A CLASS OF OPTIMIZED ENCODER FOR BLOCK CODES

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Abstract : Error correcting codes are used broadly, in *particularapplications* such asin deep satellite communication and fault tolerant memory. In this papera new block code of (32, 19) optimised encoder is proposed. Compared with extended Golay code (24,12)the existing codesare capable of correcting three adjacent errors and detecting six errors. Optimization is achieved by an algorithm which finds the "Majority Message" bits (M). The proposed work is only on the encoder section of block and cyclic codes.As of now most of the work for error correcting codes are carried only on decoder section because of its complexity. A speed encoder is proposed which is not complex through the optimised algorithm. The delay in encoder is reduced thereby it contributes to the efficient error correcting code when considered with decoder section. The codes are programmed in HDL and synthesised using cadence tool of 180 nm library. The result on encoder with optimised new block code for delay, area and power which is at par to the cyclic code. For an increased number of message bits the proposed code is much efficient in correcting triple adjacent error.

Keywords : Optimised encoder, Golaycode, Encoder formation.

1. Introduction : The real idea of coding technique is to send out reliable data. In memories particularly main memory [1], much frequently occurring data's are stored due to scaling of transistors to a great extentrepeatedly subjected to highly ionised particles [2],[3], as result the content stored in main memory are flipped from previously stored value. This change in values from 0 to 1 else from 1 to 0 is called soft errors [4] [5]. More over spreading of error to adjacent

bits occur and that leads to multiple bit upset [6],[7].Viable and cost effective solution to fault secure memory is a must and this is achieved Error Correction Code(ECC) through [8].C.E.Shannon[17]proposed a method to correct error in a channel with noise as a mathematical model, Golay [16] proposed a mathematical outline for triple bit error correction in code word length of 23. Later R.W.Hamming[15] proposed a single bit error detection, single bit error correction and double bit error detection for computers. R.W.Hamming proposed the error detection method and C.E.Shannon proposed error correction technique. D.E.Muller suggested how to correct multiple bit error on a given code word and dealt "Code for Multiple Error". Next development of coding theory moved towards the decoding scheme of correcting multiple errors proposed by Irving S. Reed [18] based on D.E.Muller's "Code for Multiple Errors".

The major classifications of information theory areError Detection,Forward Error Correction (FEC)and Automatic Repeat reQuest (ARQ).Error detection codes are capable of only detection of error, forward error correction codes are capable of detecting and correcting errors, FEC are further sub classified as block codes formed by generation matrix (G) and parity matrix (H).Cyclic codes are formed by polynomials and convolutioncodes are built using trillisor code tree. In the case of ARQ, the codes transmit error control signals. The proposed work is on coding theory of block codes of size (n, k). The key aspect in block codes and cyclic codes are code rate efficiency, error detection and error correction capability. Code rate determines the available width of information or data compared to the number of parity given in a code word of size n. For any Error Correction Code (ECC) minimum distance (d_{min}) determines the error detection and correction capability. Based on d_{min}single [19], [20]double [9], [14]and a triple adjacent error occur. Among them, triple adjacent errors [10] are very much associated to burst errors and it can be corrected. In general, detection capability of ECC is higher when it is compared with correction. To increase the number of correction capability hamming bound condition should be satisfied. If the number of correction capability increases, parity bits increases which leads to the decrease in number of data bits in a code word. A class of SEC-DAED- TAEC of (31, 19) is found to be efficient in detection and correction capability[11], but this codes lags in satisfying the hamming bound which in turn contributes to the unreliable correction of TAEC. Even though the proposed work is not related with decoding, a new block code is introduced to satisfythe hamming bound condition and anoptimised encoder for the same.

Coded messages are much efficient and reliable than uncoded data. In this regard ECC is unavoidable. Encoders are very much essential for the generation of message or data bits with parity bit which is the first source for the formation of reliable data communication. An encoder for a block code is implemented using registers and mod 2 operations, for cyclic codes flip-flops with a minimum number of XOR function based on the polynomial is formed. An Encoder for cyclic codes such as Extended Golay [12], Bose ChaudhariHocquenghes[13], and Reed Solomon codes encoder are simple to design and implement. In the case of block codes, the encoders are simple to construct except if the length of the code increases the encoder delay

increases linearly. To fix this issue an algorithm is proposed to reduce the delay that occurs in the block codes even if the size increases. The proposed algorithm is suitable only for block codes if the size of the code increases the delay in an encoder.

2. Proposed work:

Mathematical approach for the (32, 19) block code formation is given below in the form of equations. Equation (1) to (4) is used for design of encoder, Equation (5) to (8) used to design decoder. As the proposed work is on encoder, decoder part of this block code is not explained. To get the code word 'X' generation matrix 'G' should be formed; this is a matrix formation of identity 'I' and coefficient'P' of size as shown in equation (2) and (3).where n is 32 and k is 19 bits. Encoded data is the combination of information or message 'm' and parity 'p'. Generation matrix is shown in Figure.1.

Encoder formation

$$G = \begin{bmatrix} P_{(k \ by n-k)} : I_k \end{bmatrix}$$

$$= mP_{(k \ by n-k)}$$

$$p = mP_{(k \ by n-k)}$$

$$= [p:m]$$

$$= --(4)$$

X = mG

Decoder formation

$$H = \begin{bmatrix} P^{T} : I_{n-k} \end{bmatrix}$$

----(5)
$$S = EH^{T}_{(n \ by \ n-k)}$$

----(6)
$$S = YH^{T}_{(n \ by \ n-k)}$$

----(7)
$$Y = X \oplus E$$

----(8)



Figure 1:Generation Matrix 'G'

3. Algorithm

- 1. Formation of generation matrix according to the specific size of block code.
- 2. Find the parity bits.
- 3. On information bits XOR operation should be performed which in turn is determined from coefficient of G matrix.
- 4. Find the majority message bits in every parity bit.
- 5. Majority message bits are grouped to a minimum of 3 bits.
- 6. Grouped majority message bits are represented by a constant variable.
- 7. Constant variables should be unlike
- 8. Grouped majority messages are replaced by constant variables.

As given in the algorithm the parity bits are formed from the coefficient of G matrix and message bits. In the proposed work grouping of minimum three majority message 'M' bits is done and it can even be beyond 3 grouping. In addition if the block size is increased the M grouping will be better. Grouped majority message bits should not be repeated or overlapped in other grouped message bits. Using the proposed algorithm the

parity bits are formed and shown below from equation (9) to (21). In equation (11) first grouping of majority message bits are highlighted by a dotted arrow towards right direction, and denoted by a constant variable M, similarly other grouping is shown under message grouping in Table.1. In the proposed case the grouped messages bits are of minimum three, other possibility of grouping are in two messages that are similar are found more in all the parity bit equation but not considered because computation time of two messages for XOR operation is much similar when represented as M bit or majority message bit in other parity equations. Table.1also shows the repeated grouping in other parity bits. In the case of equation (14) parity bit is p6 and it holds two majority message grouping M2 and M3. This grouping is repeated in other parity bits such asp7, p8 and p7, p8, p9, p13respectively. In the same equation previously grouped majority message is represented and recalled as constant variable M1.

 $p1 = m1 \oplus m6 \oplus m13 \oplus m15 \oplus m17$ ---(9) $p2 = m2 \oplus m6 \oplus m7 \oplus m14 \oplus m15 \oplus m17$ ---(10) $p3 = m3 \oplus m6 \oplus m7 \oplus m8 \oplus m13 \oplus m15 \oplus m18$

---(11)

 $p4 = m1 \oplus m4 \oplus M1 \oplus m9 \oplus m14 \oplus m16 \oplus m18$ ----(12)

 $p5 = m1 \oplus m2 \oplus m5 \oplus M1 \oplus m9 \oplus m10 \oplus m13 \oplus m16 \oplus m17 \oplus m19$ ---(13)

 $p6 = m1 \oplus m2 \oplus m3 \oplus M1 \oplus m9 \oplus m10 \oplus m11 \oplus m14 \oplus m16 \oplus m17$ ---(14)

 $p7 = M2 \oplus m4 \oplus m7 \oplus m8 \oplus M3 \oplus m12 \oplus m13 \oplus m15 \oplus m18 \oplus m19$ ---(15)

 $p8 = M2 \oplus m4 \oplus m5 \oplus m8 \oplus M3 \oplus m12 \oplus m14 \oplus m18 \oplus m19$ ---(16)

 $p9 = m2 \oplus m3 \oplus m4 \oplus m5 \oplus M3 \oplus m12 \oplus m13 \oplus m15 \oplus m17 \oplus m19$ ---(17)

 $p10 = M4 \oplus m10 \oplus m11 \oplus m12 \oplus m14 \oplus m16 \oplus m17 \oplus m19$ ----(18)

-----> M5 $p11 = m4 \oplus m5 \oplus m11 \oplus m12 \oplus m16 \oplus m18 \oplus m19$ ---(19) $p12 = m5 \oplus m12 \oplus m14 \oplus m16 \oplus m18$ ---(20) $p13 = m3 \oplus m5 \oplus m7 \oplus M3 \oplus m12 \oplus M5$

Pari	Message grouping	Repres	Repeated
ty		ented	grouping in
bits		in	other parity
		other	
		parity	
		bits	
<i>p</i> 3	$m6 \oplus m7 \oplus m8$	<i>M</i> 1	<i>p</i> 4, <i>p</i> 5, <i>p</i> 6
	$m1 \oplus m2 \oplus m3$	M 2	<i>p</i> 7, <i>p</i> 8
<i>p</i> 6	$m9 \oplus m10 \oplus m11$	М3	<i>p</i> 7, <i>p</i> 8, <i>p</i> 9, <i>p</i> 13
<i>p</i> 9	$m3 \oplus m4 \oplus m5$	<i>M</i> 4	<i>p</i> 10
<i>p</i> 10	$m16 \oplus m17 \oplus m19$	M 5	<i>p</i> 13

Table: 1 Message grouping.

In addition to grouping, prediction of grouped data is used. Grouping is in three for which the prediction is shown inTable.2. In Message Grouping *M*if 1's are odd in numbers the prediction is 1, similarly if 1's are even the prediction is 0. For any combination of width three, the prediction is either 1 or 0 based on the number of 1's.

Grouped Message Bits (M)			Prediction
1	1	1	1
1	0	0	1
0	1	1	0
0	0	0	0

Table 2: Prediction of Grouped Messages

4. Results

---(21)

In the proposed algorithm, the block code for the encoder is programmed in Verilog language and synthesized using cadence tool. Result for the encoder is tabulated in table 3, 4, 5 for proposed code without and with grouping compared with extended Golay code respectively. From the tabulation it is meant, grouping with prediction had reduced the delay considerably Extended Golay code is compared since, in general for cyclic codes encoding of the message in speedy when compared with block codes to reduce this gap our code with an optimized algorithm is a feasible solution. Area for proposed encoder with grouping is 2.42 % higher than extended Golay code similarly it's the same percentage for power also, in the case of delay 7.87 % higher compared with the Extended Golay code, although the results are slightly higher compared to (24, 12) code, comparison with grouping and without grouping had to show a considerable reduction in all the parameters. In without grouping, there is 4 % increase in area, 13 % increase in delay and 2 % increase in power when compared with the grouping of majority message bits. In with grouping, there is an increase in delay of encoder because of prediction and an initial grouping of *M*, when the same is called as constant it reduces the delay in computing approaching parity bits.

			Max	Max
n	k		Effort in	Effort in
			area	delay
		Proposed code		
32	19	 without 	730	1387
		grouping		
32	19	Proposed code	702	1154
		– with		
		grouping		
24	12	Extended	685	1002
		Golay code		

Table 3: Area Estimates Area in μm^2

п	k		Max Effort in area	Max Effort in delay
32	19	Proposed code – without grouping	2.66	1.51
32	19	Proposed code – with grouping	2.25	1.31
24	12	Extended Golay code	2.09	1.22

Table 4: Delay Estimates Delay in ns

n	k		Max Effort in area	Max Effort in delay
32	19	Proposed code – without grouping	7.34	28.25
32	19	Proposed code – with grouping	7.20	22.87
24	12	Extended Golay code	7.03	20.46

Table 5: Power Estimates Power in mW

5. Conclusion:

In this brief, new block code of (32, 19) optimized encoder is proposed. Even though our proposed block code results are closer to the existing cyclic codes, the message bits are comparatively higher (19-bit) than Extended Golay code (12-bit). As a result of this recommended block code methodology, there is a marginal increase in delay. It concludes that proposed block code with optimized algorithm may be introduced for other lengthy block codes. It is observed that, when the grouping of majority message bits is repeated in significant parity bits, the delay might be brought down apparently. Proposed (32, 19) code is not compared with similar code length of cyclic codes since presented work is first part of a fault secure memory design, second part will be TAEC for which most suitable bench mark code is Extended Golay code, other cyclic codes of proposed length will lag in correction capability. In the case of (31, 16); and (31, 21) BCH codes correction ability is 2 and 1 respectively. Also for a memory with

reduced gate width is much prone to alpha particles, in a practical aspect with moderate data and good correction capability our optimised proposed code is suitable option for fault secure memory.

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