 ;N1
02D3' 71 GTT2: MOV M,C
02D4' 23 INX H
02D5' 70 MOV M,B
02D5' 23 INX H ;(HL) <- x1
02D7' CD 0000* CALL COMP2
02DA' D2 02D3' JNC GTT2
02DD' 2A 141D" LHLD MEM4 ;x2
02E0' 44 MOV B,H
02E1' 4D MOV C,L ;BC=x2
02E2' 2A 1417" LHLD MEM1
02E5' 11 0400 LXI D,400H
02E8' 19 DAD D
02E9' 2B DCX H
02EA' 2B DCX H
02EB' EB XCHG ;DE=N1+400H-2
02EC' E1 POP H
02ED' 23 INX H
02EE' 23 INX H ;HL=N1+N-2
02EF' 71 GTT3: MOV M,C
02F0' 23 INX H
02F1' 70 MOV M,B
02F2' 23 INX H ;(HL) <- x2
02F3' CD 0000* CALL COMP2
02F6' D2 02EF' JNC GTT3
02F9' C9 RET
;
02FA' CD 4441 GTR: CALL CRLF
02FD' 3E 0F MVI A,15
02FF' CD 04FB' CALL MEPRCR ;x1
0302' 22 1419" SHLD MEM2
0305' 3E 0E GTR1: MVI A,14
0307' CD 04FB' CALL MEPRCR
030A' 7C MOV A,H
030B' FE 02 CPI 2 ;verificare HL<200H
030D' D2 0305' JNC GTR1
0310' 2B DCX H
0311' 22 141B" SHLD MEM3 ;(N-1)/2
0314' 3E 11 MVI A,17
0316' CD 04FB' CALL MEPRCR
0319' 22 141D" SHLD MEM4 ;p
031C' 3E 10 MVI A,16
031E' CD 04FB' CALL MEPRCR
0321' 22 141B" SHLD MEM5 ;x2
0324' 2A 141B" LHLD MEM3 ;(H=1)/2
0327' 29 DAD H ;N-1

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0328' EB XCHG
0329' 2A 1417" LHL D MEM1 ;N1
032C' 19 DAD D
032D' 2B DCX H
032E' 2B DCX H
032F' 2B DCX H
0330' 2B DCX H
0331' EB XCHG ;DE=N1+N-4
0332' 2A 1419" LHL D MEM2 ;x1
0335' 44 MOV B,H
0336' 4D MOV C,L ;BC=x1
0337' 2A 1417" LHL D MEM1 ;HL=N1
033A' 71 GTR2: MOV M,C
033B' 23 INX H
033C' 70 MOV M,B
033D' 23 INX H ;(HL) <- x1
033E' CD 0000* CALL COMP2
0341' D2 033A' JNC GTR2
0344' E5 PUSH H ;HL=adresa primei locatii
;libere

0345' 2A 1417" LHL D MEM1
0348' 11 0400 LXI D,400H
034B' 19 DAD D
034C' 23 DCX H
034D' 2B DCX H
034E' EB XCHG ;DE=N1+400H-2
034F' E1 POP H
0350' 71 GTR3: MOV M,C
0351' 23 INX H
0352' 70 MOV M,B
0353' 23 INX H ;(HL) <- BC
0354' CD 0000* CALL COMP2
0357' D8 RC
0358' E5 PUSH H
0359' D5 PUSH D
035A' 2A 141F" LHL D MEM5 ;x2
035D' 50 MOV D,B
035E' 59 MOV E,C
035F' CD 0000* CALL COMP2
0362' D2 036B' JNC GTR4
0365' 2A 141D" LHL D MEM4 ;p
0368' 09 DAD B
0369' 44 MOV B,H
036A' 4D MOV C,L ;BC <- BC+p
036B' D1 GTR4: POP D
036C' E1 POP H
036D' C3 0350' JMP GTR3
;
;subrutinele pentru afisare
;
; intrari:DE = nr.cuantei
; HL = valoarea
; C = nr.blancuri pina la '*'
LIN: PUSH B
PUSH H
XCHG

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0373' CD 03CA' CALL AF2 ;afisare numar cuanta
0376' 3E 20 MVI A,' '
0378' CD 4437 CALL OUT8Q
037B' E1 POP H
037C' CD 03CA' CALL AF2 ;afisare valoare
037F' 3E 20 MVI A,' '
0381' CD 4437 CALL OUT8Q
0384' C1 LIN6: POP B
0385' 16 FF MVI D,OFFH
0387' 14 LIN1: INR D
0388' 7A MOV A,D
0389' FE 20 CPI 32
038B' CA 03B4' JZ LIN4 ;ultima coloana
038E' B9 CMP C
038F' CA 03A4' JZ LIN2 ;'*
0392' FE 00 CPI 0
0394' CA 03AC' JZ LIN3 ;'!'
0397' FE 10 CPI 16
0399' CA 03AC' JZ LIN3 ;'!'
039C' 3E 20 MVI A,' '
039E' CD 4437 CALL OUT8Q
03A1' C3 0387' JMP LIN1
03A4' 3E 2A LIN2: MVI A,'*'
03A6' CD 4437 CALL OUT8Q
03A9' C3 0387' JMP LIN1
03AC' 3E 21 LIN3: MVI A,'!'
03AE' CD 4437 CALL OUT8Q
03B1' C3 0387' JMP LIN1
03B4' B9 LIN4: CMP C
03B5' CA 03C1' JZ LIN5 ;'* si terminare
03B8' 3E 21 MVI A,'!'
03BA' CD 4437 CALL OUT8Q ;'!' si terminare
03BD' CD 4441 CALL CRLF
03C0' C9 RET
03C1' 3E 2A LIN5: MVI A,'*'
03C3' CD 4437 CALL OUT8Q
03C6' CD 4441 CALL CRLF
03C9' C9 RET
03CA' 11 2710 AF2: LXI D,10000 ;subrutina de afisare HL
03CD' CD 03EA' CALL AF21
03D0' 11 03E8 LXI D,1000
03D3' CD 03EA' CALL AF21
03D6' 11 0064 LXI D,100
03D9' CD 03EA' CALL AF21
03DC' 11 000A LXI D,10
03DF' CD 03EA' CALL AF21
03E2' 7D MOV A,L
03E3' CD 45CC CALL BIN1
03E6' CD 4437 CALL OUT8Q
03E9' C9 RET
03EA' 06 FF AF21: MVI B,OFFH
03EC' 04 AF22: INR B
03ED' 7D MOV A,L
03EE' 93 SUB B
03EF' 6F MOV L,A
03F0' 7C MOV A,H

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03F1' 9A          SBB     D
03F2' 67          MOV     H,A      ;HL ← HL-DE
03F3' D2 03EC'   JNC     AF22
03F6' 19          DAD     D      ;HL=HL+DE
03F7' 78          MOV     A,B
03F8' E5          PUSH    H
03F9' CD 45CC    CALL   BIN1
03FC' CD 4437    CALL   OUT8Q
03FF' E1          POP     H
0400' C9          RET

;
;subrutina scalare si stabilire origine pe Oy
;   intrari:HL:adresa unde se afla valoarea
;           de afisat
;           SOYM:M
;           SOYN:N
;   iesiri: C: nr. de blancuri
;           HL:valoarea (pentru afisat)
0401' 5E          SOY:  MOV     E,M
0402' 23          INX     H
0403' 56          MOV     D,M
0404' 23          INX     H      ;DE ← x (valoarea)
0405' D5          PUSH    D
0406' 21 2000    LXT     H,2000H ;HL=2^13
0409' 3A 1425''   LDA     SOYM
040C' E7          ORA     A      ;CY=0
040D' 4F          MOV     C,A
040E' CA 041C'   SOY1:  JL      SOY2
0411' B7          ORA     A
0412' 7C          MOV     A,H
0413' 1F          RAR
0414' 57          MOV     H,A
0415' 7D          MOV     A,L
0416' 1F          RAR
0417' 6F          MOV     L,A
0418' 0D          DCR     C
0419' C3 040E'   JMP     SOY1    ;HL=(2^13)/(2^N)
041C' 22 1417''   SOY2:  SHLD  MEM1
041F' EB          XCHG
;           ;HL=x
0420' 0E 03      NVI     C,3
0422' B7          SOY3:  ORA     A      ;CY=0
0423' 7C          MOV     A,H
0424' 1F          RAR

;
0425' 57          MOV     H,A
0426' 7D          MOV     A,L
0427' 1F          RAR
0428' 6F          MOV     L,A
0429' 0D          DCR     C
042A' C2 0422'   JNZ     SOY3    ;HL=x*2^(-3)
042D' 3A 1424''   LDA     SOYM
0430' 3D          DCR     A      ;A=M-1
0431' E5          PUSH    H
0432' 21 0000    LXT     H,0
0435' B7          ORA     A
0436' CA 043E'   SOY4:  JZ      SOY5
0439' 19          DAD     D

```

```

043A' 3D          DCR      A
043B' C3 0436'   JMP      SOY4      ;HL=(M-1)*2^13/2^N
043E' D1          POP      D          ;DE=x*2^(-3)
043F' CD 0000*   CALL    COMP2
0442' CA 0466'   JZ       SOY9
0445' DA 046B'   JC       SOY10    ;limitare inferioara
0448' CD 0000*   CALL    CPL2
044B' 19         DAD      D
044C' EB         XCHG    ;DE=x*2^(-3)-(M-1)*2^13/2^N
044D' 2A 1417''  LHL     MEM1
0450' CD 0000*   CALL    COMP2
0453' D2 046B'   JNC     SOY10    ;limitare superioara
0456' EB         XCHG
0457' 3A 1425''  LDA     SOYN
045A' B7         ORA     A
045B' CA 0463'   SOY6:   JZ       SOY7
045E' 29         DAD      H
045F' 3D         DCR      A
0460' C3 045B'   JMP      SOY6      ;HL=(2^N)*(x*2^(-3)-(M-1)*
; *2^13/2^N)

0463' 4C          SOY7:   MOV      C,H
0464' E1         POP      H
0465' C9         RET
0466' 26 00      SOY9:   MVI     H,0    ;'*' in prima coloana
0468' C3 0463'   JMP      SOY7
046B' 26 21      SOY10:  MVI     H,33    ;nu va afisa '*'
046D' C3 0463'   JMP      SOY7

;
;subrutina pentru trasarea graficului pentru 19 linii
;din tabel
;      intrari:HL:adresa de inceput a tabelului
;              DE:nr. de ordine al primei valori care
;              se afiseaza
;              GRAFX:din cite in cite valori se
;              afiseaza
0470' 3E 18      GRAF:   MVI     A,18H
0472' CD 4437   CALL    OUT8Q
0475' 42         MOV     B,D
0476' 4B         MOV     C,E      ;BC=nr. de ordine al primei
;              valori care se va afisa
0477' C5         PUSH    B
0478' 0E         DCX     B      ;sare peste (BC-1) valori
0479' 7E         MOV     A,B
047A' B1         ORA     C
047E' E5         PUSH    H
047C' CA 0467'   GRAF1:  JZ       GRAF2
047F' 23         INX     H
0480' 23         INX     H
0481' 0E         DCX     B
0482' 7E         MOV     A,B
0483' B1         ORA     C
0484' C3 047C'   GRAF1:  JMP      GRAF1
0487' E3         GRAF2:  XTHL    ;HL=adr. de inceput a tabelului
0488' 11 4000   LXI     D,4000H
048B' 19         DAD     D
048C' 2E         DCX     H

```

```

048D' EB XCHG ;DE=adresa sfirsit tabel
048E' E1 POP H ;HL=adr. primei valori de
;afisat
048F' C1 POP B
0490' 3E 12 MVI A,18
0492' 32 1419" STA MEM2
0495' CD 0000* GRAF3: CALL COMP2
0498' D8 RC ;termina afisarea daca se
;depaseste sfirsitul tabelului
0499' D5 PUSH D
049A' E5 PUSH H
049B' C5 PUSH B
049C' C5 PUSH B
049D' CD 0401' CALL SOY ;scalare
04A0' D1 POP D
04A1' CD 0370' CALL LIN ;trasare linie
04A4' C1 POP B
04A5' E1 POP H
04A6' D1 POP D
04A7' 3A 1426" LDA GRAFK ;sare K valori in tabel
04AA' 23 GRAF4: INX H
04AB' 23 INX H
04AC' 03 INX B
04AD' 3D DCR A
04AE' C2 04AA' JNZ GRAF4
04B1' 3A 1419" LDA MEM2 ;contor linii afisate
04B4' 3D DCR A
04B5' 32 1419" STA MEM2
04B8' C2 0495' JNZ GRAF3
04BB' C9 RET
;
;subrutina pentru afisarea graficului unui tabel
; intrari:HL:adresa de inceput a tabelului
; comenzi de la tastatura:
; C<nn..n>:afisare de la cuanta <nn..n>
; Q:iesire din regimul de afisare
04BC' E5 APPAR: PUSH H
04BD' 3E 12 MVI A,18
04BE' CD 04FB' CALL MEMPROR
04C2' 7D MOV A,L
04C3' 32 1425" STA SOYM
04C5' 3E 13 MVI A,19
04C8' CD 04FB' CALL MEMPROR
04CB' 7D MOV A,L
04CC' 32 1424" STA SOYM
04CF' 3E 14 MVI A,20
04D1' CD 04FB' CALL MEMPROR
04D4' 7D MOV A,L
04D5' 32 1426" STA GRAFK
04D8' 11 0001 LXI D,1
04DB' E1 AFIS1: POP H
04DC' E5 PUSH H
04DD' CD 0470' CALL GRAF
04E0' 3E 3F MVI A,'?'
04E2' CD 4437 CALL OUTOC
04E5' CD 4429 AFIS2: CALL IIS

```

```

04E8' FE 51          CPI      'Q'
04EA' CA 04E9'      JZ      AFIS6
04ED' FE 43          CPI      'C'
04EF' C2 04E5'      JNZ     AFIS2
04F2' CD 0505'      CALL    PRNR
04F5' EE            XCHG    ;HL=nr.primei linii
04F6' C3 04DB'      JMP     AFIS1
04F9' E1            AFIS6:  POP    H
04FA' C9            RET

;
;subrutine intrare/iesire
;
;subrutina afisare mesaj, preluare numar, <CR>
04FB' CD 052F'      MBRGR: CALL  MBS
04FE' CD 0505'      CALL    PRNR
0501' CD 4441      CALL    CRLF
0504' C9            RET

;
;preluare numar zecimal de la tastatura si conversie
;in hexa
;
;  iesire:HL:valoarea hexa
0505' 21 1412''    PRNR:  LXI    H,ADNR ;buffer caractere
0508' E5            PRNO:  PUSH   H
0509' CD 4429      PRM1:  CALL   IM6
050C' 76            MOV    A,B
050D' EE 0E        CPI    13 ;<CR>
050F' CA 0525'      JZ     PRN2
0512' FE 30        CPI    30H
0514' DA 0509'      JC     PRM1
0517' FE 3A        CPI    3AH
0519' D2 0509'      JNC   PRM1 ;testare caracter valid (cifra
051C' CD 4437      CALL   OUTSQ ;ecou
051F' E1            POP    H
0520' 70            MOV    M,B ;pune caracterul in buffer
0521' 23            INX    H
0522' C3 0508'      JMP    PRNO
0525' E1            PRN2:  POP    H
0526' 36 00        MVI    M,0 ;pune 0 in buffer
;                           ;(asa cere subrutina ADNR)
0528' 01 1412''    LXI    B,ADNR
052B' CD 4534      CALL   ADEC ;conversie sir ASCII -> nr.hex
052E' C9            RET

;
;subrutina afisare mesaje
;
;  intrare:A:nr. de ordine al mesajului
;  obs.:mesajele se termina cu ';'
052F' 21 142B''    MBS:   LXI    H,M1 ;adr. primului mesaj
0532' 3D            DCR    A
0533' B7            JPHES:  ORA    A ;sare peste N-1 mesaj
0534' 47            MOV    B,A
0535' CA 0544'      JZ     APHES
0538' 7E            JPM1:  MOV    A,M
0539' 23            INX    H
053A' FE 3B        CPI    ';'
053C' C2 0535'      JNZ   JPM1
053F' 78            MOV    A,B

```


0540'	3D		DCR	A	
0541'	C3 0533'		JMP	JPMES	
0544'	7E	AFMES:	MOV	A,M	;afiseaza mesajul
0545'	23		INX	H	
0546'	FE 3B		CPI	','	
0548'	C8		RZ		
0549'	CD 4437		CALL	OUT8Q	
054C'	C3 C544'		JMP	AFMES	
			BND		

Macros:

Symbols:

1421"	ACON	4534	ADEC	1412"	ADMR
03CA'	AF2	03EA'	AF21	03EC'	AF22
04DB'	AFIS1	04E5'	AFIS2	04F9'	AFIS6
0544'	AFMES	04BC'	APPAR	007D'	AM2
1400*	ARMA1	1402*	ARMA2	0246T'	ARNC
1406*	ARNC1	1408*	ARNC2	1404*	ARNPE
C15DI'	ARNT	450C	BIN1	0496*	COMP2
0449*	CPL2	4441	CRLF'	01DE*	DIF2
4584	DOUT	015B*	ETR	0150'	EXE
017C'	EXE1	0234'	EXE2	0470'	GRAF
047C'	GRAF1	0497'	GRAF2	0495'	GRAF3
04AA'	GRAF4	1426"	GRAFK	0256'	GTAB
0259'	GTAB1	027D'	GTC	0292'	GTC1
02FA'	GTR	0305'	GTR1	033A'	GTR2
0350'	GTR3	036B'	GTR4	029D'	GTT
02A8'	GTT1	02D3'	GTT2	02EF'	GTT3
4429	IN8	0538'	JPM1	0533'	JPMES
002E*	K1	003C*	K2	004A*	K3
0055*	K4	1429"	K5	0370'	LIN
0387'	LIN1	03A4'	LIN2	03AC'	LIN3
03B4'	LIN4	03C1'	LIN5	0384'	LIN6
142B"	M1	1667"	M10	166B"	M11
169F"	M12	16A9"	M13	16C3"	M14
16F1"	M15	1705"	M16	1717"	M17
1726"	M18	1749"	M19	0025'	M1A
0070'	M1D	0078'	M1T	14BA"	M2
1764"	M20	178B"	M21	0100'	M2A
00A2'	M2G	1531"	M3	00C8'	M3P
00C2'	M3W	1585"	M4	014A'	M4CON
0141'	M40	0135'	M4P	013B'	M4T
0147'	M4U	012F'	M4W	1604"	M5
00F2'	M5A	00FA'	M5CAL	00F4'	M5CON
00ED'	M5N	00E8'	M5P	1657"	M6
165B"	M7	165F"	M8	1663"	M9
1417"	MEM1	1419"	MEM2	141B"	MEM3
141D"	MEM4	141F"	MEM5	04FB'	MEPRCR
052F'	MES	1427"	MOD	4437	OUTSQ
006B*	PRAG	0508'	PRNO	0509'	PRN1
0525'	PRN2	0505'	PRNR	01A8'	SENSO
01D9'	SENS1	01E9'	SENSC	01C0'	SENSD
01D1'	SENSM	1428"	SENSP	0401'	SOY
040E'	SOY1	046E'	SOY10	041C'	SOY2
0422'	SOY3	0436'	SOY4	043F'	SOY5
045B'	SOY6	0463'	SOY7	0466'	SOY9
1424"	SOYM	1425"	SOYN	142A"	STAR
0165*	START	01FA*	T1K	1400"	TABCON
0C00"	TABO	0800"	TABT	1000"	TABU
0400"	TABUP	0000"	TAB	00C0I'	TEST
022D*	TK	020D*	UK	0217*	US
0183*	WK				

(No Fatal error(s))

• 11.00 •

ANEXA A10

REZULTATE EXPERIMENTALE OBTINUTE CU PROGRAMUL
TEST IMPLEMENTAT PE MODEL EXPERIMENTAL

• Aloci •

Rezultatele programului de TESTARE IN CADRUL

MODELULUI EXPERIMENTAL AL S.R.A.Pa

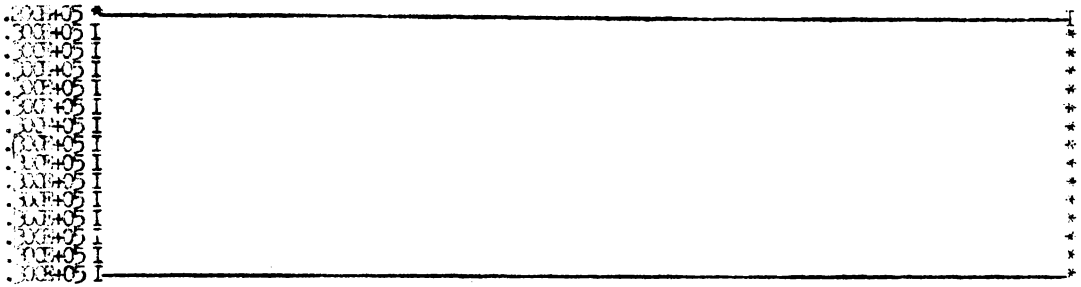
- perioade de esantionare : $T_e = 12.5$ msec
- referinta de pozitie : conform graficului V
- perturbatia simulata : $u_p = 0$

• A10.2 •

M T

MIN= 20000.0

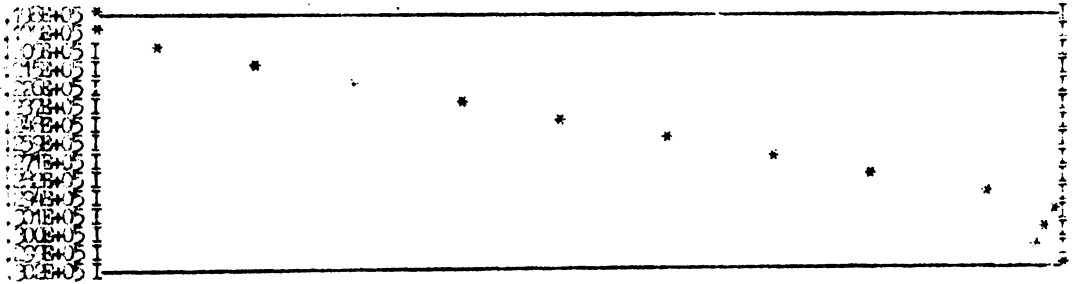
MAX= 30000.0



M T

MIN= 19300.0

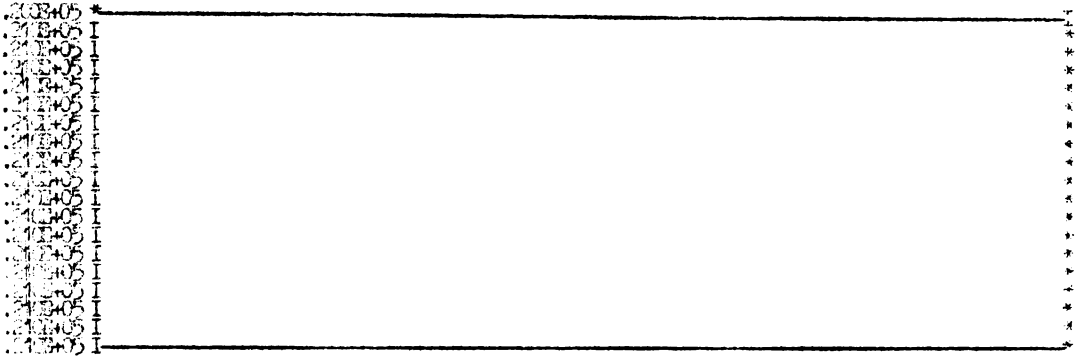
MAX= 30200.0



- 110.3 4

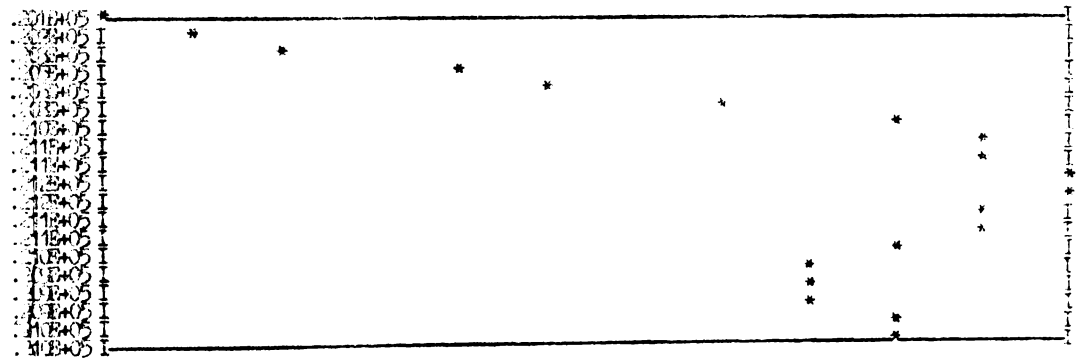
MIN= 2000.0

MAX= 2100.0



MIN= 2000.0

MAX= 2100.0



• All. e

ANEXA A11

PROGRAM DE VERIFICARE PE CALCULATOR A CORECTITINEI
DE IMPLEMENTARE IN LIMBAJ DE ASAMBLARE A
ALGORITMULUI ARMA-1

1. PROGRAMUL PRINCIPAL - IN LIMBAJ FORTRAN
 2. SUBPROGRAMUL ARMA-1 - IN LIMBAJ DE ASAMBLARE
-
1. Algoritm de rezolvare numeric, clasic PI
 2. Combinatia algoritmilor ARMA-1 si ARN-PI
 3. Combinatia algoritmilor ARMA-2 si ARN-PI

```

PROGRAM simulare
DIMENSION th(85),th1(85),s(85),u(85),v(85)
REAL k1
INTEGER TK,WK,UK,T1K
INTEGER K2,K3,K4
BYTE US

C
C parametri PCE
C
Te=12.5E-3
Ts=325.52E-9
Ta=1.8E-3
Tm=47.0E-3
A=0.457
d=0.1028

C
C coeficienti simulare PCE
C
div=8*Ta*Tm+4*Te*Tm+2*Te*Te
Beta1=(24*Ta*Tm+4*Te*Tm-2*Te*Te)/div
Beta2=(-24*Ta*Tm+4*Te*Tm+2*Te*Te)/div
Beta3=(8*Ta*Tm-4*Te*Tm+2*Te*Te)/div
Beta4=(A*Te**3)/div

C
C preluare treapta referinta
C
WRITE(3,103)
103 FORMAT(1X,'w=')
READ(1,102) w
102 FORMAT(F15.7)
WRITE(3,201)
201 FORMAT(1X,'K2=')
READ(1,204) K2
WRITE(3,202)
202 FORMAT(1X,'K3=')
READ(1,204) K3
WRITE(3,203)
203 FORMAT(1X,'K4=')
READ(1,204) K4
204 FORMAT(I6)
C
C initializari
C
DO 10 k=1,3
th(k)=0.
th1(k)=0.
u(k)=0
v(k)=0
10 CONTINUE

```



```

C
C calculo simulare
C
      DO 11 k=3,85
      WK=IFIX(w)
      TK=IFIX(th(k))
      CALL ARMA1(TK,WK,K2,K3,K4,UK,US,T1K)
      th1(k)=FLOAT(T1K)
      u(k)=FLOAT(UK)
      IF(u(k).LT.0) u(k)=32768+(32768+u(k))
      IF(US.EQ.1) u(k)=-u(k)
C
C model PCP-2
C
1005   th(k+1)=Beta1*th(k)+Beta2*th(k-1)+Beta3*th(k-2)
      th(k+1)=th(k+1)+Beta4*(u(k)+3*u(k-1)+3*u(k-2)+u(k-3))
1006   CONTINUE
C      WRITE(3,113) th(k),th1(k),u(k)
113    FORMAT(2X,3E15.7)
11     CONTINUE
      CALL grafic(th,'THETA')
      CALL grafic(th1,'OMEGA')
      CALL grafic(u,'U      ')
      END

```

```

C
SUBROUTINE grafic(vect,mes)
  EXTE line(100),mes(5)
  INTEGER tras
  REAL vect(85),ymin,ymax,deltay

C
  WRITE(3,114) mes
114  FORMAT(2X,5A1,1X,'TRASARE (0/1):')
  READ(3,115) tras
115  FORMAT(I2)
  IF(tras.NE.1) GOTO 1007

C
  WRITE(2,116) mes
116  FORMAT(2X,5A1,/)
  ymin=vect(1)
  ymax=vect(1)
  DO 12 i=3,85
    IF (vect(i).LT.ymin) ymin=vect(i)
    IF (vect(i).GT.ymax) ymax=vect(i)
12  CONTINUE
  WRITE(2,117) ymin,ymax
117  FORMAT (12X,'MIN=',G14.6,32X,'MAX=',G14.6,/)
  deltay=(ymax-ymin)/99.
  DO 14 i=3,85
    DO 13 j=1,100
      line(j)=' '
      IF((i.EQ.3).OR.(i.EQ.85)) line(j)='- '
      IF((j.EQ.1).OR.(j.EQ.100)) line(j)='I '
      IF(((ymin).GE.((j-1)*deltay)).AND.((-ymin).LT.(j*deltay)))
*      line(j)='I '
      IF(((vect(i)-ymin).GE.((j-1)*deltay))
*      .AND.((vect(i)-ymin).LT.(j*deltay)))
*      line(j)='*'
13  CONTINUE
  WRITE(2,118) vect(i),line
118  FORMAT (1X,G10.3,1X,100A1)
14  CONTINUE
1007 RETURN
  END

```

• ALL.4 •

```

;
;algorithm ARMA-1
;
PUBLIC ARMA1,K2,K3,K4
PUBLIC TK1,T1K1,UK1,VK2T,T1K
PUBLIC TK,TK,UK,US
PUBLIC ARND
EXT MUL12,CPL3,MUL121,CPL2,ADD3V,ADD3
EXT ROT3R,DEF2,COMP2,ROT3LV
0000'      TK:   DS      2
0002'      UK:   DS      2
0004'      US:   DS      2
0006'      UC:   DS      1
;variable
0007'      TK1:  DS      2      ;theta(k-1)
0009'      T1K:  DS      2      ;omega(k)
0008'      T1K1: DS      2      ;omega(k-1)
0005'      UK1:  DS      3      ;u(k-1)
0010'      VK2T: DS      3      ;v^(k-2)
0013'      K2:  DW      64      ;3.2*10
0015'      K3:  DW     4000     ;0.1*P
0017'      K4:  DW      10     ;-0.514*Q
;procedure
ARMA1:    MOV     A,M
0019'      7E          STA     TK
001A'      32 0000'   INX     H
001D'      23          MOV     A,M
001E'      7E          STA     TK+
001F'      32 0001'   XCHG
0022'      EB          MOV     A,M
0023'      7E          STA     UK
0024'      32 0002'   INX     H
0027'      23          MOV     A,M
0028'      7E          STA     UK+
0029'      32 0003'   XCHG
002C'      60          MOV     H,D
002D'      69          MOV     D,C
002E'      5B          INX     H,M
002F'      23          INX     H
0030'      56          MOV     D,H
0031'      23          INX     H
0032'      EB          XCHG
0033'      7E          MOV     A,M
0034'      32 0003'   STA     K2
0037'
0038'      23          INX     H
0039'      7E          MOV     A,M
0039'      32 0014'   STA     K2+
003C'      EB          XCHG
003D'      5E          MOV     E,H
003E'      23          INX     H
003F'      56          MOV     D,H
0040'      23          INX     H
0041'      EB          XCHG
0042'      7E          MOV     A,M
0043'      32 0005'   STA     T3
0046'      23          INX     H

```

```

0047' 7E          MOV     A,M
0048' 32 0016'   STA     K5+1
0049' EB          XCHG
004C' 5E          MOV     E,M
004D' 23          INX     H
004E' 56          MOV     D,M
004F' 23          INX     H
0050' EB          XCHG
0051' 7E          MOV     A,M
0052' 32 0017'   STA     K4
0055' 23          INX     H
0056' 7E          MOV     A,M
0057' 32 0013'   STA     K4+1
005A' D5          PUSH    D

;
005B' 2A 0000'   LHLD   TK
005E' EB          XCHG
005F' 2A 0007'   LHLD   TK1
0062' CD 0000*   CALL   DIF2      ;DE=omega(k)=theta(k)-
                  ; -theta(k-1)
0065' 2A 0000'   LHLD   TK
0068' 22 0007'   SHLD   TK1      ;theta(k-1) <- theta(k)
006B' EB          XCHG
006C' 22 0009'   SHLD   T1K
006F' EB          XCHG
0070' 2A 0003'   LHLD   T1K1
0073' CD 0000*   CALL   DIF2      ;DE=omega1(k)=omega(k)-
                  ; -omega(k-1)
0076' 2A 0009'   LHLD   T1K
0079' 22 0003'   SHLD   T1K1   ;omega(k-1) <- omega(k)
007C' 42          MOV     B,D
007D' 63          MOV     H,B
007E' 2E 00      MVI     E,0      ;EHL=omega1(k)*2^8
0080' 4A          MOV     C,D
0081' 53          MOV     D,E
0082' 5D          MOV     E,L      ;ODE=omega1(k)*2^8
0083' CD 0000*   CALL   ADD3V     ;EHL=omega1(k)*2^9
0086' CD 0000*   CALL   R1T3R     ;ODE=omega1(k)*2^7
0089' CD 0000*   CALL   ADD3V     ;EHL=omega(k)*(2^7+2^9)
008C' CD 0000*   CALL   CPL3      ;EHL=-omega(k)*(2^7+2^9)
008F' EB          XCHG
0090' 48          MOV     C,B      ;ODE=-omega(k)*(2^7+2^9)
0091' 2A 000D'   LHLD   UK1
0094' 3A 000F'   LDA     UK1+2
0097' 47          MOV     B,A      ;EHL=u(k-1)
0098' CD 0000*   CALL   ADD3V     ;EHL=v(k-1)
009B' EB          XCHG
009C' 48          MOV     C,B      ;ODE=v(k-1)
009D' 21 0000   LXI     H,0
00A0' 06 00      MVI     B,0      ;EHL=0
00A2' CD 0000*   CALL   R1T3R
00A5' CD 0000*   CALL   ADD3
00A8' CD 0000*   CALL   R1T3R
00AB' CD 0000*   CALL   R1T3R
00AE' CD 0000*   CALL   ADD3      ;EHL=v(k-1)*(2^7+2^9)
00B1' EB          XCHG

```

```

00B2' 2A 0010'      LHL D   VK2T
00B5' EB           XCHG
00B6' 3A 0012'      LDA     VK2T+2
00B9' 4F           MOV     C,A      ;ODE=v~(k-2)
00BA' CD 0000*     CALL   ROT3R
00BD' CD 0000*     CALL   ROT3R
00C0' CD 0000*     CALL   ADD3
00C3' CD 0000*     CALL   ROT3R
00C6' CD 0000*     CALL   ADD3      ;BHL=v~(k-1)
00C9' 22 0010'     SHLD   VK2T
00CC' 78           MOV     A,B
00CD' 32 0012'     STA     VK2T+2    ;v~(k-2) <- v~(k-1)
00D0' 2A 00C0'     LHL D   TK
00D3' EB           XCHG      ;DE=theta(k)
00D4' 2A 00D2'     LHL D   WK      ;HL=w(k)
00D7' CD 0000*     CALL   COMP2
00DA' D2 00DE'     JNC    ARN1      ;theta(k) > w(k)
00DD' EB           XCHG      ;face DB > HL
00DE' F5           PUSH   PSW      ;CY=1 due to e(k) < 0
00DF' CD 0000*     CALL   DIF2      ;DE= !e(k)!
00E2' 3A 0013'     LDA     K2
00E5' 4F           MOV     C,A
00E6' C7 0000*     CALL   MUL12     ;BHL=K2*!e(k)! > 0
00E9' 6C           MOV     L,H
00EA' 60           MOV     H,B
00EB' 06 00        MVI     B,0      ;DE=K2*!e(k)!*2^3
00ED' F1           POP     PSW      ;CY=1 due to e(k) < 0
00EE' DC 0000*     CC     CPL3      ;BHL=K2*e(k)*2^3
00F1' EB           XCHG
00F2' 48           MOV     C,B      ;ODE=K2*e(k)*2^3
00F3' 2A 00D9'     LHL D   TK      ;HL=omega(k)
00F6' 7C           MOV     A,H
00F7' 17           RAL     ;CY=1 due to HL < 0
00F8' 3E 00        MVI     A,0
00FA' D2 00FE'     JNC    ARN2
00FB' 2F           CMA
00FC' 47           MOV     B,A      ;BHL=omega(k)
00FD' CD 0000*     CALL   ADD3      ;BHL=s(k)
0102' 78           MOV     A,B
0103' 17           RAL     ;CY=1 due to s(k) < 0
0104' F5           PUSH   PSW
0105' 2A 0009'     LHL D   TK
0108' EB           XCHG      ;DE=omega(k)
0109' 3A 0017'     LDA     K4
010C' 4F           MOV     C,A
010D' CD 0000*     CALL   MUL12     ;BHL=K4*omega(k)
0110' CD 0000*     CALL   CPL3
0113' 5D           MOV     E,L
0114' 54           MOV     D,H
0115' 48           MOV     C,D      ;ODE=K4*omega(k)
0116' CD 0000*     CALL   ROT3LV
0119' CD 0000*     CALL   ROT3LV
011C' CD 0000*     CALL   ROT3LV
011F' CD 0000*     CALL   ROT3LV    ;ODE=K4*omega(k)*2^4
0122' 2A 0015'     LHL D   K3
0125' 06 00        MVI     B,0      ;BHL=K3

```

ALL.7

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```

0127' F1 POP PSW ;CY=1 daca s(k) < 0
0128' D5 PUSH D
0129' D4 0000* CNC CPL3 ;BHL=-K3*sgn{s(k)}
012C' D1 POP D
012D' CD 0000* CALL ADD3V ;BHL=omega1D(k)
;
; XCHG
; MOV C,B ;ODE=omega1D(k)
; L'LD VK2T
; LDA VK2T+2
; MOV B,A ;BHL=v~(k-2)
; CALL ADD3V ;DHL=u(k)
0130' 22 000D' C'LD UK1
0131' 78 MOV A,T
0134' 32 000F' STA UK1+2 ;v(k-1) <- u(k)
0137' 17 RAL
0138' 3B 00 MVI A,0
013A' 17 RAL ;A=1 daca u(k) < 0
013D' 32 0006' STA US
013E' 1F RAR
013F' DC 0000* CC CPL3 ;BHL=!u(k)!
0142' 78 MOV A,B
0143' 57 ORA A
0144' CA 014A' JC ARN3
0147' 24 FFFF LXI H,FFFF ;limitara superioara !u(k)!
014A' 22 0004' ARN3: SHLD UK
014D' F1 POP H
014E' 5D MOV B,M
014F' 23 INX H
0150' 56 MOV I,M
0151' 23 INX H
0152' EB XCHG
0153' 3A 0004' LDA UK
0156' 77 MOV M,A
0157' 23 INX H
0158' 3A 0005' LDA UK+1
015B' 77 MOV M,A
015C' EB XCHG
015D' 5F MOV B,M
015E' 23 INX H
015F' 56 MOV I,M
0160' 23 INX H
0161' EB XCHG
0162' 3A 0006' LDA US
0165' 77 MOV M,A
0166' EB XCHG
0167' 5E MOV B,M
0168' 23 INX H
0169' 56 MOV D,M
016A' 23 INX H
016B' EB XCHG
016C' 3A 0009' LDA TX
016F' 77 MOV M,A
0170' 23 INX H
0171' 3A 000A' LDA TX+
0174' 77 MOV M,A
0175' C9 RET

```

• ALLS •

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END

Macros:

Symbols:

0100*	ADD3	012E*	ADD3V	0019I'	ARM1
00DE'	ARM1	00FE'	ARM2	014AI'	ARM3
00D8*	COMP2	0000*	CPL2	0140*	CPL3
00E0*	DIF2	0013I'	K2	0015I'	K3
0017I'	K4	010E*	MIL12	0000*	MIL12S
0120*	RCT3LV	00C4*	R T3R	0009I'	T1K
000BI'	T1K1	0000I'	TK	0007I'	TK1
0004I'	UK	000DI'	UK1	0006I'	US
0010I'	VK2T	0002I'	WK		

No Fatal error(s)

4 112.0 2

ANEXA A12

REZULTATELE VERIFICĂRII PE CALCULATOR A SUBPROGRAMULUI
DE IMPLEMENTARE ÎN LIMBAJ DE ASAMBLARE A ALGORITMULUI
DE REGLARE AFNA - 1

Rezultatele programului de TESTARE PRIN SIMULARE
a subrutinei care implementeaza ARK

- algoritmul de reglare : tip ARMA - 1
 - cu compensarea perturbatiilor
 - si limitarea moduluii comenzii
 - 2 = 64
 - 3 = 5000
 - 4 = 10
- modelul procesului condus extins : PCE - 2
- perioada de esantionare : $T_e = 12.5$ msec
- referinta de pozitie : treapta cu amplitudinea $w = 500$
- perturbatia simulata : $u_p = 0$

